Introduction to Algorithms and Data Structures

NP-completeness: A closer look

- Stands for "non deterministic polynomial time".
- Problems that can be solved in polynomial time by a nondeterministic Turing machine.
- More intuitive definition:
 - Problems such that, *if a solution is given*, it can be checked that it is indeed a solution in polynomial time.
 - Efficiently verifiable.



Interval Scheduling

Interval Scheduling Weighted Interval Scheduling

Shortest Paths in Graphs

Interval Scheduling Weighted Interval Scheduling

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Subset Sum

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Subset Sum Knapsack

3 SAT

• A CNF formula with m clauses and k literals.

 $\boldsymbol{\varphi} = (X_1 \lor X_5 \lor X_3) \land (X_2 \lor X_6 \lor \mathbf{X}_5) \land \dots \land (X_3 \lor X_8 \lor X_{12})$

- ("An AND of ORs").
- Each clause has three literals.
- Truth assignment: A value in {0,1} for each variable x_i.
- Satisfying assignment: A truth assignment which makes the formula evaluate to 1 (= true).
- Computational problem 3SAT : Decide if the input formula φ has a satisfying assignment.

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Subset Sum Knapsack

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Subset Sum Knapsack 3SAT

Vertex Cover decision version

- Definition: A vertex cover C of a graph G=(V, E) is a subset of the nodes such that every edge e in the graph has at least one endpoint in C.
- Definition: A minimum vertex cover is a vertex cover of the smallest possible size.
- Vertex Cover

Input: A graph G=(V, E) and a number k Output: Is there a vertex cover of size $\leq k$?.

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Subset Sum Knapsack 3SAT

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover

Subset Sum Knapsack 3SAT

 Independent Set in graph G: A set of nodes in the graph, such that there is no edge between any two nodes in the set.

- Independent Set in graph G: A set of nodes in the graph, such that there is no edge between any two nodes in the set.
- Maximum Independent Set Given a graph G, find an independent set of maximum size.

- Independent Set in graph G: A set of nodes in the graph, such that there is no edge between any two nodes in the set.
- Maximum Independent Set Given a graph G, find an independent set of maximum size.
- Maximum Independent Set (decision version) Given a graph G, and an integer k, is there an independent set of size at least k?

Set Packing

Given a set U of elements, a collection S_1, \ldots, S_m of subsets of U and a number k, does there exist a collection of at least k of these sets such that no two of them intersect?

Set Packing

Given a set U of elements, a collection S_1, \ldots, S_m of subsets of U and a number k, does there exist a collection of at least k of these sets such that no two of them intersect?

• Set Cover

Given a set U of elements, a collection S_1, \ldots, S_m of subsets of U and a number k, does there exist a collection of at most k of these sets whose union is equal to U?

• 3-Dimensional Matching

Given disjoint sets X, Y and Z each of size n, and given a set T (which is a subset of $X \times Y \times Z$) of ordered triples, does there exist a set of n triples in T, so that each element of X U Y U Z is contained in exactly in one of these triples?

 k-Colouring of a graph G: A function f: V → {1, ..., k} so that for every edge (u, v) we have that f(u) ≠ f(v).

- k-Colouring of a graph G: A function f: V → {1, ..., k} so that for every edge (u, v) we have that f(u) ≠ f(v).
- 3-Colouring Given a graph G, does it have a 3-Colouring?

• Hamiltonian cycle in a directed graph G: A cycle in a directed graph that visits each vertex *exactly once*.

- Hamiltonian cycle in a directed graph G: A cycle in a directed graph that visits each vertex *exactly once*.
- Hamiltonian path in a directed graph G: A path in a directed graph that contains each vertex *exactly once*.

- Hamiltonian cycle in a directed graph G: A cycle in a directed graph that visits each vertex *exactly once*.
- Hamiltonian path in a directed graph G: A path in a directed graph that contains each vertex *exactly once*.
- Hamiltonian Cycle Given a directed graph G, does it have a Hamiltonian Cycle?

