

# Introduction to Algorithms and Data Structures

## Lecture 12: BuildHeap and HeapSort

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## Heap operations and their asymptotic complexity

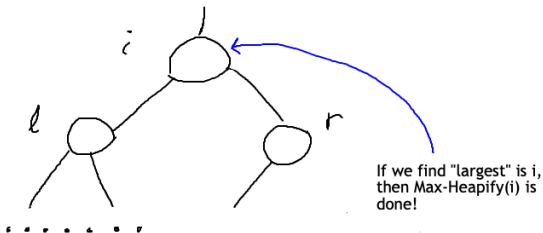
Parent( $i$ )	$O(1)$
Left( $i$ )	$O(1)$
Right( $i$ )	$O(1)$
Heap-Maximum( $A$ )	$O(1)$
Max-Heapify( $A, i$ )	$\Theta(\lg(n))$
Heap-Extract-Max( $A$ )	$\Theta(\lg(n))$
Max-Heap-Insert( $A, k$ )	$\Theta(\lg(n))$
Heap-Increase-Key( $A, i, k$ )	$\Theta(\lg(n))$
Build-Heap( $A$ )	$\Theta(n)$

# Max-heapify

The “top-level” work of  $\text{Max-Heapify}(i)$  depends on comparisons between the value at  $i$  and the values at  $i$ 's two child nodes.  $\Theta(1)$  time to do these comparisons.

The easy case:

Calling  $\text{Max-Heapify}$  at node  $i$ , we need to compare its entry to the value at its left child  $l$  and also the value stored at its right child  $r$ .

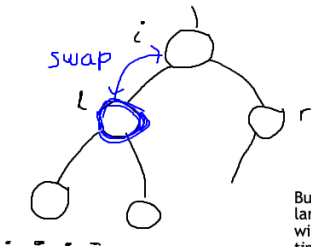


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The recursive case:

Calling  $\text{Max-Heapify}$  at node  $i$ , we need to compare its entry to the value at its left child  $l$  and also the value stored at its right child  $r$ .



But if one/more of  $i$ 's child nodes have a larger value, then we must swap  $i$ 's value with the “largest” (say  $l$  in this), in  $O(1)$  time .... then follow-up with a recursive call from “largest”.

## Running time of Max-Heapify

Max-Heapify( $A, i$ ):

- ▶  $\Theta(1)$  work to consider  $i$  and its two child nodes and to swap the maximum of those 3 values into node/index  $i$ .

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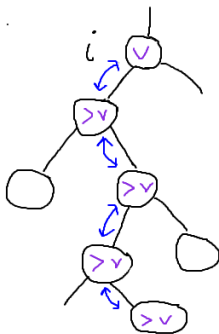
Hence  $T_{\text{Max-Heapify}}(n)$  is  $\lg(n) \cdot O(1)$ , ie  $O(\lg(n))$ .

Note we don't need/use the Master theorem here ..., and it would not fit.

## Running time of Max-Heapify

For the lower bound on  $T_{\text{Max-Heapify}}(n)$ , again work wrt height and  $T'_{\text{Max-Heapify}}(h)$ .

Note we may end up making all  $h$  recursive calls:



If there is a downwards path from  $i$  with values  $> v$  all the way ( $v$  the value at  $i$ ) then Max-Heapify will get called recursively all the way down to the Leaf.

Are doing  $\Omega(1)$  work each step, so get  $h \cdot \Omega(1)$ , ie  $\Omega(h)$ .

If  $i$  is the root, then  $h \geq \lg(n) - 1$ , so we have  $T_{\text{Max-Heapify}}(n) = \Omega(\lg(n))$

## Running times of related operations

The other  $\Theta(\lg(n))$  operations ...

**Heap-Extract-Max** This is just a swap of the Maximum with the rightmost leaf position  $\Theta(1)$ , a decrement of the Heap size ( $\Theta(1)$ ) and a call to Heapify ( $\Theta(\lg(n))$ ).

Note  $\Omega(\lg(n))$  can really happen (explain).

**Max-Heap-Insert** We “bubble-up” through the Heap.  $\Theta(1)$  work done at each step, so  $O(\lg(n))$  overall.

We have  $\Omega(\lg(n))$  for the worst-case - say we insert a new item bigger than anything in the Heap.

**Heap-Increase-Key** This operation is similar to Max-Heap-Insert, and can use same arguments.

# Build-Max-heap

**Algorithm** Build-Max-Heap( $A$ )

1.  $A.heap\_size \leftarrow A.length$
2. **for**  $i \leftarrow \lfloor A.heap\_size/2 \rfloor - 1$  **downto** 0
3.     Max-Heapify( $A, i$ )

$A.length$  is our usual “ $n$ ”.

Build-Max-Heap builds a Max Heap from an unsorted array in  $O(n)$  time.

