

Algorithms and Data Structures

Max Flow in Polynomial Time: The Edmonds-Karp Algorithm

Ford-Fulkerson analysis

Feasibility

Does the algorithm produce a flow if it terminates?

Termination

Does the algorithm always terminate?

Running Time

What is the running time of the algorithm?

Optimality / Correctness

Does the algorithm produce a maximum flow?

Ford-Fulkerson analysis

Feasibility



Does the algorithm produce a flow if it terminates?

Termination

Does the algorithm always terminate?

Running Time

What is the running time of the algorithm?

Optimality / Correctness

Does the algorithm produce a maximum flow?

Ford-Fulkerson analysis

Feasibility



Does the algorithm produce a flow if it terminates?

Termination



Does the algorithm always terminate?

Running Time

What is the running time of the algorithm?

Optimality / Correctness

Does the algorithm produce a maximum flow?

Ford-Fulkerson analysis

Feasibility



Does the algorithm produce a flow if it terminates?

Termination



Does the algorithm always terminate?

Running Time



What is the running time of the algorithm?

Optimality / Correctness

Does the algorithm produce a maximum flow?

Ford-Fulkerson analysis

Feasibility



Does the algorithm produce a flow if it terminates?

Termination



Does the algorithm always terminate?

Running Time



What is the running time of the algorithm?

Optimality / Correctness



Does the algorithm produce a maximum flow?

Running Time

The running time of FF is $O(mF)$, where F is the value of the maximum flow.

Since $F \leq c$, this is in fact $O(mc)$.

Is this an efficient algorithm?

The running time is *pseudopolynomial*, as it runs in time polynomial in n and the *unary representation* of the total capacity c .

It is fairly efficient, if in the numbers involved in the input are reasonably small.

The Ford-Fulkerson Algorithm

Max-Flow

Initially set $f(e) = 0$ for all e in E .

While there exists an s - t path in the residual graph G_f

 Choose such a path P

$f' = \text{augment}(f, P)$

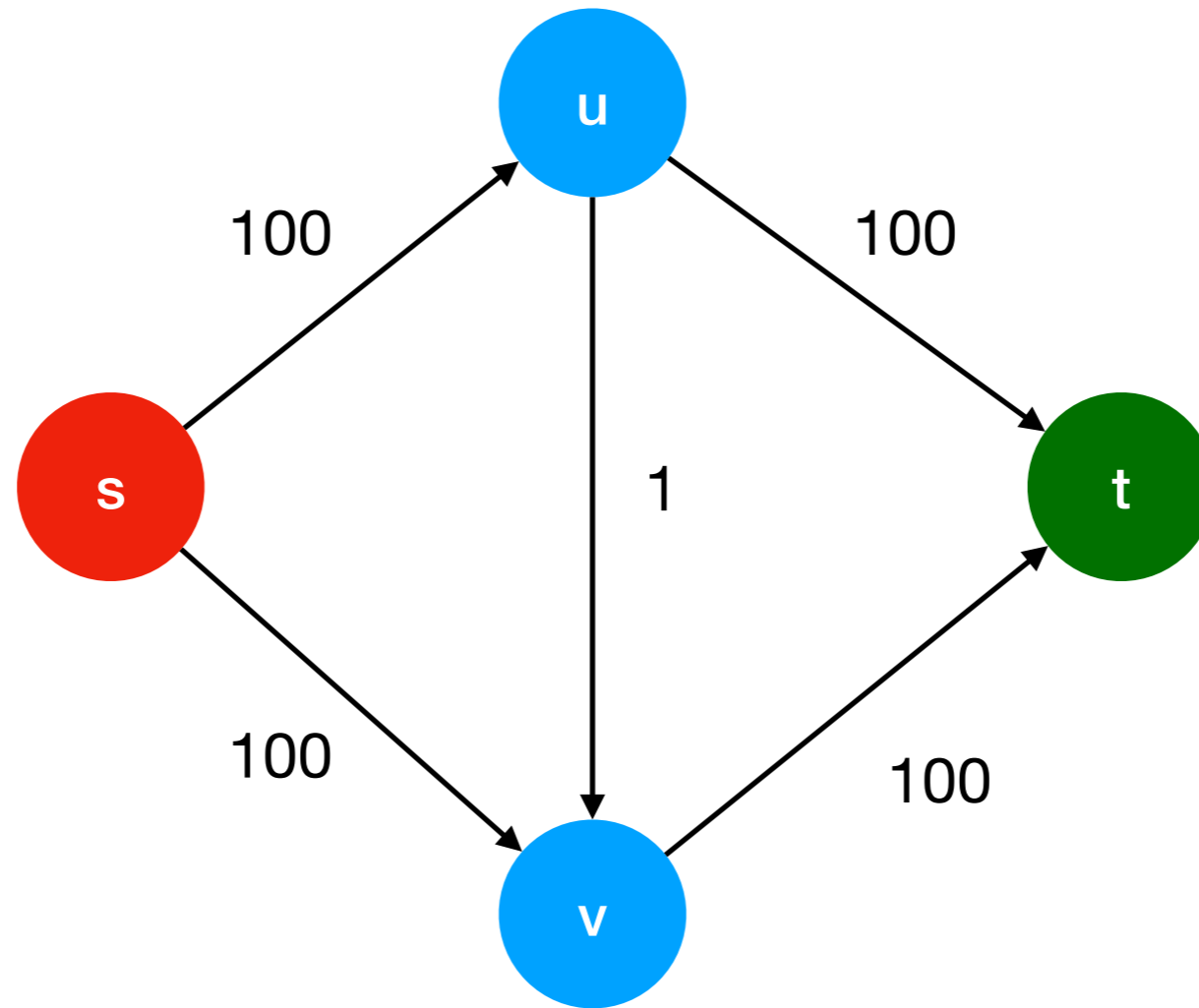
 Update f to be f'

 Update the residual graph to be $G_{f'}$

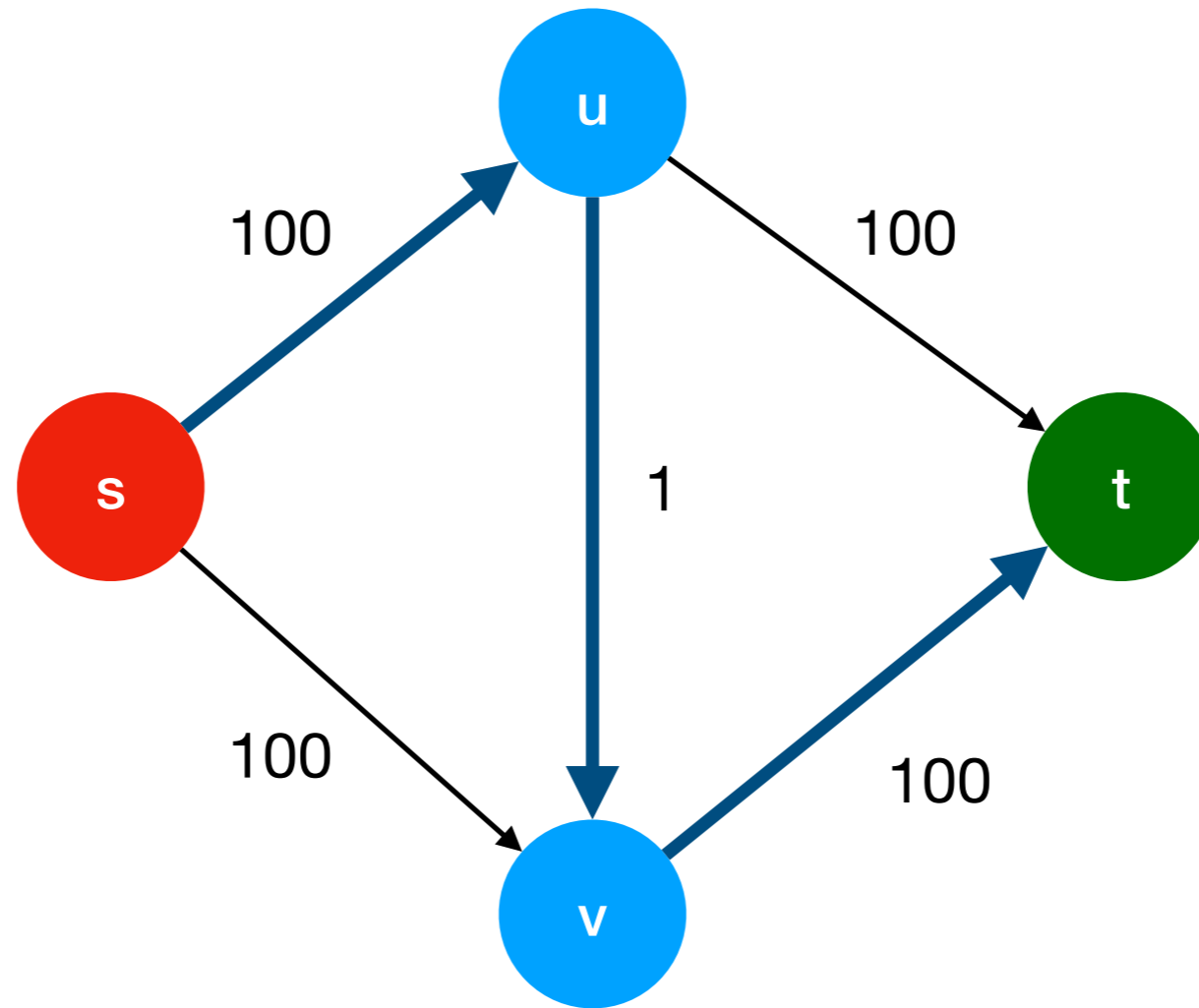
Endwhile

Return (f)