- Hamiltonian cycle in a directed graph G: A cycle in a directed graph that visits each vertex *exactly once*.
- Hamiltonian path in a directed graph G: A path in a directed graph that contains each vertex *exactly once*.
- Hamiltonian Cycle Given a directed graph G, does it have a Hamiltonian Cycle?
- Hamiltonian Path

Given a directed graph G, does it have a Hamiltonian Path?

- Hamiltonian cycle in a directed graph G: A cycle in a directed graph that visits each vertex *exactly once*.
- Hamiltonian path in a directed graph G: A path in a directed graph that contains each vertex *exactly once*.
- Hamiltonian Cycle Given a directed graph G, does it have a Hamiltonian Cycle?
- Hamiltonian Path

Given a directed graph G, does it have a Hamiltonian Path?

• Traveling Salesman (def Kleinberg and Tardos, p. 474).

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover

Subset Sum Knapsack 3SAT
Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Subset Sum Knapsack 3SAT

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Subset Sum Knapsack 3SAT

Set Packing

Interval Scheduling Weighted Interval Scheduling

> Subset Sum Knapsack

Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing

3SAT

Interval Scheduling Weighted Interval Scheduling

> Subset Sum Knapsack

Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing 3D-Matching

3SAT

3SAT

Interval Scheduling Weighted Interval Scheduling

> Subset Sum Knapsack

Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing 3D-Matching

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing 3D-Matching

Subset Sum Knapsack

3SAT

Hamiltonian Cycle

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing 3D-Matching

Subset Sum Knapsack 3SAT

Hamiltonian Cycle Hamiltonian Path

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing 3D-Matching

Subset Sum Knapsack 3SAT

Hamiltonian Cycle Hamiltonian Path Traveling Salesman

- A problem B is NP-complete if
 - It is in NP.
 - i.e., it has a polynomial-time verifiable solution.
 - It is NP-hard.
 - i.e., every problem in NP can be efficiently reduced to it.

3SAT

Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing 3D-Matching

Subset Sum Knapsack

> Hamiltonian Cycle Hamiltonian Path Traveling Salesman





Interval Scheduling Weighted Interval Scheduling Shortest Paths in Graphs Minimum-cost Paths in Graphs Testing Bipartiteness 3SAT Topological Sort

Vertex Cover Independent Set

Set Cover Set Packing 3D-Matching

Subset Sum Knapsack

SAT

Hamiltonian Cycle Hamiltonian Path Traveling Salesman











The Cook-Levin Theorem (1971, 1973)



The Cook-Levin Theorem (1971, 1973)

The proof uses a generic argument that if a problem has a solution which can be verified in polynomial-time, then it reduces in polynomial time to the SAT problem.



U DEGREE REGULATIONS & PROGRAMMES OF STUDY 2023/2024

Timetable information in the Course Catalogue may be subject to change.

DRPS : Course Catalogue : School of Informatics : Informatics

Undergraduate Course: Introduction to Theoretical Computer Science (INFR10059)

