

# Informatics 2 – Introduction to Algorithms and Data Structures

## Tutorial 2: Analysis of Algorithms

1. In Lecture 2 we considered three algorithms (A, B, C) for computing  $\mathbf{Expmod}(a, n, m) = a^n \bmod m$ , and mentioned how this operation can be used to test for ‘probable primes’. For example:

$$\mathbf{ProbablePrime}(n) = (\mathbf{Expmod}(2, n - 1, n) == 1)$$

We can gain insight into the time complexity of this procedure by analysing the *number of arithmetic operations performed* (+, −, ×, div, mod).

- (a) Give an asymptotic upper bound – i.e.  $O(\text{some function of } n)$  – for the number of arithmetic operations required to compute  $\mathbf{ProbablePrime}(n)$  using Algorithm B for  $\mathbf{Expmod}$ :

```
Expmod (a,n,m):  
  b=1  
  for i = 1 to n  
    b = (b × a) mod m  
  return b
```

- (b) Do the same for Algorithm C:

```
Expmod (a,n,m):  
  if n=0 then return 1  
  else  
    d = Expmod (a,[n/2],m)  
    if n is even  
      return (d × d) mod m  
    else return (d × d × a) mod m
```

Give informal justifications for your answers. (We are not expecting rigorous proofs here, though you’re welcome to think about what they’d look like.)

2. The sorting algorithm known as **BubbleSort** works by repeatedly sweeping through an array, swapping any pairs of adjacent elements that are out of order. Here is a very crude version of **BubbleSort**. (NB. This may be simpler than other versions you might have come across, so pay close attention to the details of how the loops are set up.)

```
BubbleSort (A):  
  for i = 1 to |A| - 1  
    for j = 0 to |A| - 2  
      if A[j] > A[j+1]  
        swap A[j] and A[j+1]
```

- (a) First, let's see why this algorithm works. Explain why after the *first* sweep through the array (i.e. after the completion of the  $j$ -loop when  $i=1$ ), the largest element will be in its correct place at position  $n - 1$ , where  $n = |A|$ . Develop this idea to show that after  $n - 1$  sweeps, the array will be fully sorted.
- (b) What is the asymptotic worst-case number of comparisons performed by this algorithm for inputs of size  $n$  (as  $\Theta(\text{something})$ )? What about the asymptotic best case?
- (c) The above version of **BubbleSort** can be made more efficient in two ways. One of these might be suggested by your answer to part (a) above: perhaps we don't need to sweep through the *whole* of  $A$  each time? Another comes from noting that if we ever happen to complete a sweep of the array without doing any swaps, the array must be fully sorted and we can stop.

Write some pseudocode for a new version, **BubbleSort2**, that incorporates both these improvements. (It is this version, or something very close, that is most often referred to as 'BubbleSort'.)

- (d) What are the asymptotic worst- and best-case runtimes for **BubbleSort2**? For what inputs do these worst and best cases arise?
- (e)  $\star$  (Optional) A useful measure of the *unsortedness* of an array  $A$  is the number of pairs of indices  $i, j < |A|$  such that  $i < j$  but  $A[i] > A[j]$ . (Such a pair  $i, j$  is often called an *inversion*.) For example, a fully sorted array has unsortedness 0. A reverse-sorted array of size  $n$  has unsortedness  $n(n - 1)/2$ , since here *every* pair  $i, j$  with  $i < j$  satisfies  $A[i] > A[j]$ .

Argue that the number of comparisons performed by **BubbleSort2** on input  $A$  is at least the unsortedness of  $A$ .

3.  $\star$  The version of **MergeSort** given in lectures is rather wasteful on space, as it allocates a fresh array  $D$  for every merge performed. Give pseudocode for an alternative version of **MergeSort** that sorts a given array  $A$  of size  $n$ , returning the sorted result within  $A$  itself, and using another array  $B$  of size  $n$  as workspace, but not creating any other arrays.

[Here's one way to approach it: Write a function that sorts the portion of  $A$  from position  $m$  to  $n-1$ , by splitting this portion into four roughly equal parts, recursively sorting each of these, then merging the results with the help of  $B$ .]

Does your algorithm require any memory space beyond that used to store  $A$  and  $B$ ? Give a  $\Theta$ -estimate for the total space usage of your algorithm, informally justifying your answer.