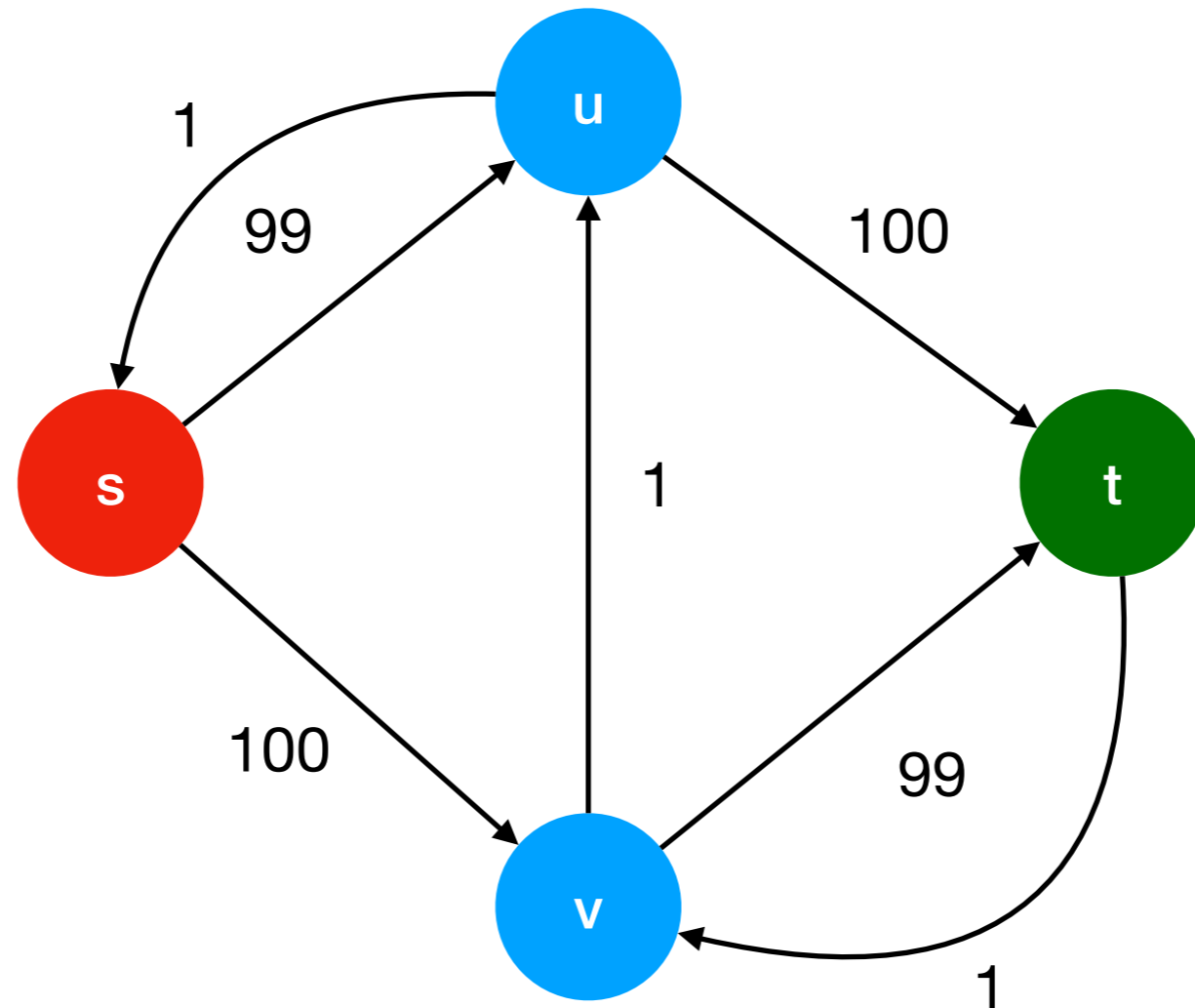
Example



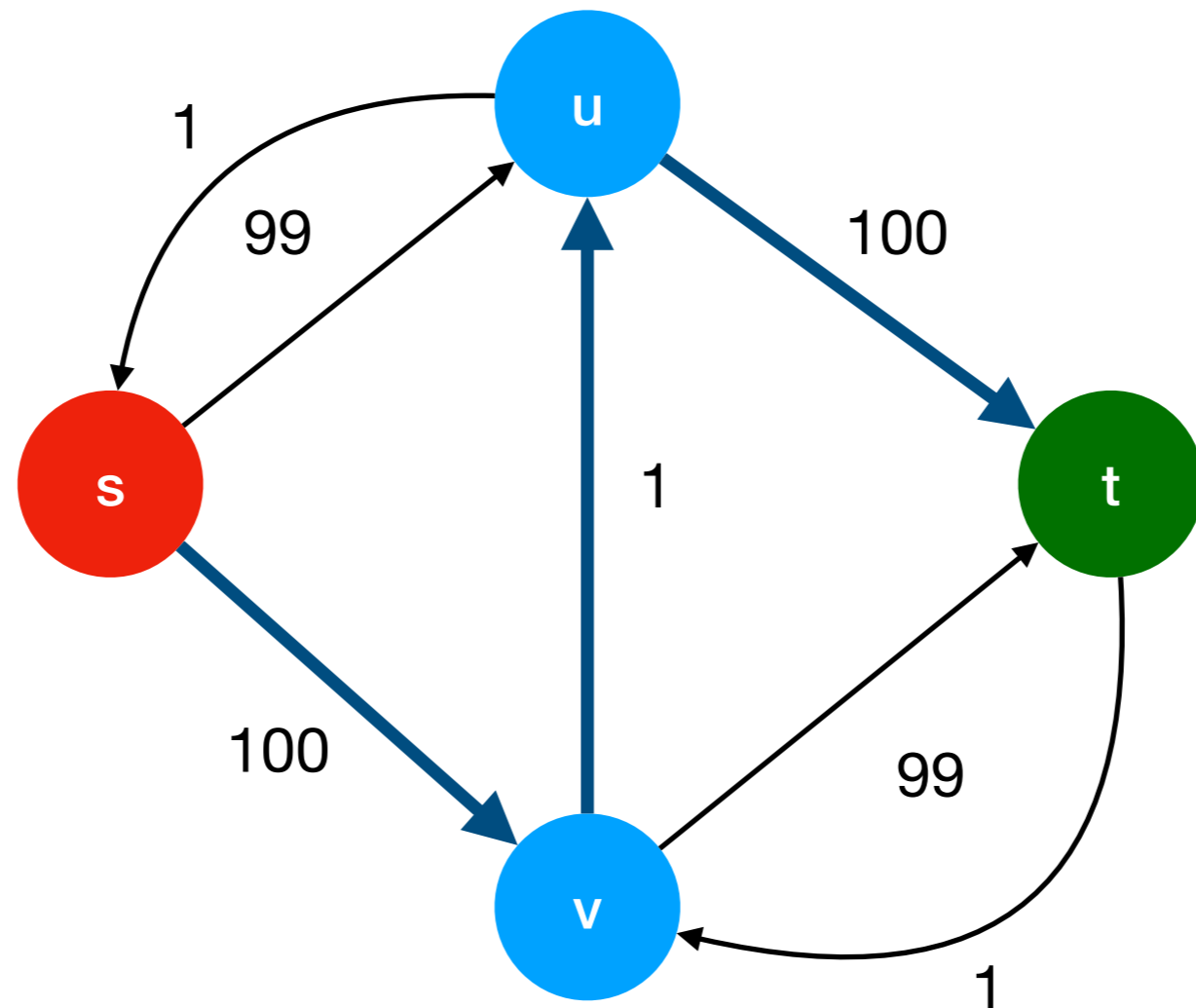
Example



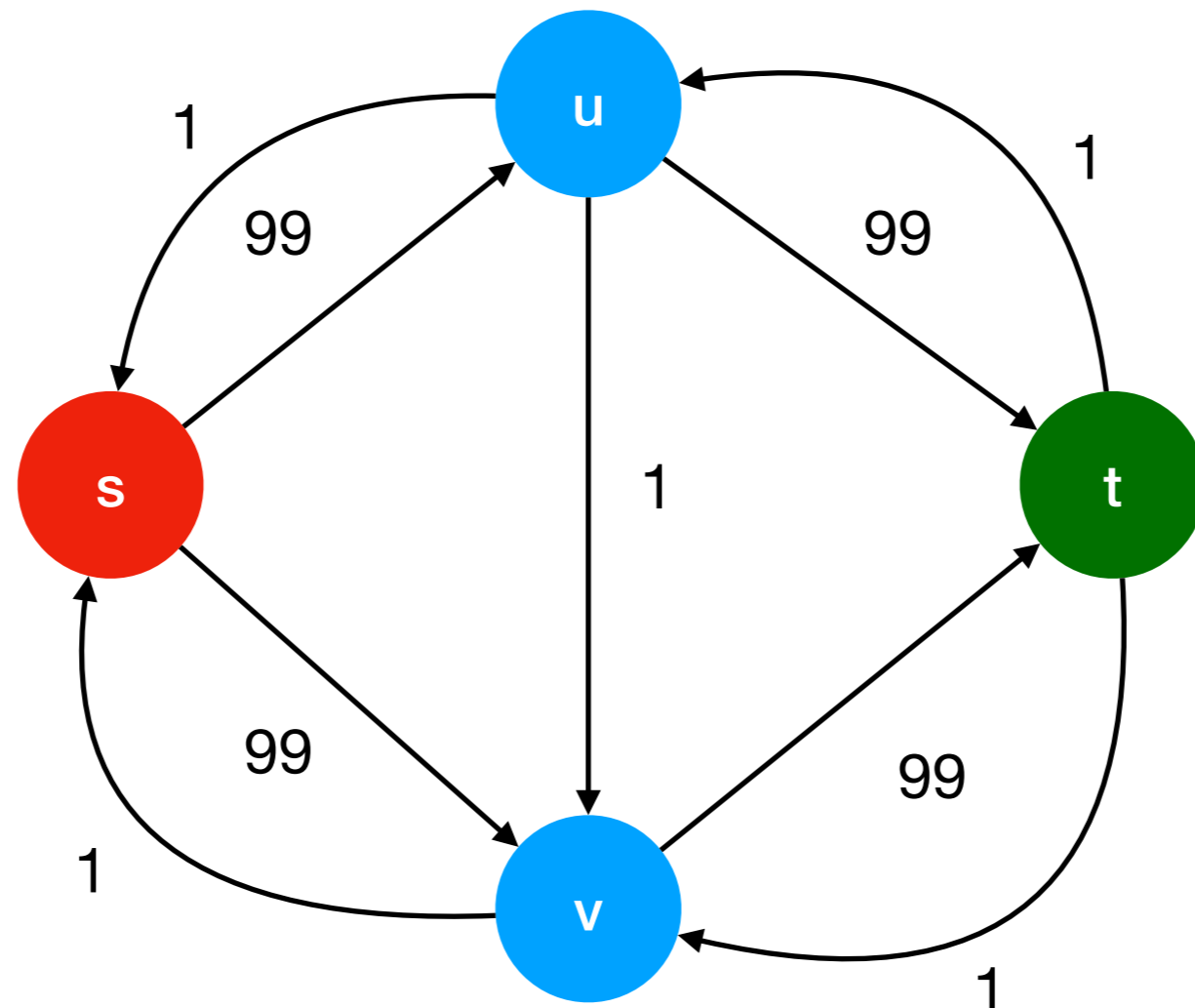
Example



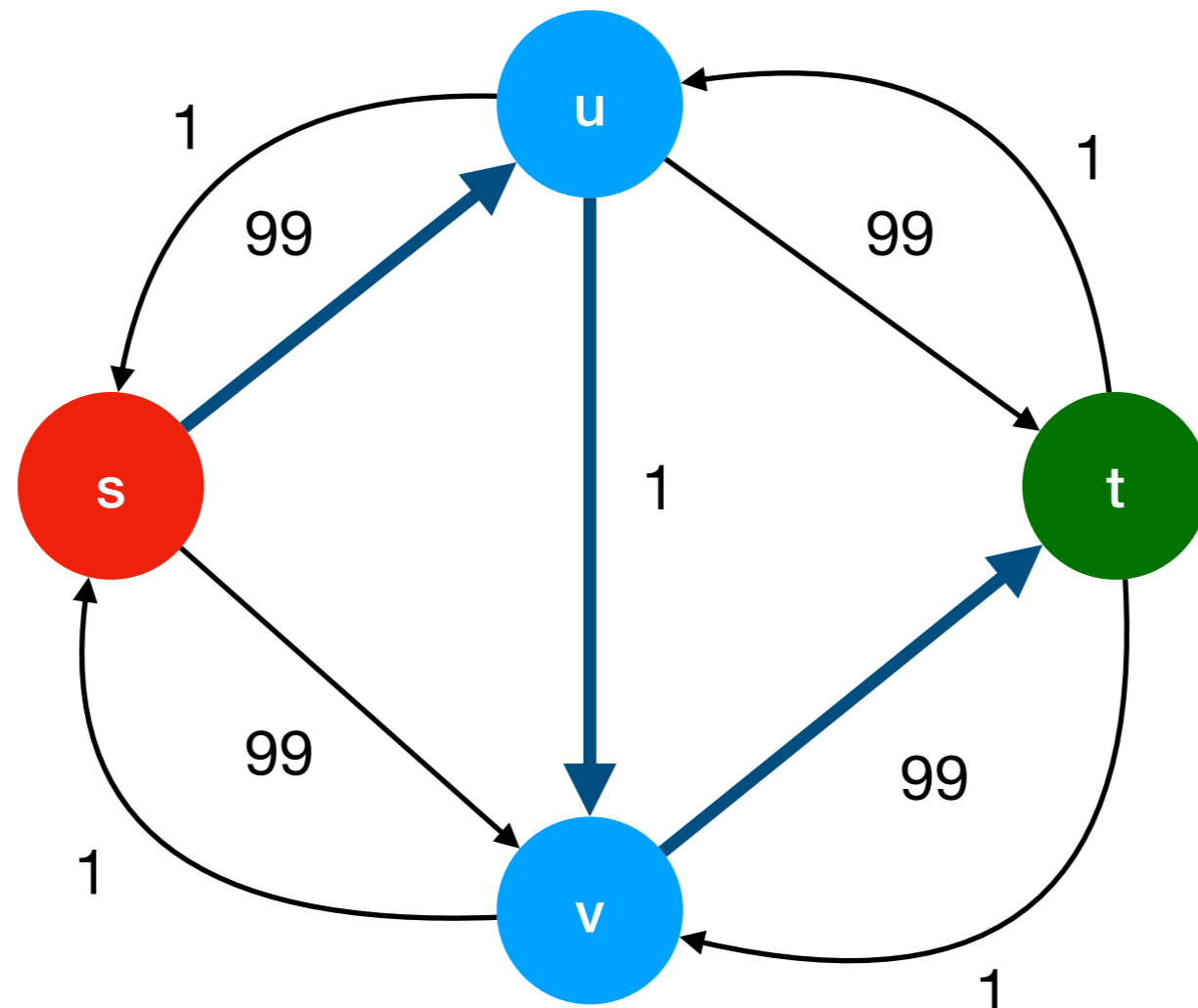
Example



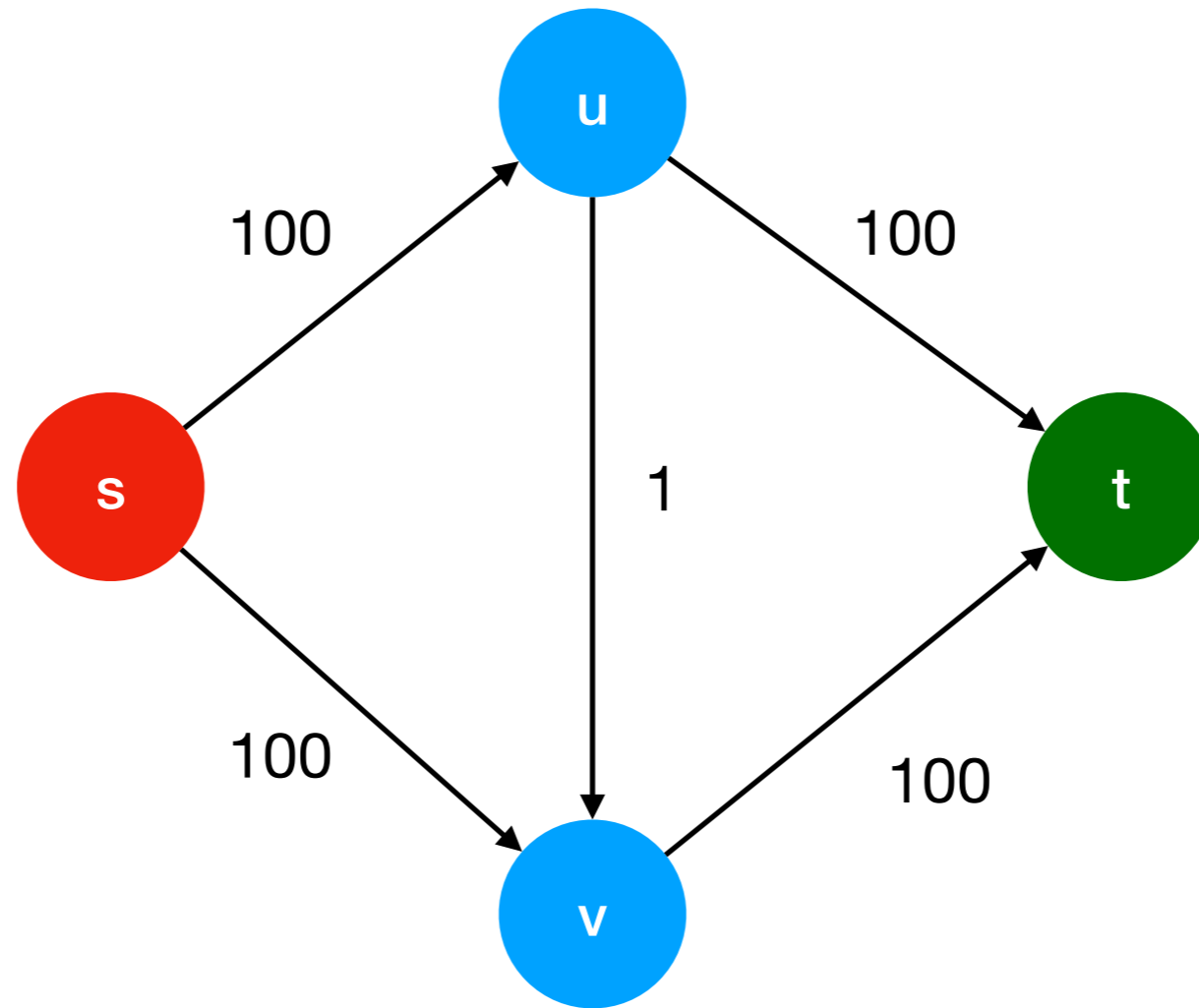
Example



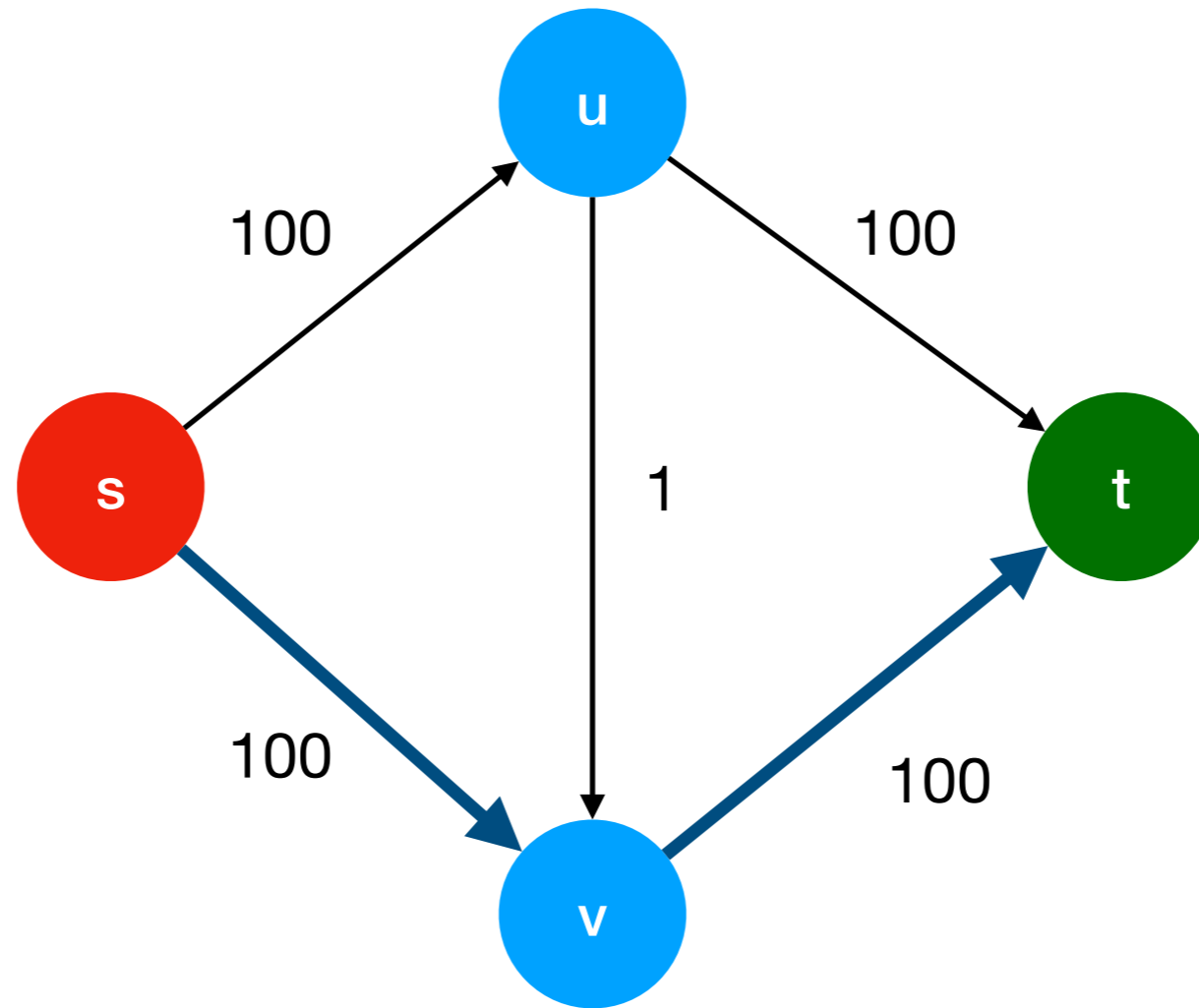
Example



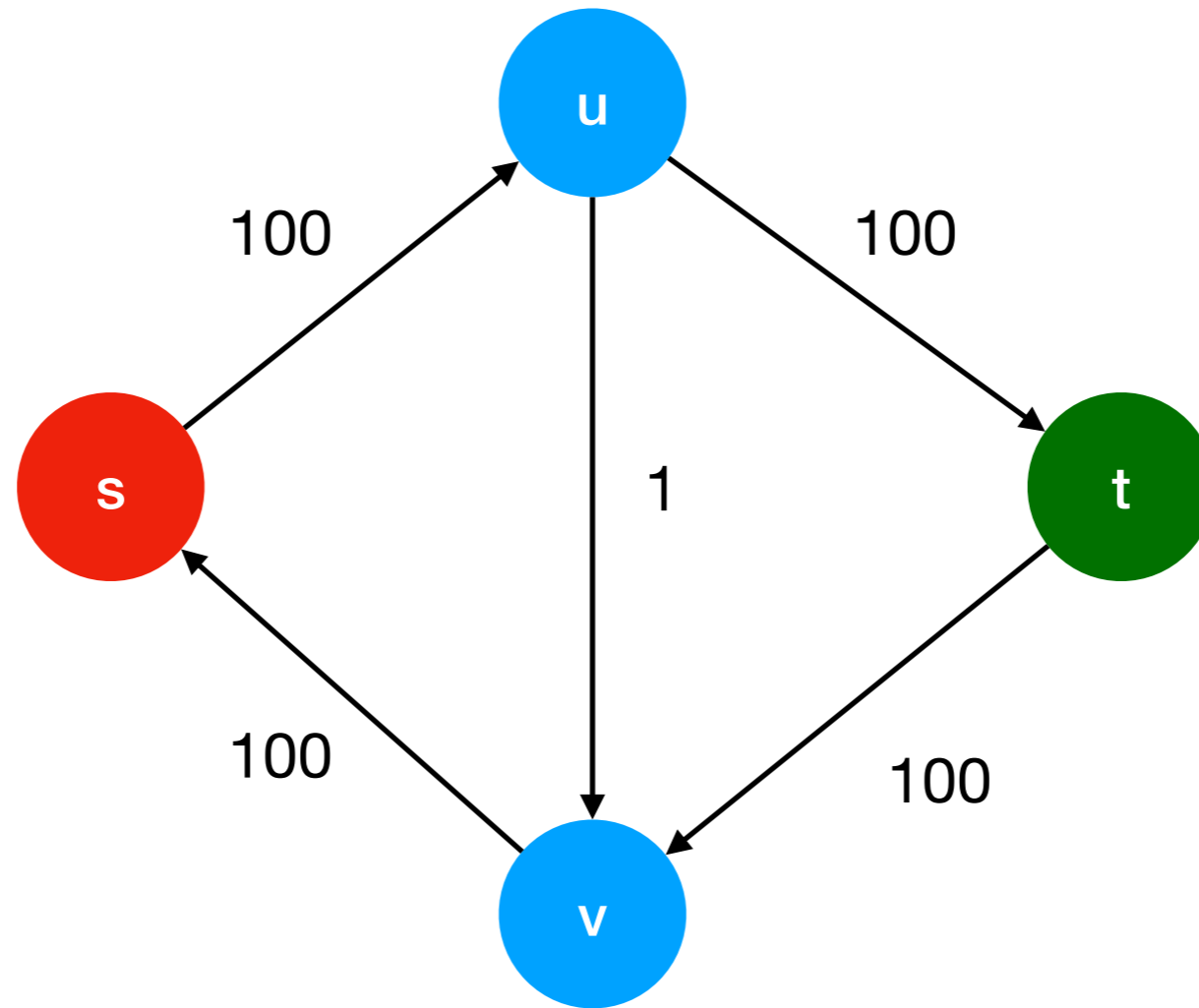
Example



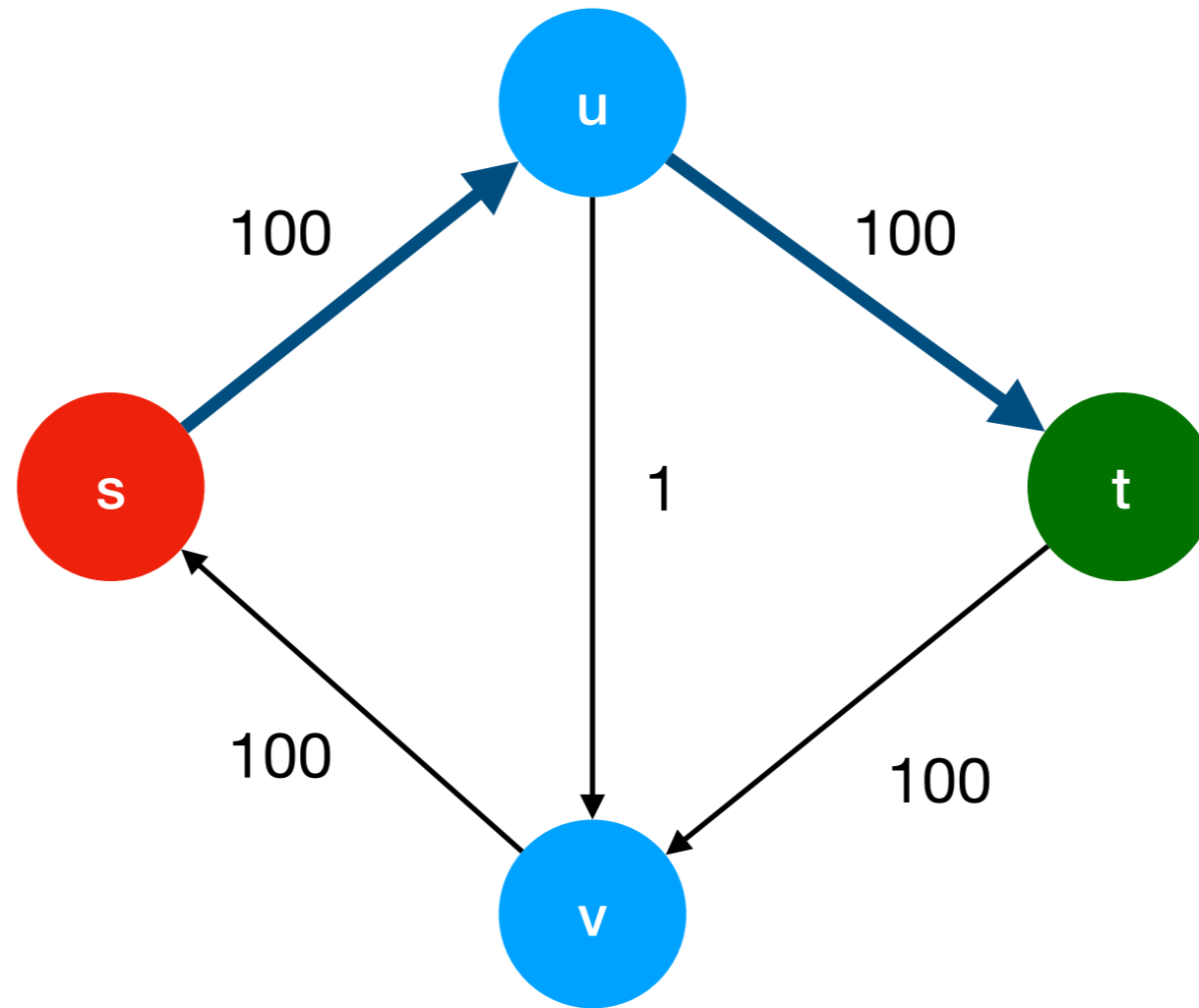
Example



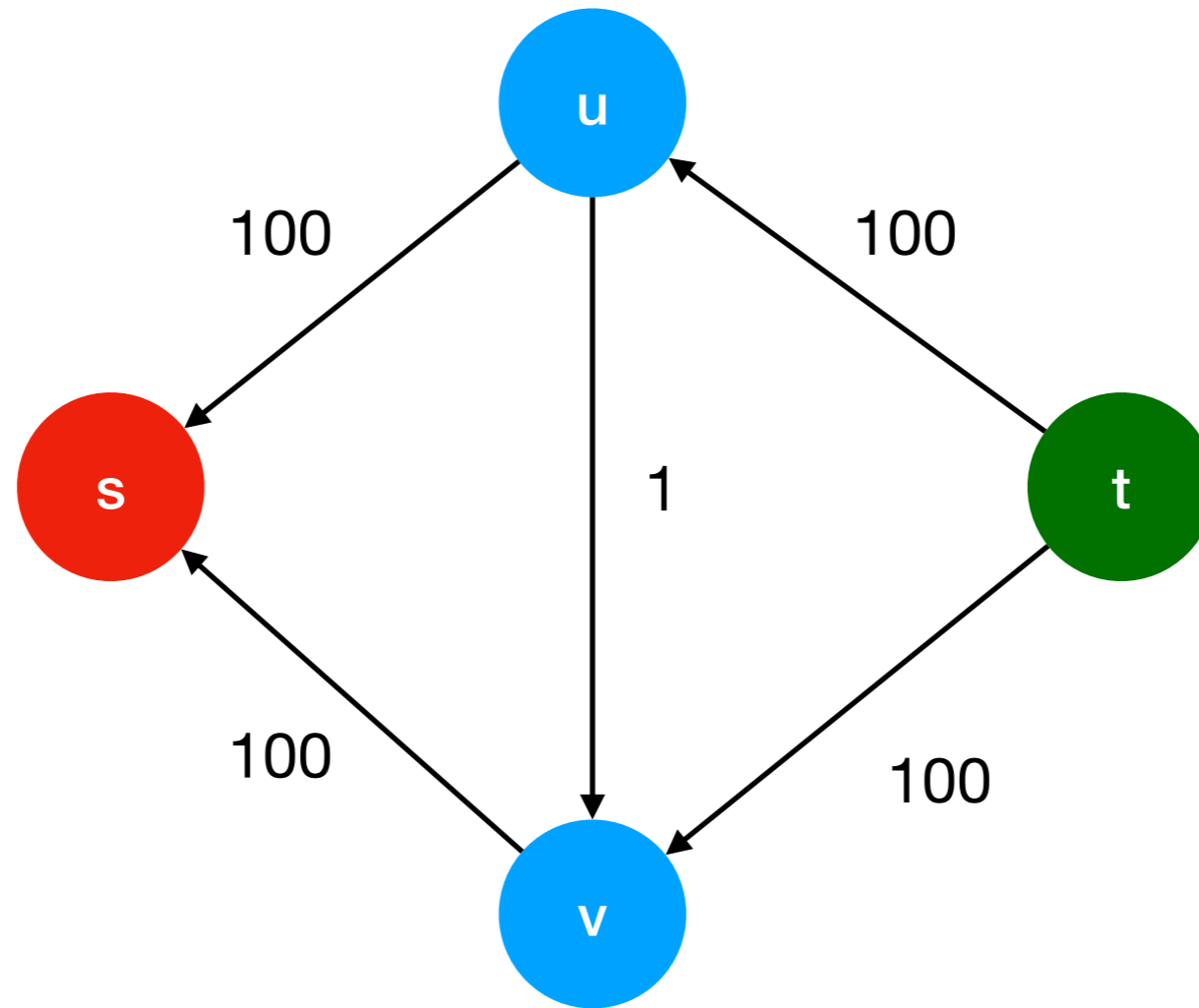
Example



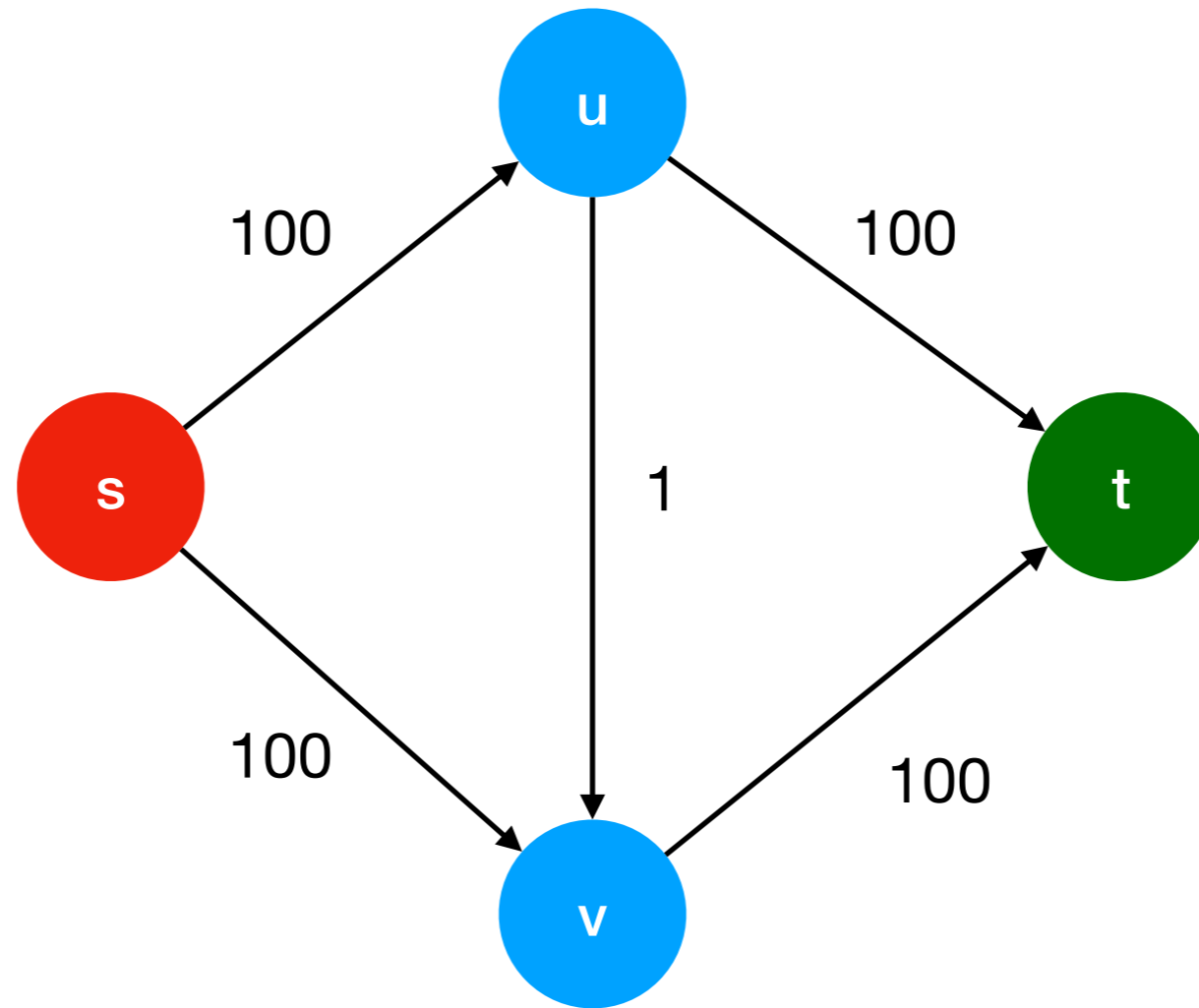
Example



Example



Example



Max-Flow in polynomial time

We made the algorithm must faster by simply selecting the shortest path with available capacity.

Can we always hope to do that?

The Ford-Fulkerson Algorithm

Max-Flow

Initially set $f(e) = 0$ for all e in E .

While there exists an s - t path in the residual graph G_f

 Choose such a path P

$f' = \text{augment}(f, P)$

 Update f to be f'

 Update the residual graph to be $G_{f'}$

Endwhile

Return (f)

The Edmonds-Karp Algorithm

Max-Flow

Initially set $f(e) = 0$ for all e in E .

While there exists an s - t path in the residual graph G_f

 Choose the shortest such path P

$f' = \text{augment}(f, P)$

 Update f to be f'

 Update the residual graph to be $G_{f'}$

Endwhile

Return (f)

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Suppose $(u, v) \in E_f$, then:

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Suppose $(u, v) \in E_f$, then:

$$d_f(s, v) \leq d_f(s, u) + 1 \leq d_{f'}(s, u) + 1 = d_{f'}(s, v)$$

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Suppose $(u, v) \in E_f$, then:

why?

$$d_f(s, v) \leq d_f(s, u) + 1 \leq d_{f'}(s, u) + 1 = d_{f'}(s, v)$$

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Suppose $(u, v) \in E_f$, then:

$$d_f(s, v) \stackrel{\text{why?}}{\leq} d_f(s, u) + 1 \stackrel{\text{why?}}{\leq} d_{f'}(s, u) + 1 = d_{f'}(s, v)$$

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Suppose $(u, v) \in E_f$, then:

$$d_f(s, v) \stackrel{\text{why?}}{\leq} d_f(s, u) + 1 \stackrel{\text{why?}}{\leq} d_{f'}(s, u) + 1 \stackrel{\text{why?}}{=} d_{f'}(s, v)$$

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ i.e., u is the “previous” node on the path before v .