All distant

Course Outline			
School	School of Informatics	College	College of Science and Engineering
Credit level (Normal year taken)	SCQF Level 10 (Year 3 Undergraduate)	Availability	Available to all students
SCQF Credits	10	ECTS Credits	5
Summary	This course introduces the fundamental concepts of the theory of computer science, which include some of the greatest intellectual advances of the last century: what does `computing' mean? Are all `computers' basically the same? Can we tell whether our programs are `correct' - and what does `correct' mean, anyway? Can we solve problems in reasonable time, and can we tell whether we can?		
Course description	The first section of the course asks the question, what does it mean to compute? We start with the finite automata introduced in earlier years, and then generalize to pushdown automata, and show that they have more power. Next we generalize further to very simple abstract general computers, and argue they can do everything real computers can do. We then ask, can we solve every computational question? The answer, with which Turing shocked the mathematicians of the 1930s, is "no", with a remarkably easy but beautiful argument (introduced at the end of Inf2-IADS INFR08026). We then explore some different, but always equivalent, ways of defining "a computer". We finish the section by asking how we can compare the difficulty of different problems, and introduce the idea of "reduction" as a way of compiling one problem into another. Technically, this covers register machines, undecidability, Turing machines, and reductions. The second section thinks about how hard it is to solve solvable problems, leading to one of the most important problems in all mathematics, and the foundation of internet security. We start by reprising Inf2-IADS INFR08026 analysis of algorithms, and then discuss the idea of classifying problems as 'tractable' (easy) or 'intractable' (hard). We find that the idea of algorithms whose running time grows polynomially in the problem size is a good mathematical definition of 'tractable', though not always a practical one. After making this more precise, we ask what happens if we're allowed to just check all the possible answers in parallel - does this give us more problem-solving power? The question is made precise by the concept of NP, and we show that there are "hardest" such problems, such as the famous Travelling Salesman. Although the question is easy to ask, nobody knows how to answer it. This is P = NP - if you can solve it, you win a million dollars, and fame for as long as civilization lasts. So far, NP problems are very hard to solve in practice, so we discuss how to deal with them. We fini		
Entry Requirements (not applicable to Visiting Students)			
Pre-requisites		Co-requisites	
Prohibited Combinations		Other requirements	This course is open to all Informatics students including those on joint degrees. It is also open to students in the School of Mathematics.
Information for Visiting Students			
Pre-requisites	None		
High Demand Course?	Yes		
Course Delivery Information			
Academic year 2023/24. Available to all students	(SV1)	Quota: None	
Course Start	Semester 1	2	
Timetable	Imetable		
Learning and Teaching activities (Further Info)	Total Hours: 100 (Programme Level Learning and Teaching Hours 2. Directed Learning and Independent Learning Hours 98.)		
Assessment (Further Info)	Witten Fyam 80 % Coursework 20 % Practical Evam 0 %		
Additional Information (Assessment)	In tech scale of any concerning by an interced scale of the three major sections the format will be three compulsory assign questions and a choice of one of two longer questions		
Assessed coursework will be issued at two points, containing mainly relatively straightforward exercises designed to reinforce basics, the first coursework being formative and the second being summative. Additional formative work in tutorial sheets will stretch those who wish.			
			e second being summative. Additional formative work in tutorial sheets will stretch those who wish.
	You should expect to spend approximately 15 hours on the coursework for this course.		
Feedback	Formative feedback is given verbally in tutorials, and in writing for the first exercise. Summative and formative feedback is given in writing for the second exercise.		
Traveling Salesman			

The Cook-Levin Theorem (1971, 1973)

The proof uses a generic argument that if a problem has a solution which can be verified in polynomial-time, then it reduces in polynomial time to the SAT problem.

• What does the NP-completeness of SAT mean?

- What does the NP-completeness of SAT mean?
 - It means that it is *at least as hard to solve* as any other problem in NP.

- What does the NP-completeness of SAT mean?
 - It means that it is at least as hard to solve as any other problem in NP.
 - In particular, if we had a polynomial-time algorithm for solving SAT, we could solve any other problem in NP, via the reduction (the arrow).

Wooclap!



- What does the NP-completeness of SAT mean?
 - It means that it is at least as hard to solve as any other problem in NP.
 - In particular, if we had a polynomial-time algorithm for solving SAT, we could solve any other problem in NP, via the reduction (the arrow).
 - At this stage, that doesn't necessarily say much.

 Some time passes, and we tried and tried to find a polynomial-time algorithm for SAT (or 3SAT) and we are still looking for one...

- Some time passes, and we tried and tried to find a polynomial-time algorithm for SAT (or 3SAT) and we are still looking for one...
- This seems to suggest that SAT might be in some sense harder to solve than e.g., Interval Scheduling or Testing Bipartiteness.