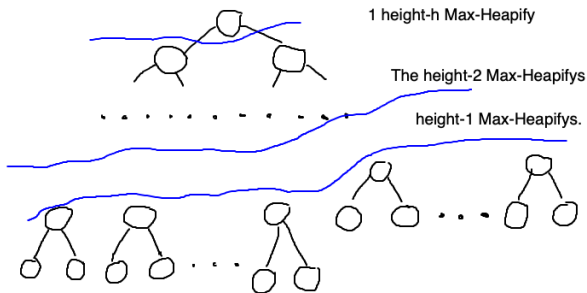
To show correctness, our **invariant** will be

*(Inv) At step  $i$ , we are guaranteed that for every node/index  $j$  with  $j > i$ , the subtree-at- $j$  is a legal Max Heap.*

At step  $i$ , Left( $i$ ) and Right( $i$ ) are guaranteed to be legal Max Heaps. So conditions for Max-Heapify( $A, i$ ) are satisfied. Hence after calling Max-Heapify( $A, i$ ) in line 3, (Inv) now holds for  $i - 1$ .

Base case: all indices  $\lfloor A.length/2 \rfloor, \dots, A.length - 1$  are leaves, so trivially Heaps.

# Build-Max-Heap



- ▶ We will start with the height-1 Heaps at the bottom first, then the heaps of height 2, ... finally the one Heap of height  $h$
- ▶ So we always satisfy the “pre-condition” for Max-Heapify and its Left and Right sub-Heaps.

## Analysis of Build-Max-Heap

We will do  $\lfloor A.length/2 \rfloor$  calls to Max-Heapify.

But these are on Heaps of **varying heights** ...

1 call of height  $h$  (root) ...

2 calls of height  $h - 1$  ...

...

$\lceil n/2^{\ell+1} \rceil$  calls of height  $\ell$ .

So

$$\begin{aligned} T_{\text{Build-Max-Heap}}(n) &= \sum_{\ell=1}^{\lfloor \lg(n) \rfloor} \left\lceil \frac{n}{2^{\ell+1}} \right\rceil O(\ell) \\ &= O\left( \sum_{\ell=1}^{\lfloor \lg(n) \rfloor} \frac{n}{2^{\ell+1}} \ell \right) = O\left( \frac{n}{2} \cdot \sum_{\ell=1}^{\lfloor \lg(n) \rfloor} \frac{\ell}{2^{\ell}} \right) = O(n). \end{aligned}$$

(in the last step we use A.8 of the book, with  $x = 1/2$ , to show  $\sum_{\ell=1}^{\lfloor \lg(n) \rfloor} \frac{\ell}{2^{\ell}} < 2$ )

# HeapSort

In a Heap, we are missing “total order” information about the items, but we do know where the **maximum** is, and can retrieve it efficiently. SO:

Heap-Extract-Max the max item (*heap gets rearranged*) ...

Heap-Extract-Max the next-max item (*heap gets rearranged again*) ...

**Algorithm** HeapSort( $A$ )

1.  $n \leftarrow A.length$
2. Build-Max-Heap( $A$ )
3. **for**  $i \leftarrow n - 1$  **downto** 0
4.      $v \leftarrow \text{Heap-Extract-Max}(A)$
5.      $A[A.heap\_size] \leftarrow v$

Each time Heap-Extract-Max is called (and the current maximum is deleted)  $A.heap\_size$  gets decremented again. So we copy the extracted value into the index  $A.heap\_size$  (this is where this “next max” belongs in the sorted order).

## Analysis of HeapSort

(forget about the time for the Build-Max-Heap call as that is only  $\Theta(n)$ )  
For the rest of the work, like Build-Max-Heap we are doing a linear number of Max-Heapify (well, Heap-Extract-Max ) operations ...

But **unlike** Build-Max-Heap every single one of the Max-Heapify calls (from Heap-Extract-Max) is carried out from the root ...

Upper bound is therefore

$$\begin{aligned}\sum_{m=n}^2 O(\lg(m)) &= O\left(\sum_{m=1}^n \lg(m)\right) \\ &= O\left(\lg\left(\prod_{m=1}^n m\right)\right) \quad (\text{by } \lg(a \cdot b) = \lg(a) + \lg(b)) \\ &= O(\lg(n!))\end{aligned}$$

Easy inequality  $n^{n/2} \leq n! \leq n^n$  gives us  $O(n \lg(n))$ .

To show  $\Omega(n \lg(n))$  direction consider an input array in reverse sorted order.

## HeapSort: some properties

HeapSort (and the binary Heap itself) were invented by J.W.J. (Bill) Williams, in 1964.



HeapSort is an **in-place** Algorithm, as it can be implemented without any auxiliary “scratch” array.

A sorting algorithm is said to be **stable** if for any input array  $A$ , we are guaranteed that any two entries of  $A$  with the same key will appear in the **same relative order** after sorting.

- ▶ HeapSort is not stable.

# Python and Heaps



Python provides the `heapq` Library:

- ▶ Their implementation is a Min Heap, rather than a Max heap
  - ▶ Not hard to re-work it to be a Max Heap, can store the items with negative values (if they are `int` or `float` or similar).
  - ▶ For more complicated types, can instead add a “wrapper” class wrapping them in a class with an inverted `__lt__` operator.
- ▶ arrays start at 0 (like us)
- ▶ Names of operations are different (their `Heapify` is really `Build-Max-Heap`, lots of other differences).

# Reading Material

From [CLRS]:

- ▶ BuildHeap is presented and analysed in 6.1-6.3 of [CLRS] (eds 3 and 4)
- ▶ Heapsort and its running time is 6.4 of [CLRS] (eds 3 and 4).

“Algorithms Illuminated” [AI] by Roughgarden:

- ▶ Sections 10.2, 10.3 ... plus Problem 10.5 (Heapify/BuildHeap)