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Suppose $(u, v) \in E_f$, then:

$$d_f(s, v) \leq d_f(s, u) + 1 \leq d_{f'}(s, u) + 1 = d_{f'}(s, v)$$

Useful Lemma

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Suppose $(u, v) \in E_f$, then:

$$d_f(s, v) \leq d_f(s, u) + 1 \leq d_{f'}(s, u) + 1 = d_{f'}(s, v)$$

This is a contradiction, hence $(u, v) \notin E_f$

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f weakly increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_f(s, v)$ for which $d_f(s, v) > d_{f'}(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in G_f such that $d_f(s, u) = d_f(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f weakly increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_f(s, v)$ for which $d_f(s, v) > d_{f'}(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_f(s, u) \geq d_{f'}(s, u)$ (why?)

Useful Lemma

Useful Lemma

So we have $(u, v) \in E_{f'}$ but
 $(u, v) \notin E_f$.

Useful Lemma

So we have $(u, v) \in E_{f'}$ but
 $(u, v) \notin E_f$.

Flow must have been routed
through (v, u) (in the opposite
direction).

Useful Lemma

So we have $(u, v) \in E_{f'}$ but
 $(u, v) \notin E_f$.

Flow must have been routed
through (v, u) (in the opposite
direction).

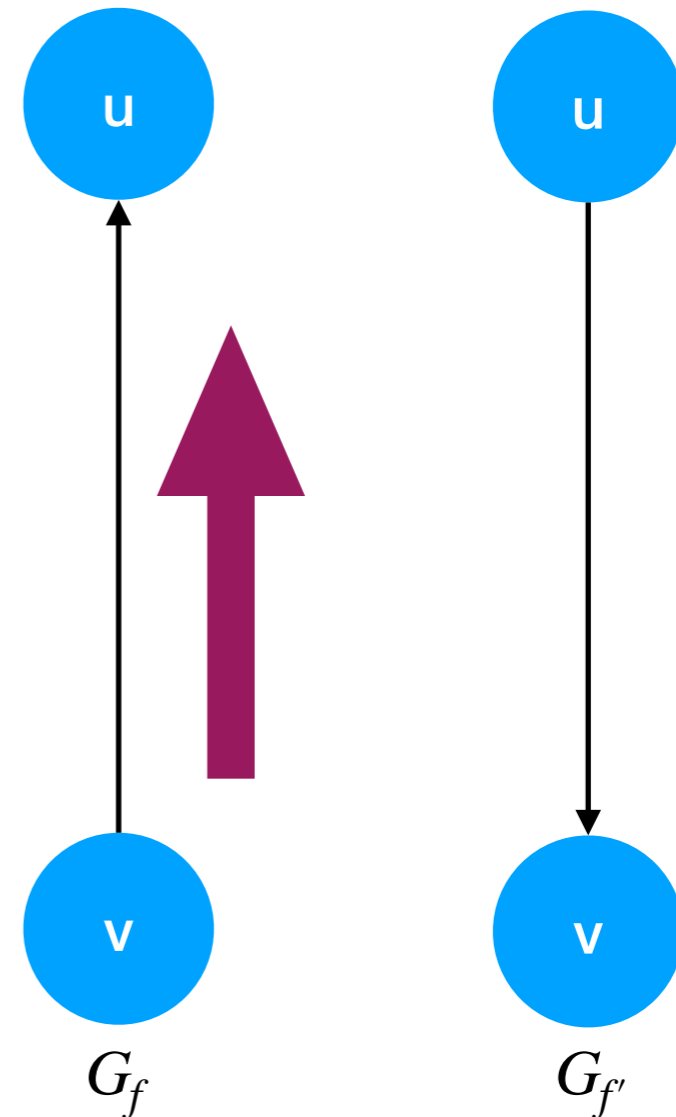
That means that (v, u) was part
of the chosen augmenting path,
which was a shortest (s, t) path
in G_f .

Useful Lemma

So we have $(u, v) \in E_{f'}$ but $(u, v) \notin E_f$.

Flow must have been routed through (v, u) (in the opposite direction).

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .



Useful Lemma

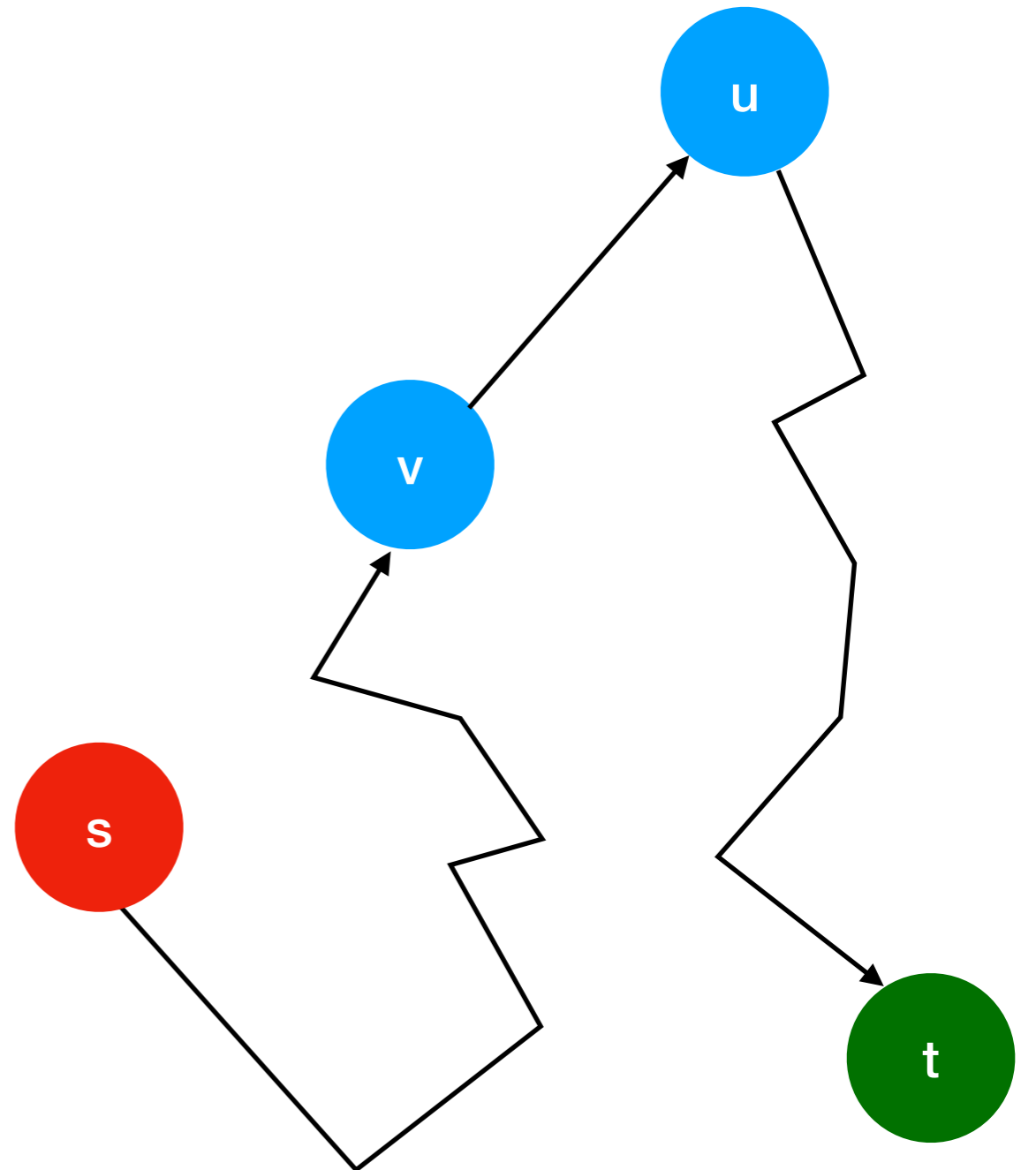
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

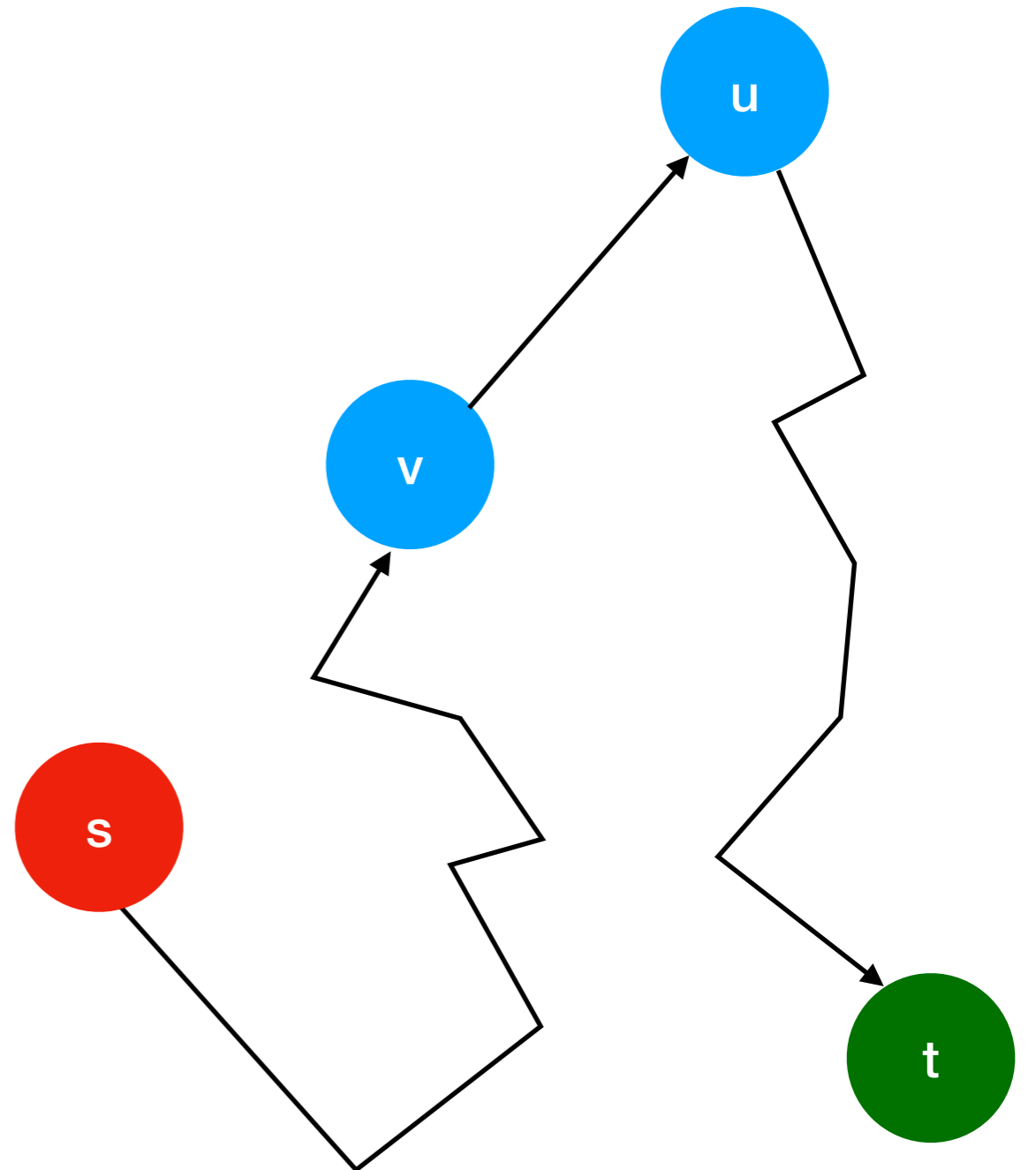


Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have



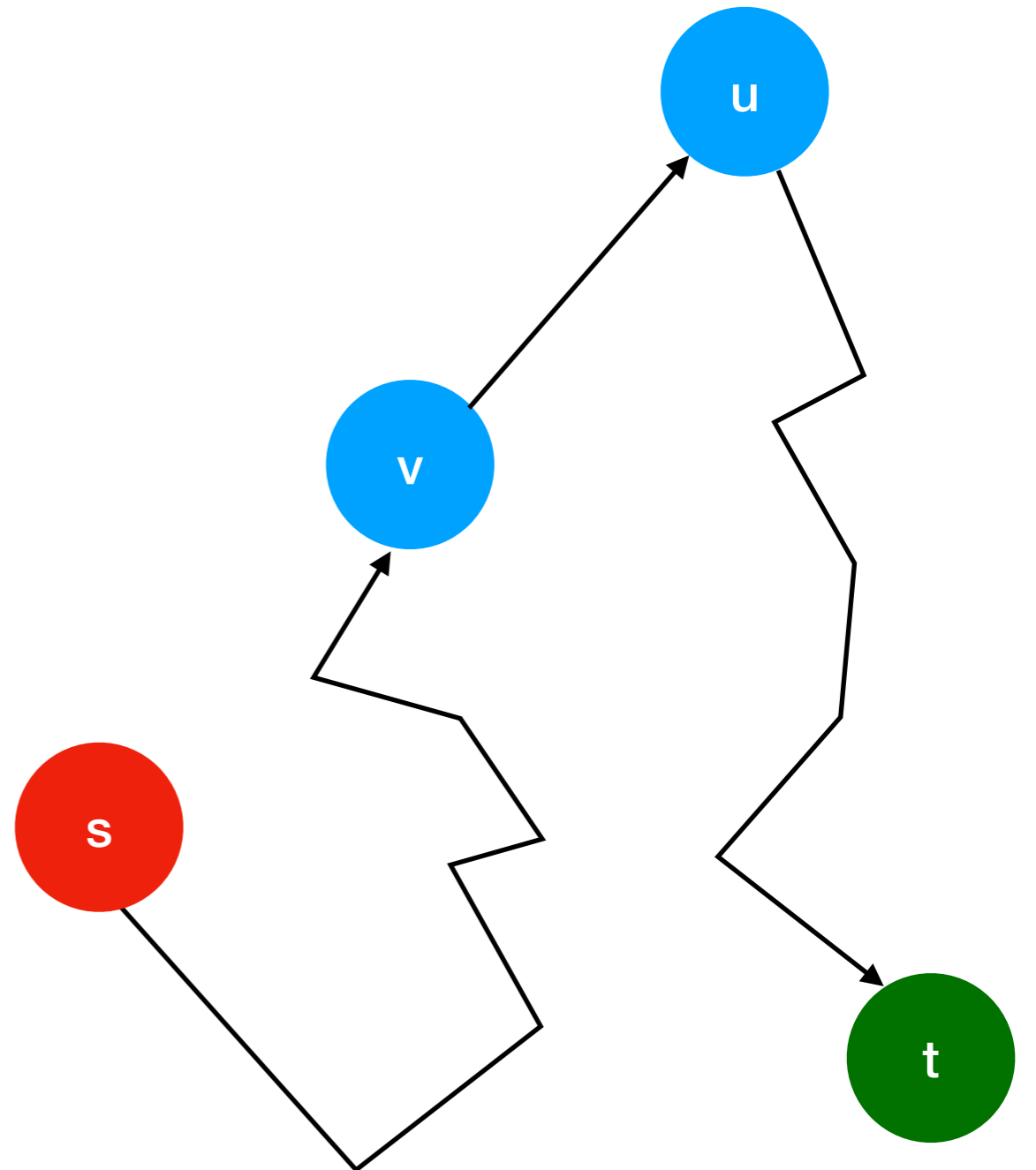
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$d_f(s, v) =$$