- Some time passes, and we tried and tried to find a polynomial-time algorithm for SAT (or 3SAT) and we are still looking for one...
- This seems to suggest that SAT might be in some sense harder to solve than e.g., Interval Scheduling or Testing Bipartiteness.
 - We know of course that it is at least as hard to solve, by virtue of being NP-complete.

- Some time passes, and we tried and tried to find a polynomial-time algorithm for SAT (or 3SAT) and we are still looking for one...
- This seems to suggest that SAT might be in some sense harder to solve than e.g., Interval Scheduling or Testing Bipartiteness.
 - We know of course that it is at least as hard to solve, by virtue of being NP-complete.
 - But this seems to suggest that some problems in NP are harder than others.

 After a while, we gave up on SAT and decided to try to solve our new favourite problem, Vertex Cover, in polynomial time.

- After a while, we gave up on SAT and decided to try to solve our new favourite problem, Vertex Cover, in polynomial time.
- We tried hard and we failed... We are still looking for a polynomial-time algorithm.

- After a while, we gave up on SAT and decided to try to solve our new favourite problem, Vertex Cover, in polynomial time.
- We tried hard and we failed... We are still looking for a polynomial-time algorithm.
- Hmm, maybe Vertex Cover is also harder to solve than, say, Interval Scheduling or Testing Bipartiteness...










• Vertex Cover is NP-complete.

- Vertex Cover is NP-complete.
- This means that it is at least as hard as any problem in NP, including SAT.

- Vertex Cover is NP-complete.
- This means that it is at least as hard as any problem in NP, including SAT.
- But we really tried to solve SAT in polynomial-time... No wonder we failed to solve Vertex Cover too!

 Ok, let's try to solve Independent Set in polynomial time then.

- Ok, let's try to solve Independent Set in polynomial time then.
- Arghh, we can't solve that either!









• Independent Set is NP-complete.

- Independent Set is NP-complete.
- This means that it is at least as hard as any problem in NP, including SAT and Vertex Cover.

- Independent Set is NP-complete.
- This means that it is at least as hard as any problem in NP, including SAT and Vertex Cover.
- But we really tried to solve SAT and Vertex Cover in polynomial-time... No wonder we failed to solve Independent Set too.





















 3SAT, Vertex Cover, Independent Set, Subset Sum, Knapsack, Hamiltonian Path, Hamiltonian Cycle, Traveling Salesman, 3-Colouring, Set Cover, Set Packing, 3D-Matching are all NP-complete.

- 3SAT, Vertex Cover, Independent Set, Subset Sum, Knapsack, Hamiltonian Path, Hamiltonian Cycle, Traveling Salesman, 3-Colouring, Set Cover, Set Packing, 3D-Matching are all NP-complete.
- Actually, this is only a very small subset of NP-complete problems.

- 3SAT, Vertex Cover, Independent Set, Subset Sum, Knapsack, Hamiltonian Path, Hamiltonian Cycle, Traveling Salesman, 3-Colouring, Set Cover, Set Packing, 3D-Matching are all NP-complete.
- Actually, this is only a very small subset of NP-complete problems.
 - Hundreds of other meaningful problems are NP-complete.

- 3SAT, Vertex Cover, Independent Set, Subset Sum, Knapsack, Hamiltonian Path, Hamiltonian Cycle, Traveling Salesman, 3-Colouring, Set Cover, Set Packing, 3D-Matching are all NP-complete.
- Actually, this is only a very small subset of NP-complete problems.
 - Hundreds of other meaningful problems are NP-complete.
- We don't know how to solve any one of those in polynomialtime.

The effect of NP-hardness
• Imagine that you have a new favourite problem P.

- Imagine that you have a new favourite problem P.
- You try to design a polynomial-time algorithm for it but you find it hard to do so.

- Imagine that you have a new favourite problem P.
- You try to design a polynomial-time algorithm for it but you find it hard to do so.
- Then you discover that it can be reduced to one of all of these NP-complete problems.