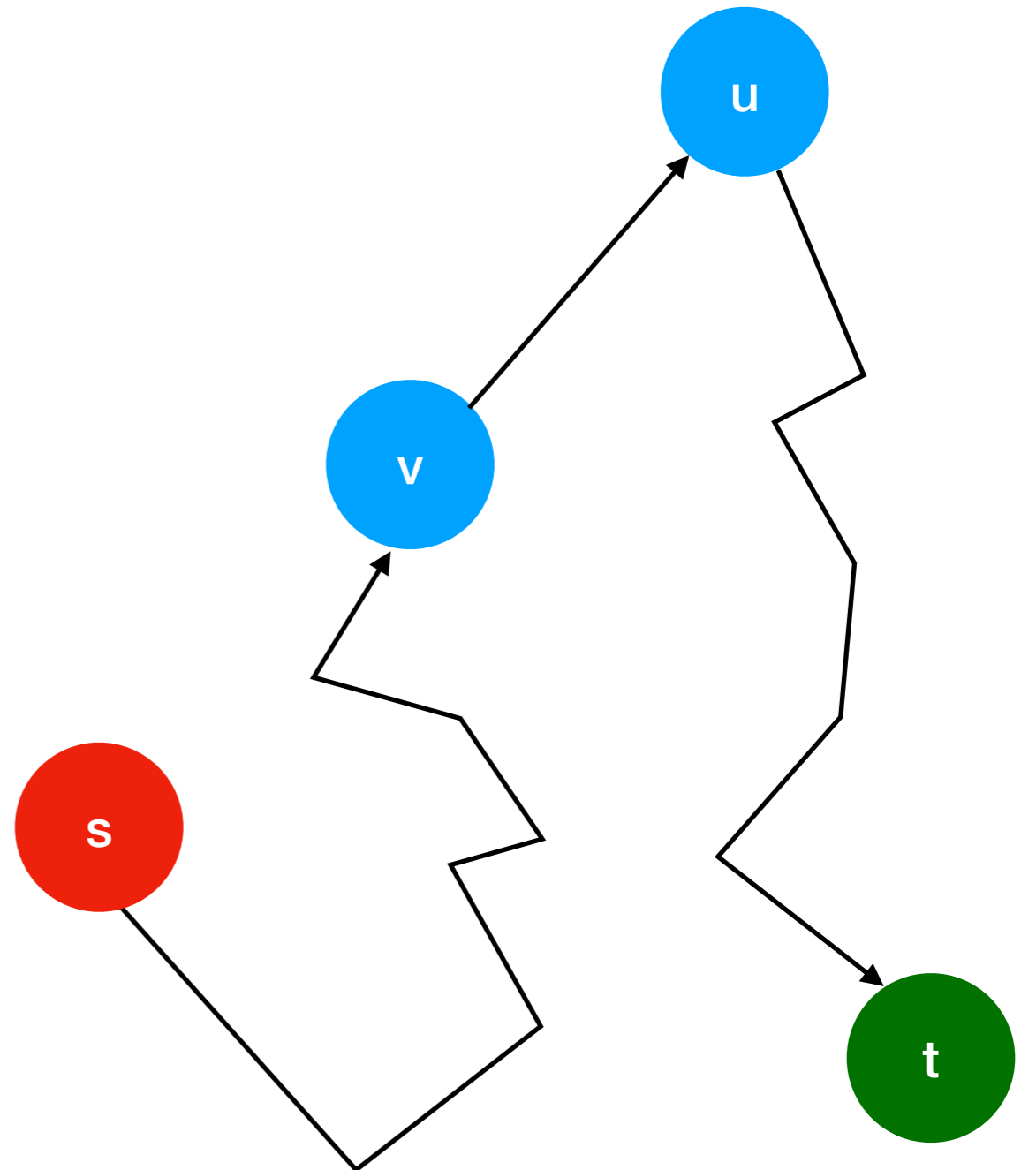
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$d_f(s, v) = d_f(s, u) - 1$$



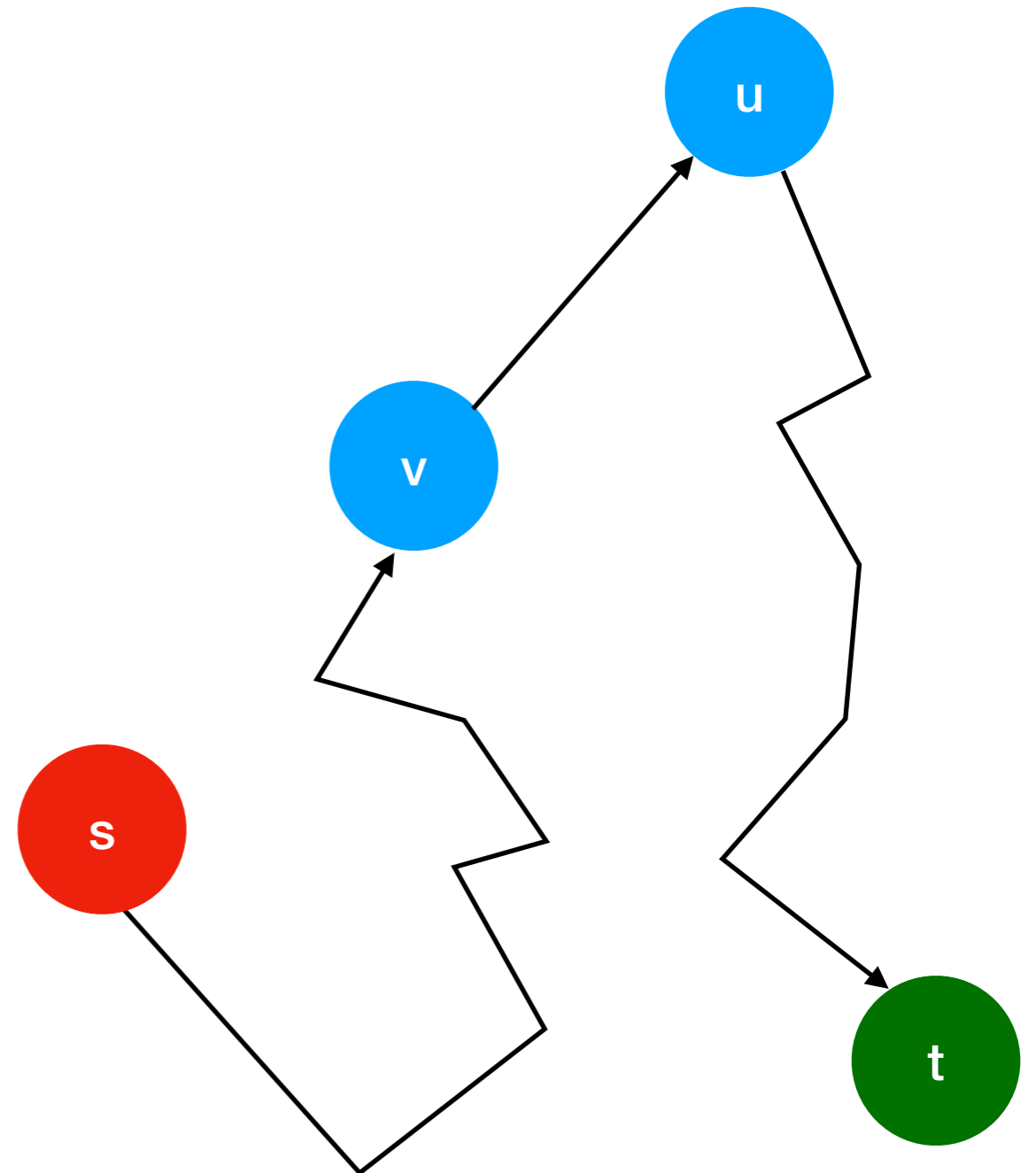
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$d_f(s, v) = d_f(s, u) - 1 \quad \text{obvious}$$



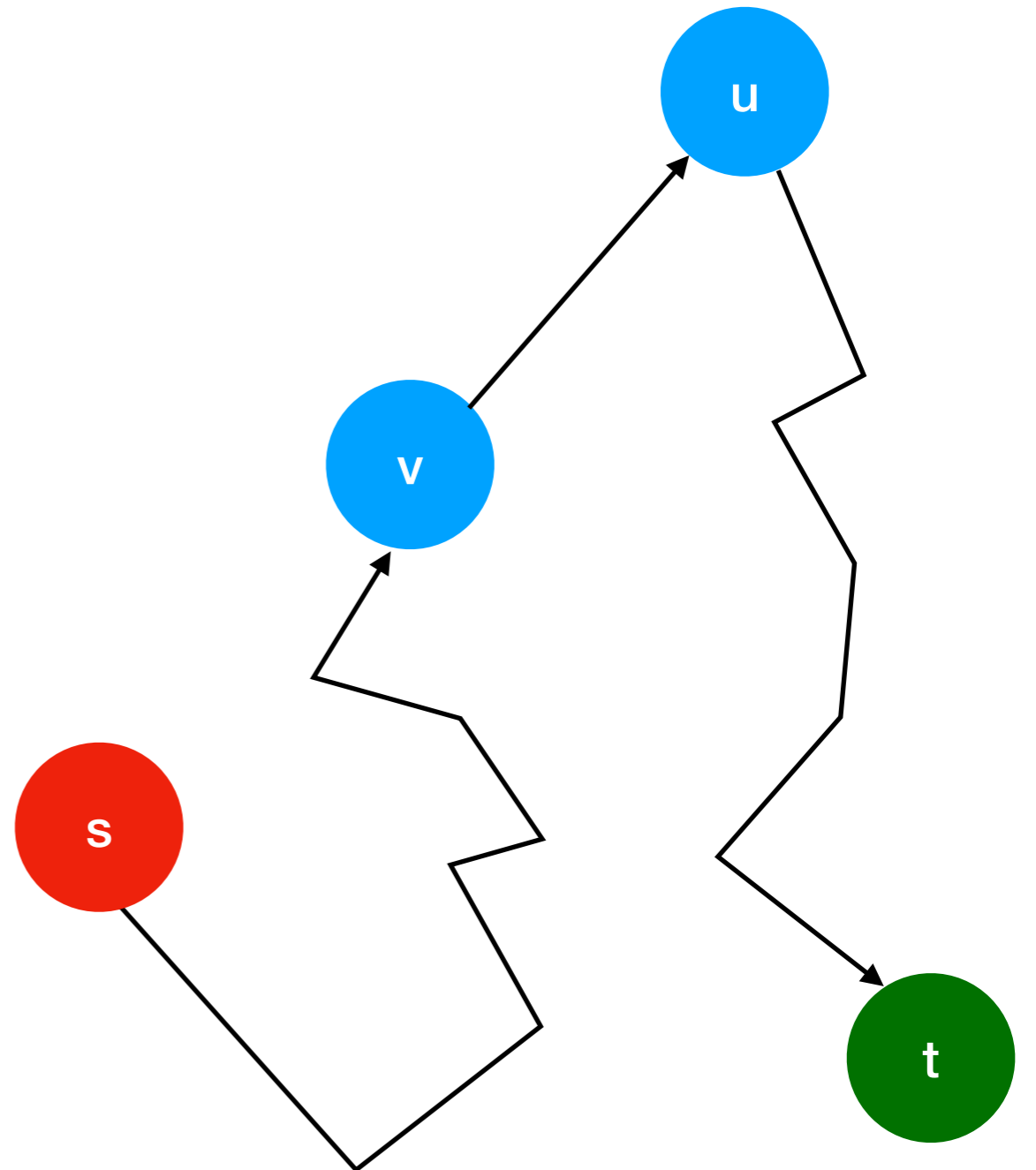
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$\begin{aligned}d_f(s, v) &= d_f(s, u) - 1 \quad \text{obvious} \\ &\leq d_f(s, u) - 1\end{aligned}$$



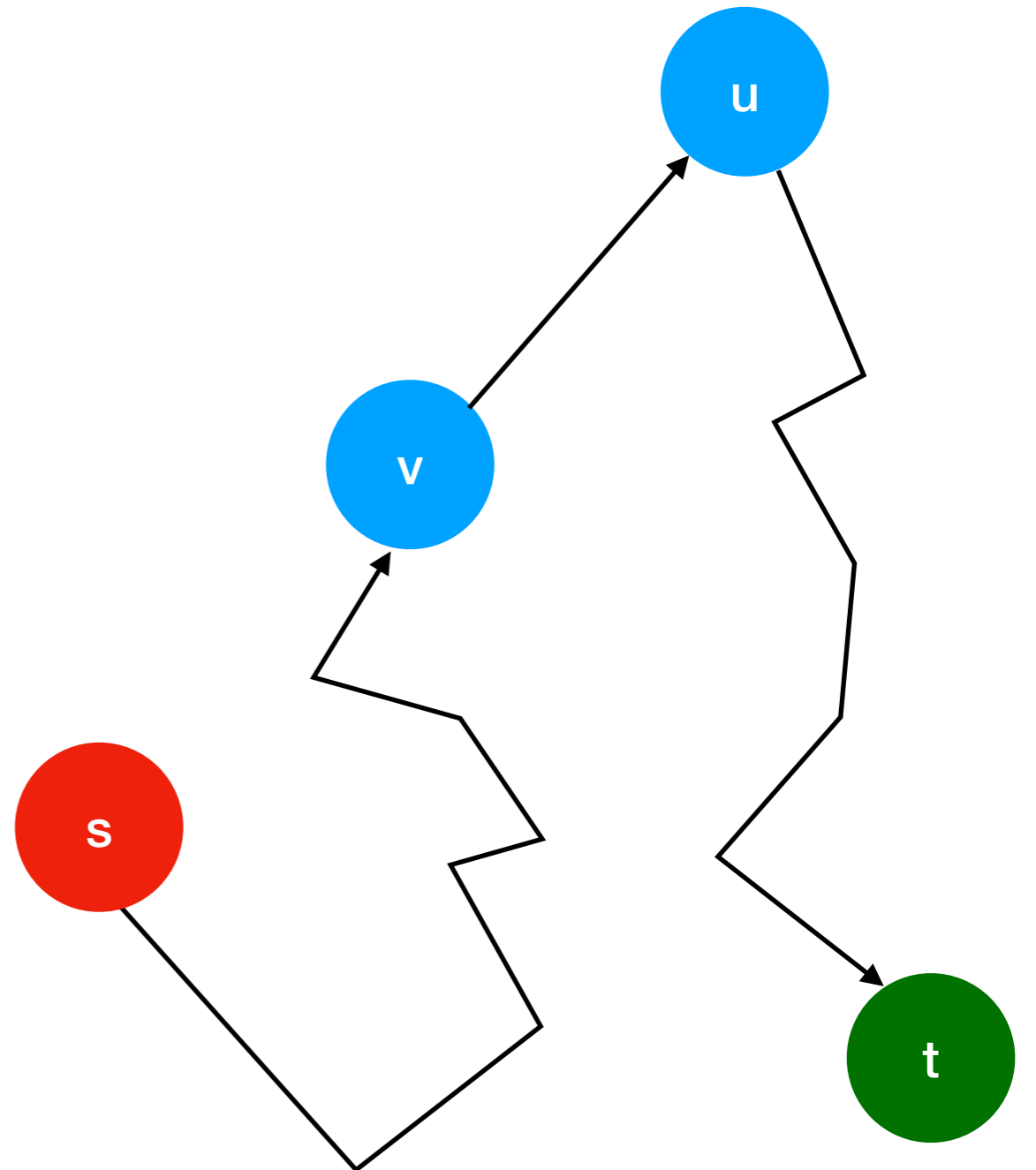
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$\begin{aligned} d_f(s, v) &= d_f(s, u) - 1 && \text{obvious} \\ &\leq d_f(s, u) - 1 && \text{why?} \end{aligned}$$



Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

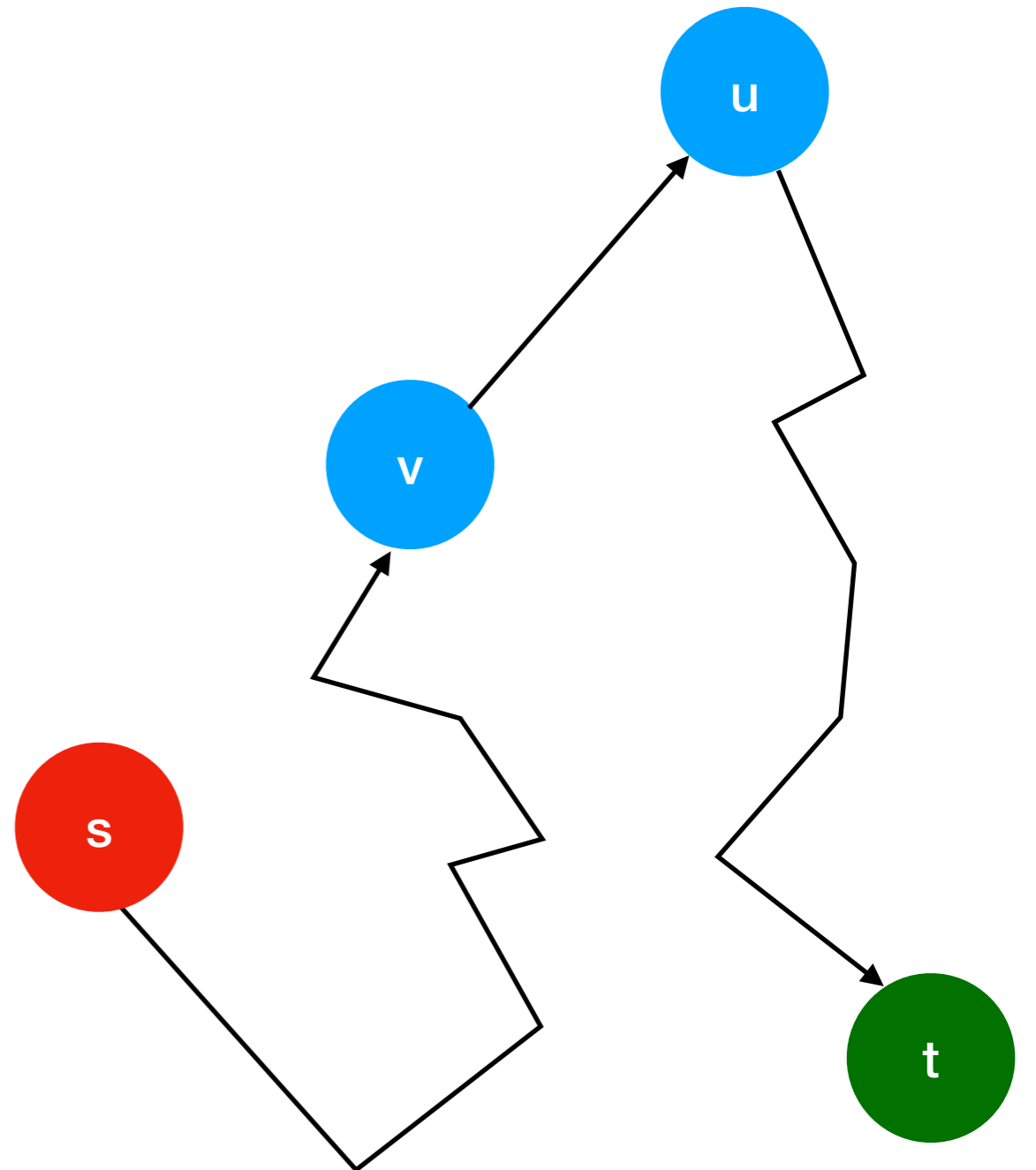
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$\begin{aligned}d_f(s, v) &= d_f(s, u) - 1 && \text{obvious} \\ &\leq d_f(s, u) - 1 && \text{why?}\end{aligned}$$



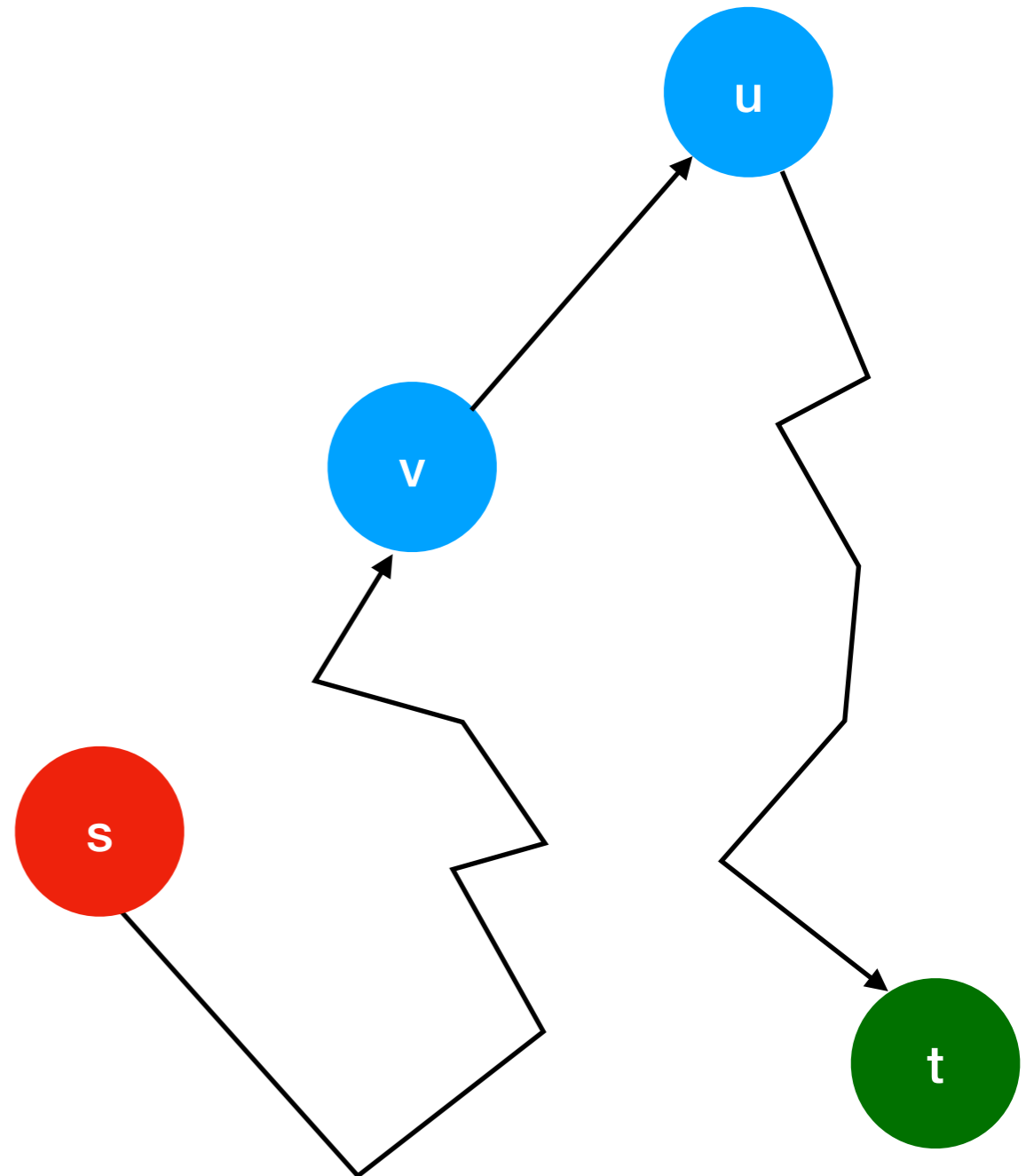
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$\begin{aligned}d_f(s, v) &= d_f(s, u) - 1 && \text{obvious} \\ &\leq d_{f'}(s, u) - 1 && \text{why?} \\ &= d_{f'}(s, v) - 2\end{aligned}$$



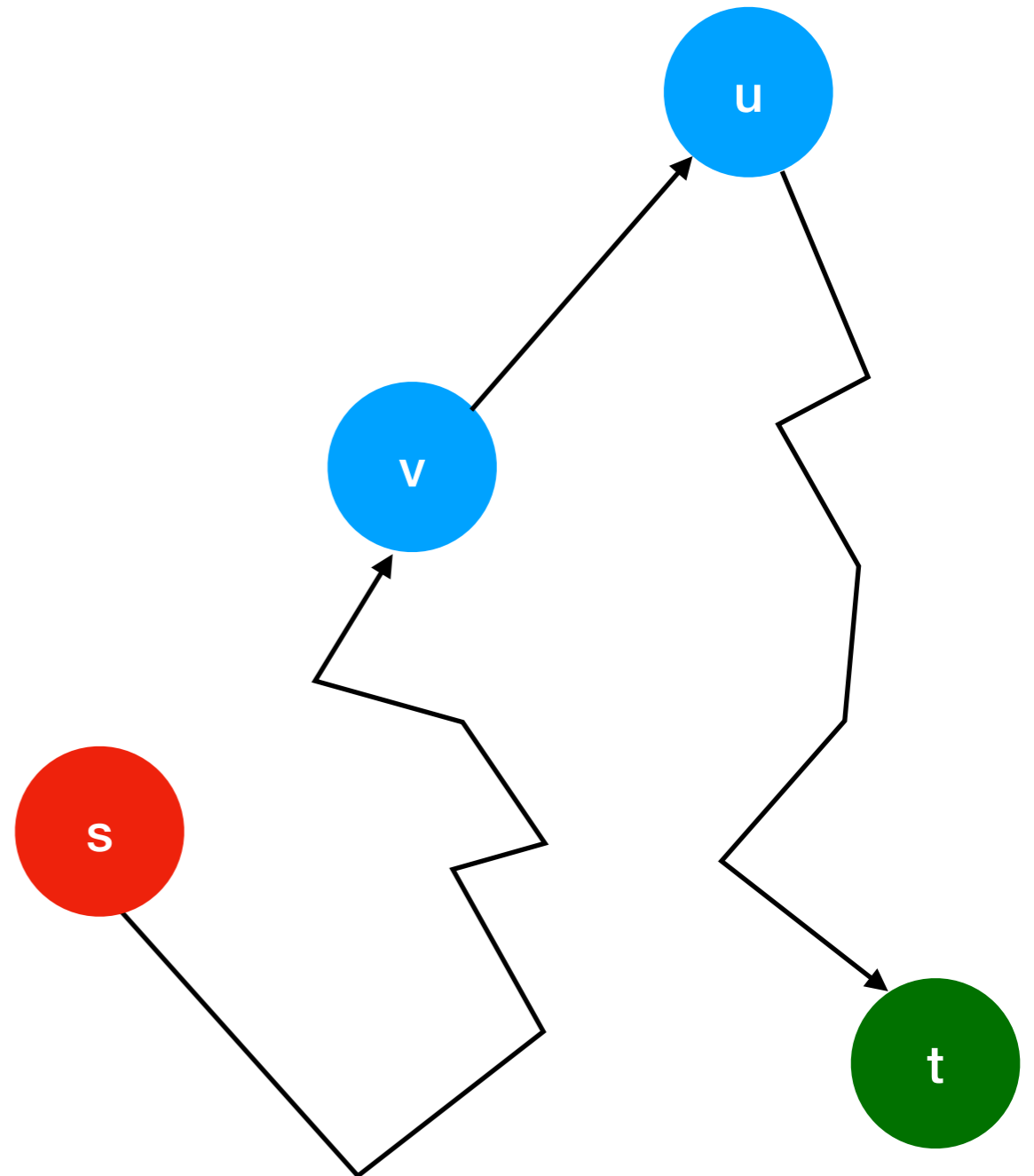
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$\begin{aligned}d_f(s, v) &= d_f(s, u) - 1 && \text{obvious} \\ &\leq d_{f'}(s, u) - 1 && \text{why?} \\ &= d_{f'}(s, v) - 2 && \text{why?}\end{aligned}$$



Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

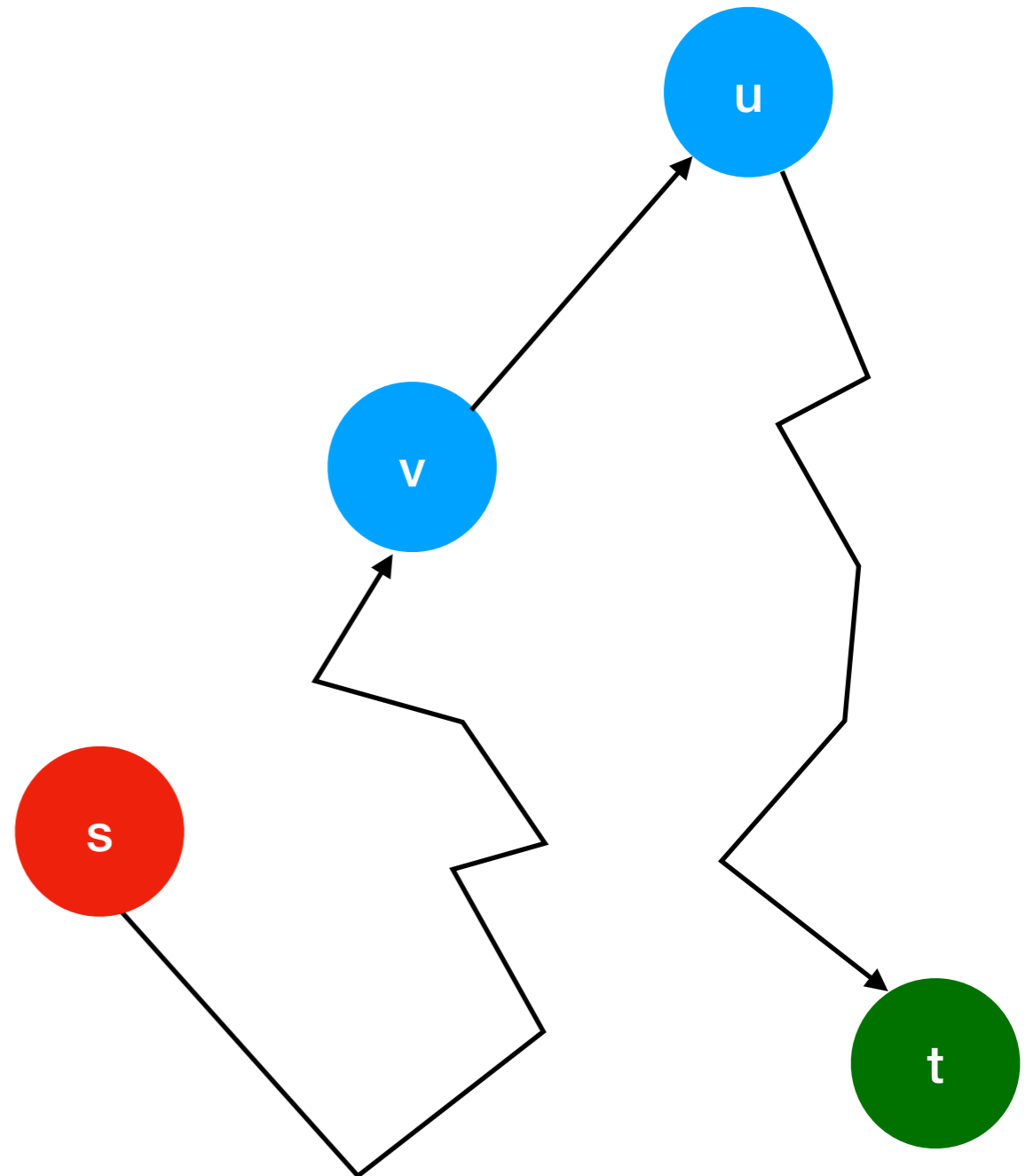
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$\begin{aligned}d_f(s, v) &= d_f(s, u) - 1 && \text{obvious} \\ &\leq d_{f'}(s, u) - 1 && \text{why?} \\ &= d_{f'}(s, v) - 2 && \text{why?}\end{aligned}$$



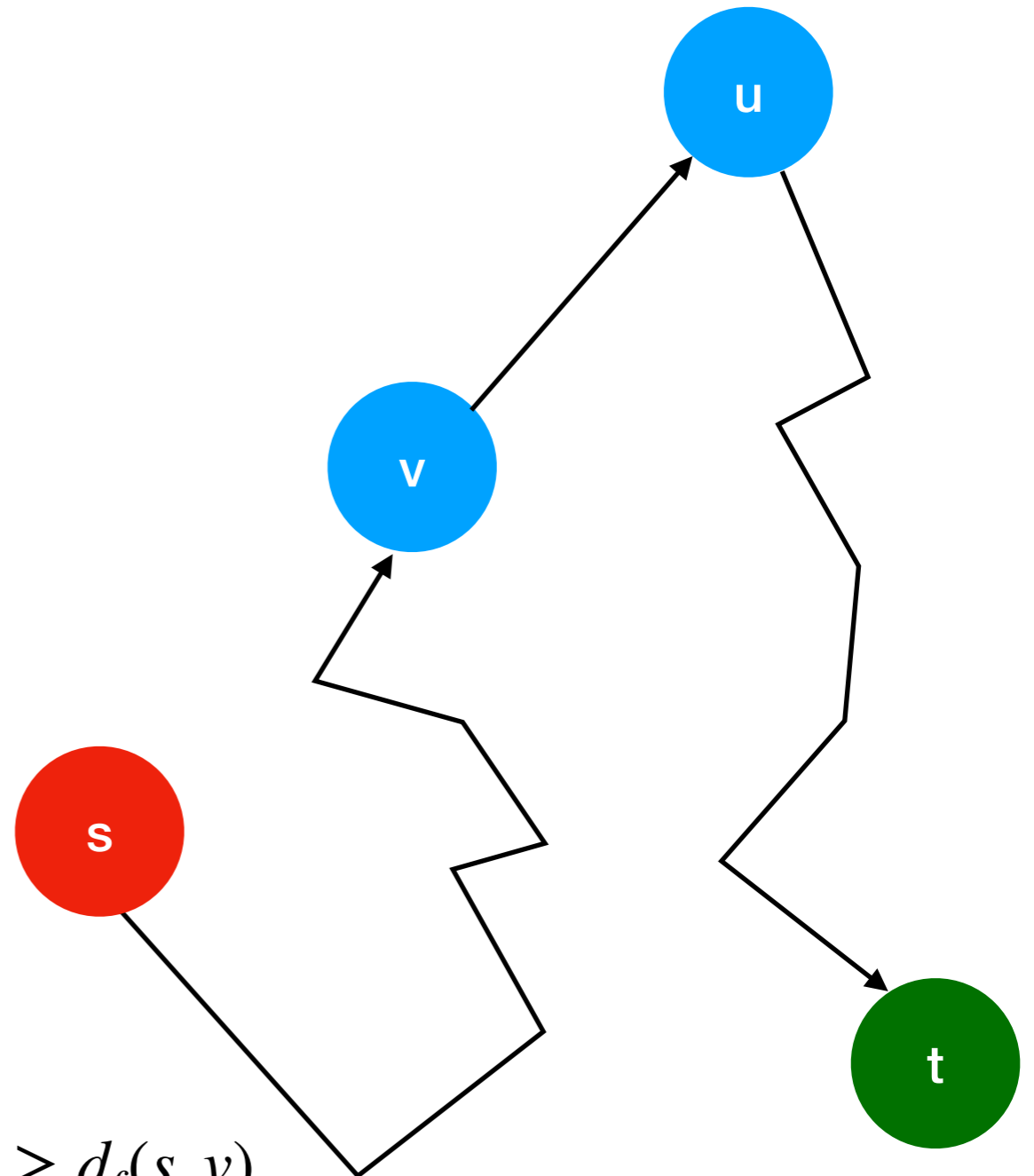
Useful Lemma

That means that (v, u) was part of the chosen augmenting path, which was a shortest (s, t) path in G_f .