- Imagine that you have a new favourite problem P.
- You try to design a polynomial-time algorithm for it but you find it hard to do so.
- Then you discover that it can be reduced to one of all of these NP-complete problems.
- This means that if you succeeded in your quest, you would solve all of these problems in polynomial-time.

- Imagine that you have a new favourite problem P.
- You try to design a polynomial-time algorithm for it but you find it hard to do so.
- Then you discover that it can be reduced to one of all of these NP-complete problems.
- This means that if you succeeded in your quest, you would solve all of these problems in polynomial-time.
- That would mean that you are smarter than generations of researchers and pretty much anyone else that has studied computer science ever.

- Imagine that you have a new favourite problem P.
- You try to design a polynomial-time algorithm for it but you find it hard to do so.
- Then you discover that it can be reduced to one of all of these NP-complete problems.
- This means that if you succeeded in your quest, you would solve all of these problems in polynomial-time.
- That would mean that you are smarter than generations of researchers and pretty much anyone else that has studied computer science ever.
- I don't know about you, but I would probably be convinced that I am not going to come up with a polynomial-time algorithm!

Wooclap!

• For now, we'll tell you what to reduce from.

- For now, we'll tell you what to reduce from.
- And the reduction will be relatively simple.

- For now, we'll tell you what to reduce from.
- And the reduction will be relatively simple.
- In general, the idea is to find a problem that looks similar to the one we are trying to prove NP-hardness for.

- For now, we'll tell you what to reduce from.
- And the reduction will be relatively simple.
- In general, the idea is to find a problem that looks similar to the one we are trying to prove NP-hardness for.
- Try to think of reductions you have seen in the past.

- For now, we'll tell you what to reduce from.
- And the reduction will be relatively simple.
- In general, the idea is to find a problem that looks similar to the one we are trying to prove NP-hardness for.
- Try to think of reductions you have seen in the past.
 - This takes time!

NP-completeness, a taxonomy



• So when a problem is NP-complete, this means:

- So when a problem is NP-complete, this means:
 - That it is in NP, and it is at least as hard to solve as any other problem in NP.

- So when a problem is NP-complete, this means:
 - That it is in NP, and it is at least as hard to solve as any other problem in NP.
 - That it is unlikely that we solve it in polynomial time, as that would imply that we solve all the NP-complete problems.

- So when a problem is NP-complete, this means:
 - That it is in NP, and it is at least as hard to solve as any other problem in NP.
 - That it is unlikely that we solve it in polynomial time, as that would imply that we solve all the NP-complete problems.
 - That it is not solvable in polynomial time assuming $P \neq NP$.

Wooclap!



• Let's recall the NP-hardness proof for Vertex Cover.



• Let's recall the NP-hardness proof for Vertex Cover.



• If I could decide Vertex Cover on this graph, I could decide 3SAT.



What about this graph? Can I decide Vertex Cover on this graph?



What about this graph? Can I decide Vertex Cover on this graph?



• "Choose one leave one" finds a minimum vertex cover.

 An NP-hardness result does not mean that (unless P=NP) we cannot solve the problem in polynomial time *for any* instance.

- An NP-hardness result does not mean that (unless P=NP) we cannot solve the problem in polynomial time *for any* instance.
- It means that we cannot solve it in polynomial time for every instance.

- An NP-hardness result does not mean that (unless P=NP) we cannot solve the problem in polynomial time *for any* instance.
- It means that we cannot solve it in polynomial time for every instance.
- For all we know, every other instance besides those used in the reduction could be easy to solve.

• For all we know, every other instance besides those used in the reduction could be easy to solve.

- For all we know, every other instance besides those used in the reduction could be easy to solve.
- Usually not the case! In practice usually we don't have good ways of solving NP-hard problems.

- For all we know, every other instance besides those used in the reduction could be easy to solve.
- Usually not the case! In practice usually we don't have good ways of solving NP-hard problems.
- Still, sometimes we can provably design polynomial algorithms on certain *input structures*.

- For all we know, every other instance besides those used in the reduction could be easy to solve.
- Usually not the case! In practice usually we don't have good ways of solving NP-hard problems.
- Still, sometimes we can provably design polynomial algorithms on certain *input structures*.
- For example, a minimum Vertex Cover on *trees* can be found in polynomial time using Dynamic Programming.

Wooclap!

NP-hardness \neq Exponential Time
• This is true even if $P \neq NP$.

- This is true even if $P \neq NP$.
- Roughgarden: Acceptable Inaccuracy #3.

- This is true even if $P \neq NP$.
- Roughgarden: Acceptable Inaccuracy #3.
- Subexponential time: $n^{O(\lg n)}$ or $2^{O(\sqrt{n})}$.

- This is true even if $P \neq NP$.
- Roughgarden: Acceptable Inaccuracy #3.
- Subexponential time: $n^{O(\lg n)}$ or $2^{O(\sqrt{n})}$.
- There are NP-complete problems that can be solved in subexponential time.

- This is true even if $P \neq NP$.
- Roughgarden: Acceptable Inaccuracy #3.
- Subexponential time: $n^{O(\lg n)}$ or $2^{O(\sqrt{n})}$.
- There are NP-complete problems that can be solved in subexponential time.
- Exponential Time Hypothesis (ETH): SAT requires exponential time to be solved.

- This is true even if $P \neq NP$.
- Roughgarden: Acceptable Inaccuracy #3.
- Subexponential time: $n^{O(\lg n)}$ or $2^{O(\sqrt{n})}$.
- There are NP-complete problems that can be solved in subexponential time.
- Exponential Time Hypothesis (ETH): SAT requires exponential time to be solved.
 - ETH $\Rightarrow P \neq NP$

• Every NP-complete problem is NP-hard.

- Every NP-complete problem is NP-hard.
- Is every NP-hard problem NP-complete?

- Every NP-complete problem is NP-hard.
- Is every NP-hard problem NP-complete?
- Are there problems that are NP-hard but not in NP?

• A CNF formula with m clauses and k literals, and a set of quantifiers.

 $Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$

where $Q_i \in \{ \forall, \exists \}$

• A CNF formula with m clauses and k literals, and a set of quantifiers.

 $Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$

where $Q_i \in \{\forall, \exists\}$

• For example, we may have $\exists x_1 \forall x_2 \exists x_3, ..., \forall x_n \phi(x_1, x_2, x_3, ..., x_n)$

• A CNF formula with m clauses and k literals, and a set of quantifiers.

 $Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$

where $Q_i \in \{ \forall, \exists \}$

- For example, we may have $\exists x_1 \forall x_2 \exists x_3, ..., \forall x_n \phi(x_1, x_2, x_3, ..., x_n)$
- We read "Does there exists x_1 such that for every x_2 there exists x_3 such that ... such that for every x_n , the formula ϕ is satisfiable?"

Or maybe a game of chess



Or maybe a game of chess



• Does white have a winning strategy?

Or maybe a game of chess



- Does white have a winning strategy?
- Does there exist a move for white, such that for every move of black, there exists a move for white, such that for every move of black, ..., such that for every move of black, white wins?

• A CNF formula with m clauses and k literals, and a set of quantifiers.

 $Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$

where $Q_i \in \{\forall, \exists\}$

• For example, we may have $\exists x_1 \forall x_2 \exists x_3, \dots, \forall x_n \phi(x_1, x_2, x_3, \dots, x_n)$

• A CNF formula with m clauses and k literals, and a set of quantifiers.

 $Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$

where $Q_i \in \{\forall, \exists\}$

- For example, we may have $\exists x_1 \forall x_2 \exists x_3, \dots, \forall x_n \phi(x_1, x_2, x_3, \dots, x_n)$
- TQBF is NP-hard. Why?

NP-completeness



NP-completeness



NP-completeness



• A CNF formula with m clauses and k literals, and a set of quantifiers.