Consider the sub-path (s, u) of the (s, t) path above. This is also a shortest (s, u) path.

We have

$$\begin{aligned} d_f(s, v) &= d_f(s, u) - 1 && \text{obvious} \\ &\leq d_{f'}(s, u) - 1 && \text{why?} \\ &= d_{f'}(s, v) - 2 && \text{why?} \end{aligned} \quad \Rightarrow \quad d_{f'}(s, v) \geq d_f(s, v)$$



Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

Let v be the node with the minimum $d_{f'}(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in $G_{f'}$ such that $d_{f'}(s, u) = d_{f'}(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Useful Lemma

Lemma: Suppose that we run the Edmonds-Karp algorithm on a flow network $G = (V, E)$. For every node $u \in V \setminus \{s, t\}$, the length of the shortest path $d_f(s, u)$ from s to u in the residual graph G_f given by f increases with each flow augmentation.

Proof: Suppose that it decreases with some flow augmentation; let f to f' be this augmentation.

contradiction!

Let v be the node with the minimum $d_f(s, v)$ for which $d_{f'}(s, v) < d_f(s, v)$.

Let $p = s \sim u \rightarrow v$ be a shortest path from s to v “via” u in G_f such that $d_f(s, u) = d_f(s, v) - 1$ (i.e., u is the “previous” node on the path before v).

By the choice of v , we know that $d_{f'}(s, u) \geq d_f(s, u)$ (why?)

Edmonds-Karp Running Time

Edmonds-Karp Running Time

Terminology: We will call an edge e *critical*, if $c_e = \text{bottleneck}(P, f)$.

Edmonds-Karp Running Time

Terminology: We will call an edge e *critical*, if $c_e = \text{bottleneck}(P, f)$.

What is the effect that augmenting the flow to f on P has on e in the residual graph G_f ?

Edmonds-Karp Running Time

Terminology: We will call an edge e *critical*, if $c_e = \text{bottleneck}(P, f)$.

What is the effect that augmenting the flow to f on P has on e in the residual graph G_f ?

It disappears from G_f .

Edmonds-Karp Running Time

Terminology: We will call an edge e *critical*, if $c_e = \text{bottleneck}(P, f)$.

What is the effect that augmenting the flow to f on P has on e in the residual graph G_f ?

It disappears from G_f .

How many critical edges are there at least in P ?

Edmonds-Karp Running Time

Terminology: We will call an edge e *critical*, if $c_e = \text{bottleneck}(P, f)$.

What is the effect that augmenting the flow to f on P has on e in the residual graph G_f ?

It disappears from G_f .

How many critical edges are there at least in P ?

At least 1.

Edmonds-Karp Running Time

Terminology: We will call an edge e *critical*, if $c_e = \text{bottleneck}(P, f)$.

What is the effect that augmenting the flow to f on P has on e in the residual graph G_f ?

It disappears from G_f .

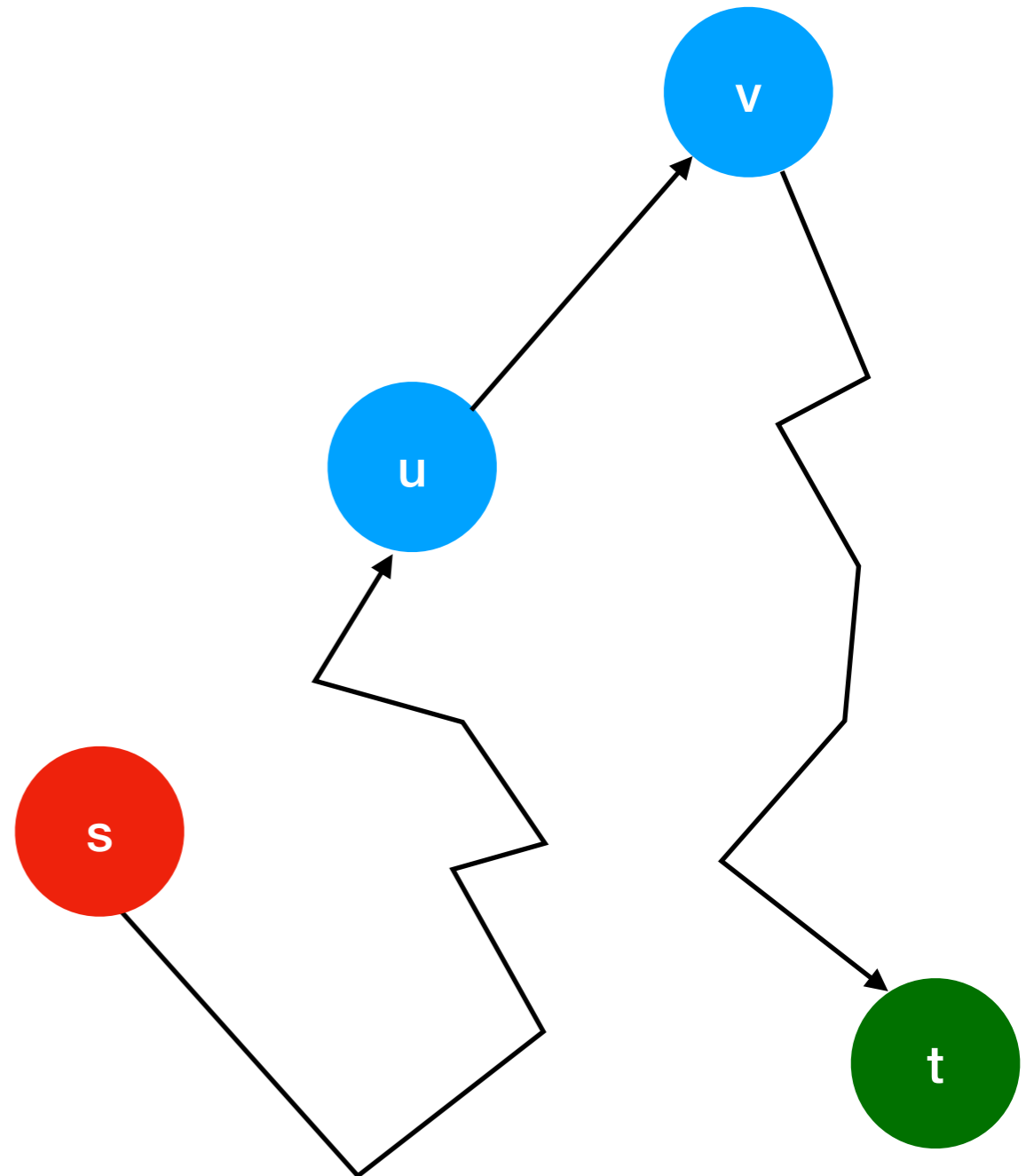
How many critical edges are there at least in P ?

At least 1.

How many times can an edge e become *critical* during the execution of the algorithm?

Edmonds-Karp Running Time

Let (u, v) be an edge.
Consider the first time it becomes **critical**, at which point the residual graph is G_f .

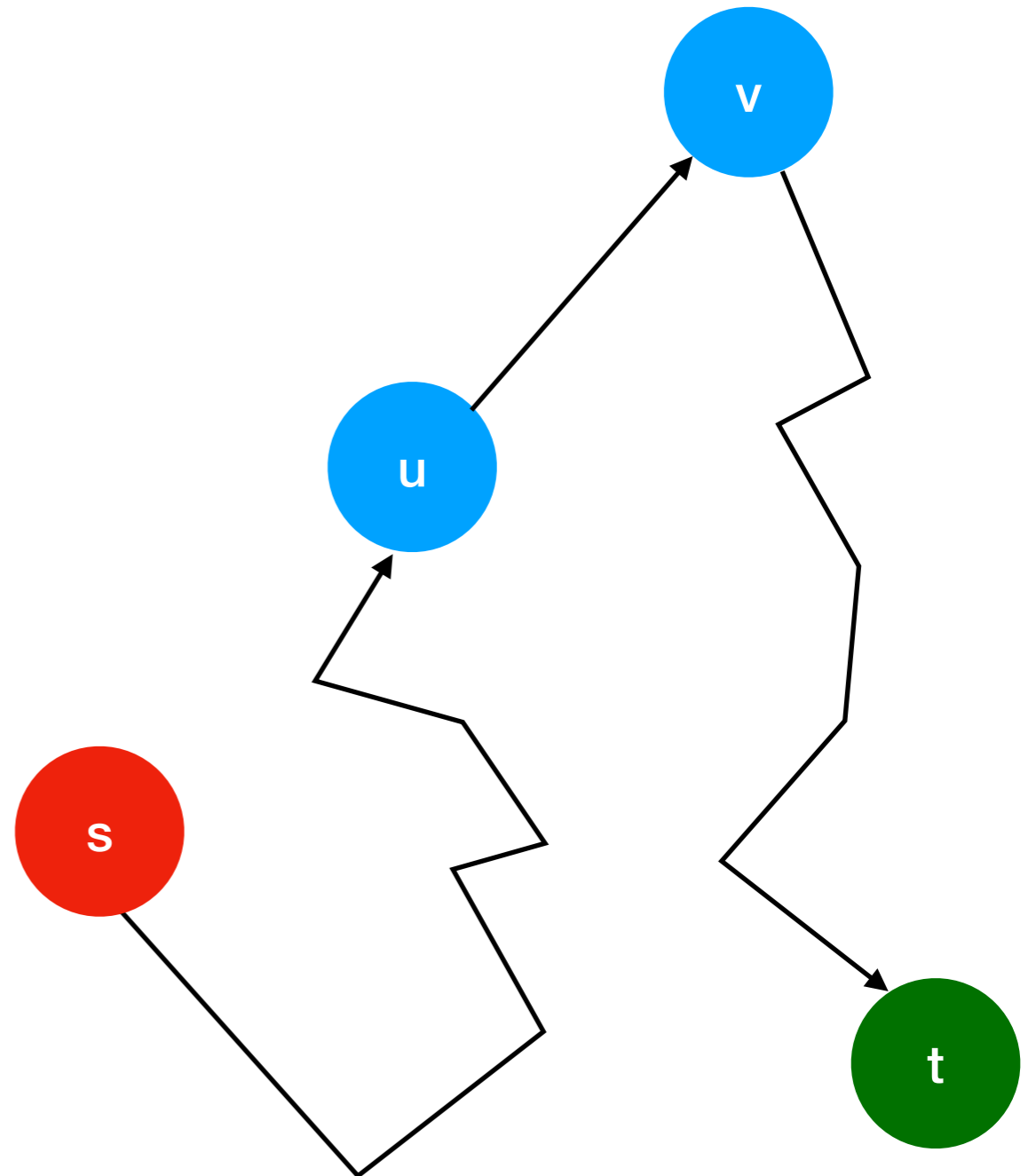


Edmonds-Karp Running Time

Let (u, v) be an edge.
Consider the first time it becomes **critical**, at which point the residual graph is G_f .

We have

$$d_f(s, v) = d_f(s, u) + 1 \text{ (why?)}$$



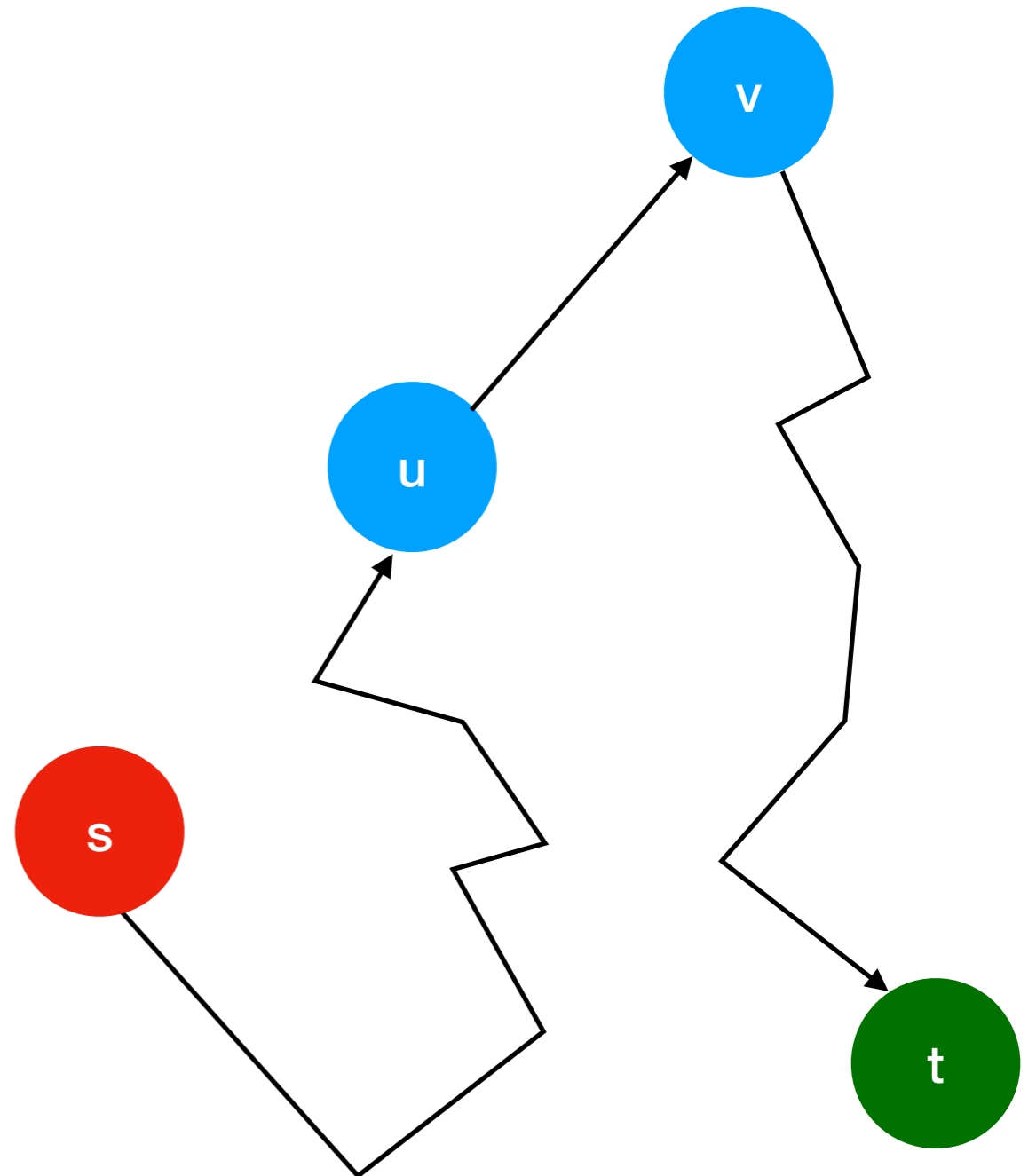
Edmonds-Karp Running Time

Let (u, v) be an edge.
Consider the first time it becomes **critical**, at which point the residual graph is G_f .