 $Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$

where $Q_i \in \{\forall, \exists\}$

- For example, we may have $\exists x_1 \forall x_2 \exists x_3, \dots, \forall x_n \phi(x_1, x_2, x_3, \dots, x_n)$
- We read "Does there exists x_1 such that for every x_2 there exists x_3 such that ... such that for every x_n , the formula ϕ is satisfiable?"

• A CNF formula with m clauses and k literals, and a set of quantifiers.

 $Q_1 x_1 Q_2 x_2 \dots Q_n x_n \phi(x_1, x_2, \dots, x_n)$

where $Q_i \in \{ \forall, \exists \}$

- For example, we may have $\exists x_1 \forall x_2 \exists x_3, \dots, \forall x_n \phi(x_1, x_2, x_3, \dots, x_n)$
- We read "Does there exists x_1 such that for every x_2 there exists x_3 such that ... such that for every x_n , the formula ϕ is satisfiable?"
- For a given x_1 we have to check the values of x_2 for all possible values of the remaining x_4, x_6 , etc. Does not seem to be doable in polynomial time.

• We cannot categorically say that TQBF is not efficiently verifiable (i.e., that it is not in NP).

- We cannot categorically say that TQBF is not efficiently verifiable (i.e., that it is not in NP).
- In the same way as we cannot categorically say that SAT is not efficiently solvable (i.e., that it is not in P).

- We cannot categorically say that TQBF is not efficiently verifiable (i.e., that it is not in NP).
- In the same way as we cannot categorically say that SAT is not efficiently solvable (i.e., that it is not in P).
- But we have reasons to believe that SAT is not in P.

- We cannot categorically say that TQBF is not efficiently verifiable (i.e., that it is not in NP).
- In the same way as we cannot categorically say that SAT is not efficiently solvable (i.e., that it is not in P).
- But we have reasons to believe that SAT is not in P.
 - Because then we would be able to solve all NP-complete problems.

- We cannot categorically say that TQBF is not efficiently verifiable (i.e., that it is not in NP).
- In the same way as we cannot categorically say that SAT is not efficiently solvable (i.e., that it is not in P).
- But we have reasons to believe that SAT is not in P.
 - Because then we would be able to solve all NP-complete problems.
- Similarly we have reasons to believe that TQBF is not in NP.

NP



PSPACE



PSPACE



PSPACE



Another NP-hard problem that is not in NP

Another NP-hard problem that is not in NP

 Informally: Given the description of an arbitrary computer program and an input to the program, determine if the program will terminate or not.
Another NP-hard problem that is not in NP

- Informally: Given the description of an arbitrary computer program and an input to the program, determine if the program will terminate or not.
- This is the Halting Problem, which is NP-hard but it is undecidable.

Another NP-hard problem that is not in NP

- Informally: Given the description of an arbitrary computer program and an input to the program, determine if the program will terminate or not.
- This is the Halting Problem, which is NP-hard but it is undecidable.
 - i.e., it cannot be solved in any amount of time on any computer.

Another NP-hard problem that is not in NP

- Informally: Given the description of an arbitrary computer program and an input to the program, determine if the program will terminate or not.
- This is the Halting Problem, which is NP-hard but it is undecidable.
 - i.e., it cannot be solved in any amount of time on any computer.
 - More about that later!





pseudopolynomial time.



We solved those in pseudopolynomial time.

Could they be "easier" than SAT in some sense?

 A problem P is strongly NP-hard if it remains NP-hard even when the numerical parameters in the input are given in unary representation.

- A problem P is strongly NP-hard if it remains NP-hard even when the numerical parameters in the input are given in unary representation.
- Otherwise, it is weakly NP-hard.

- A problem P is strongly NP-hard if it remains NP-hard even when the numerical parameters in the input are given in unary representation.
- Otherwise, it is weakly NP-hard.
 - Weakly NP-hard problems admit pseudopolynomial algorithms.





Another way to compare: Approximate Solutions



Another way to compare: Approximate Solutions More about that over the next two lectures!