We have

$$d_f(s, v) = d_f(s, u) + 1 \text{ (why?)}$$

We now augment f to f' , and (u, v) disappears from $G_{f'}$.



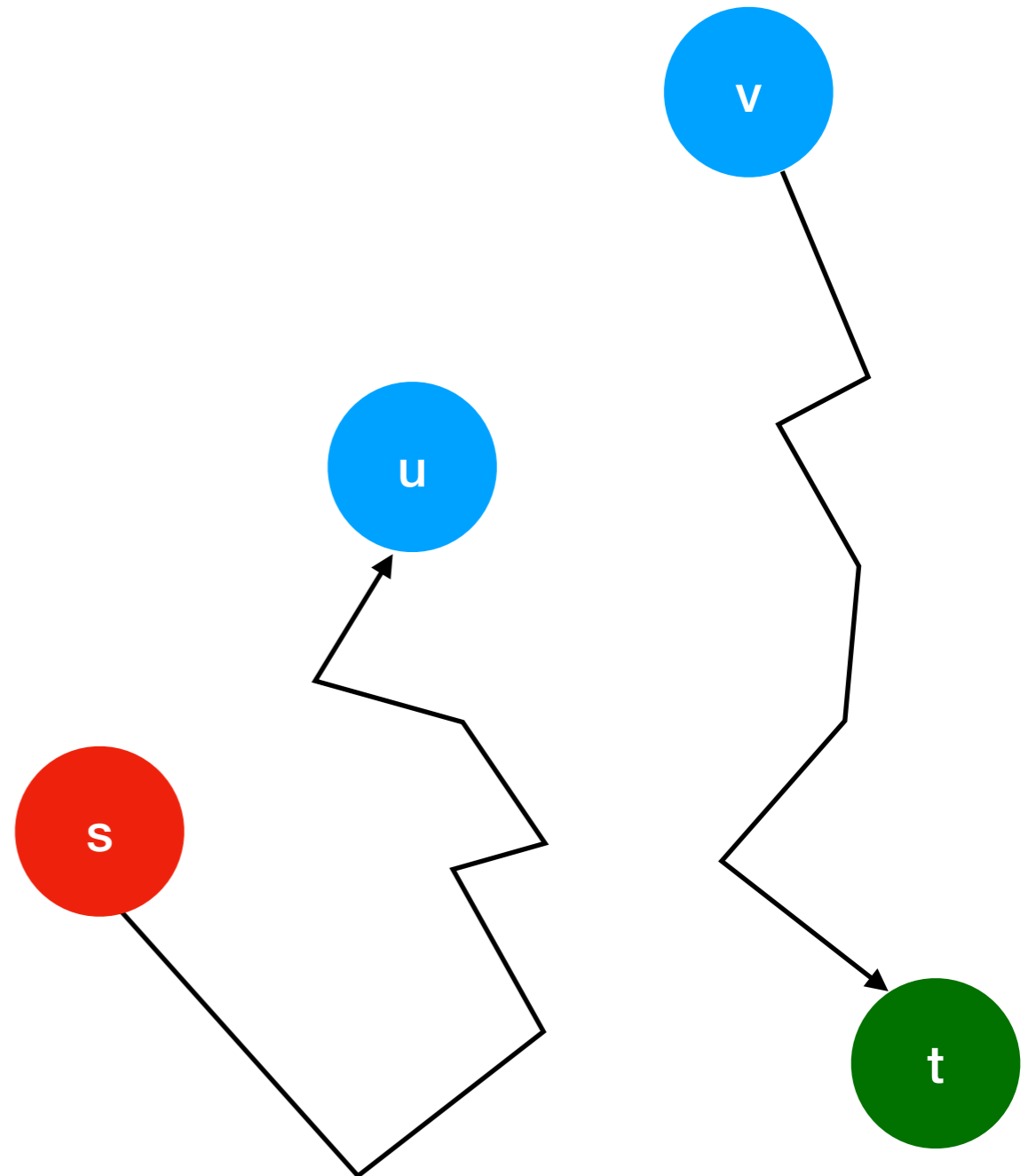
Edmonds-Karp Running Time

Let (u, v) be an edge.
Consider the first time it becomes **critical**, at which point the residual graph is G_f .

We have

$$d_f(s, v) = d_f(s, u) + 1 \text{ (why?)}$$

We now augment f to f' , and (u, v) disappears from $G_{f'}$.



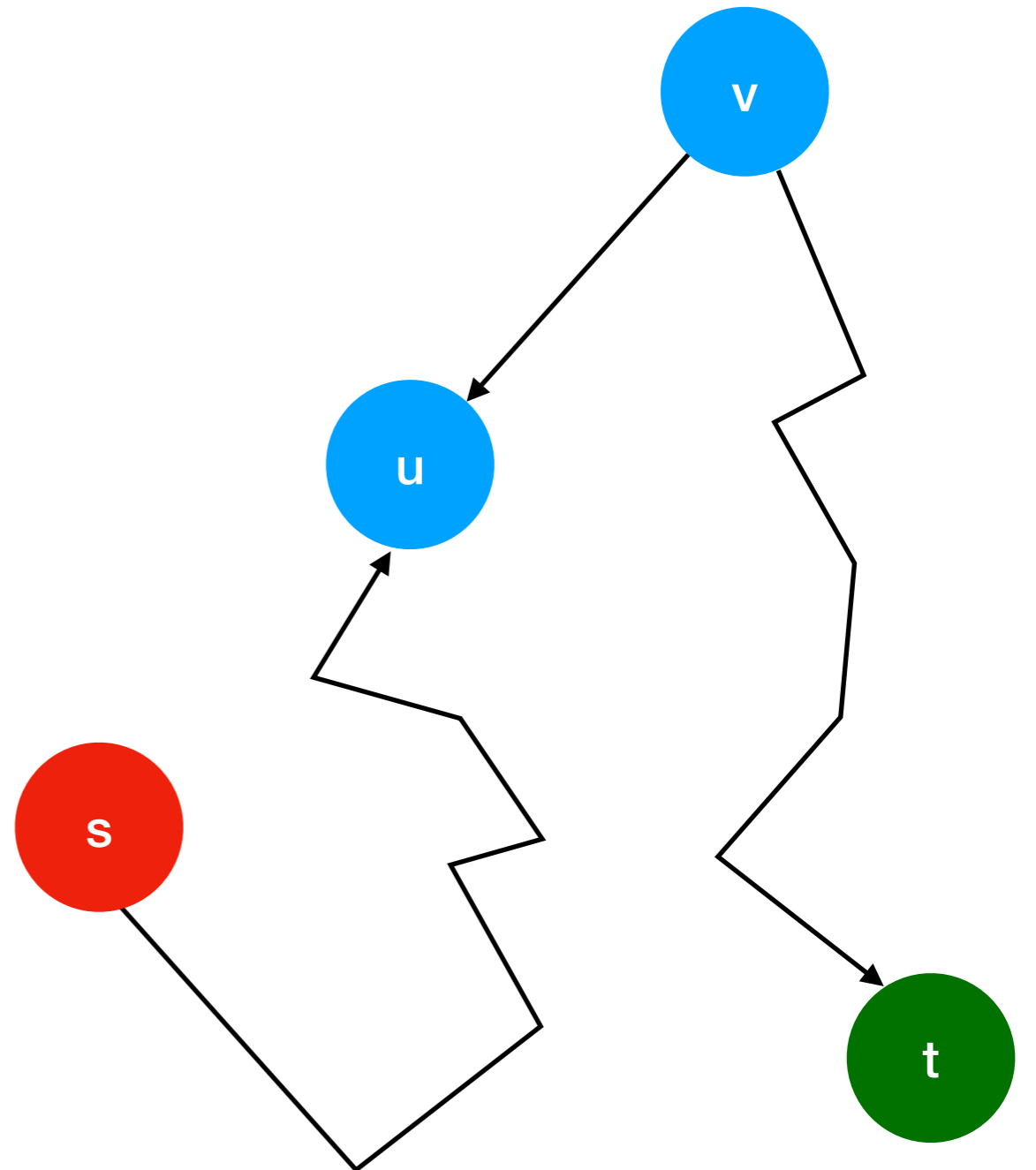
Edmonds-Karp Running Time

Let (u, v) be an edge.
Consider the first time it becomes **critical**, at which point the residual graph is G_f .

We have

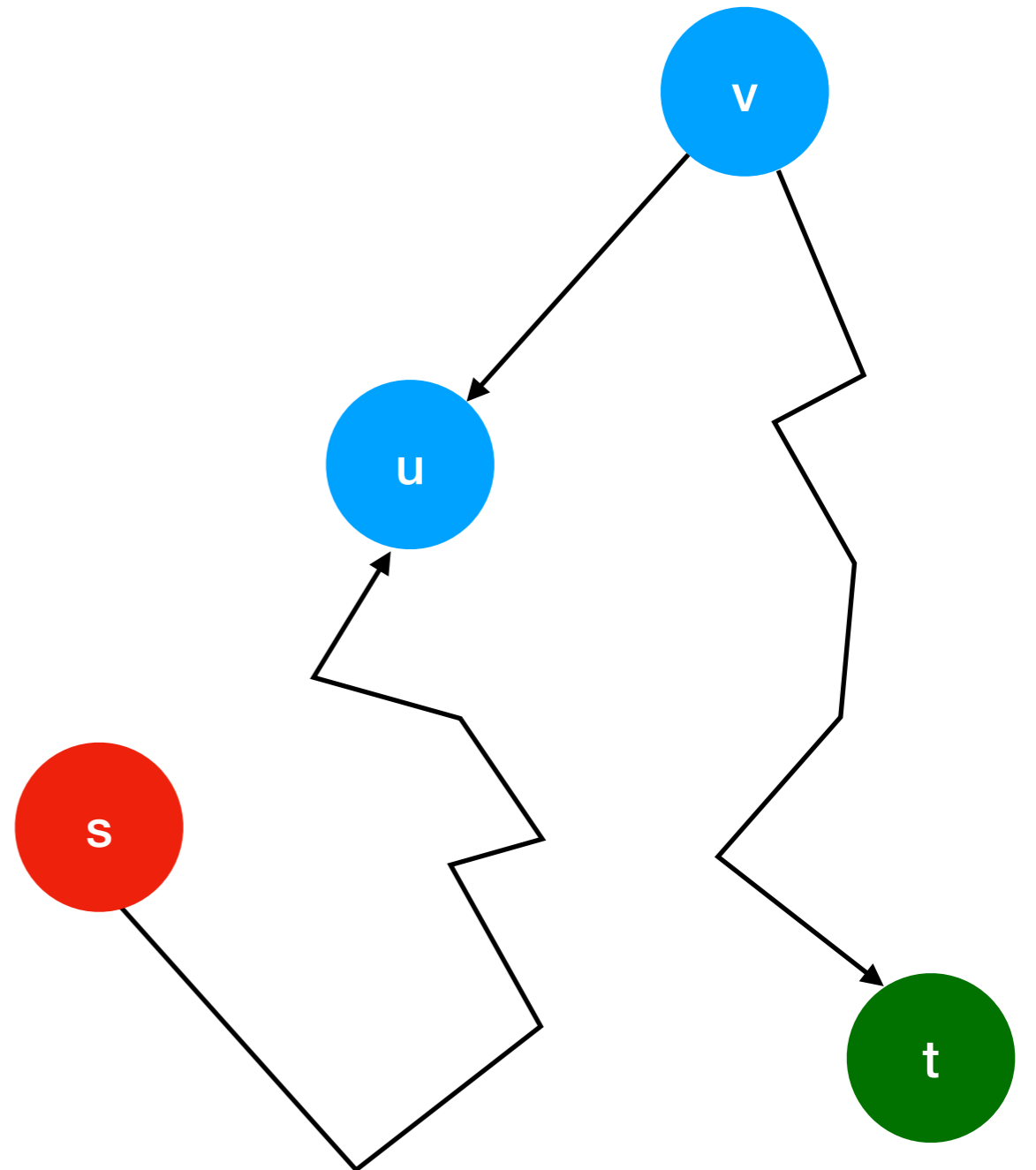
$$d_f(s, v) = d_f(s, u) + 1 \text{ (why?)}$$

We now augment f to f' , and (u, v) disappears from $G_{f'}$.



Edmonds-Karp Running Time

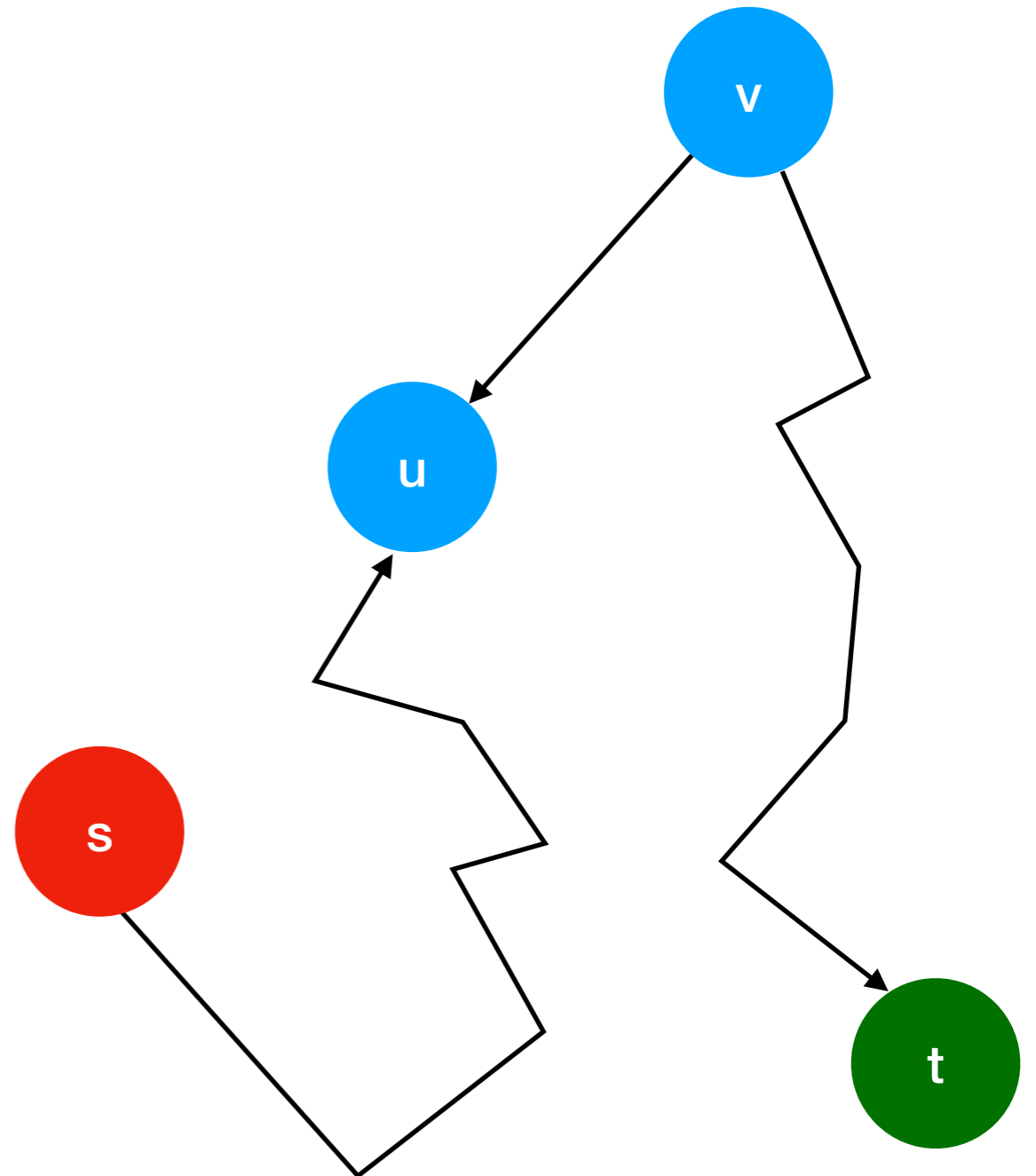
We now augment f to f' , and (u, v) disappears from $G_{f'}$.



Edmonds-Karp Running Time

We now augment f to f' , and (u, v) disappears from $G_{f'}$.

What needs to happen for it to reappear?

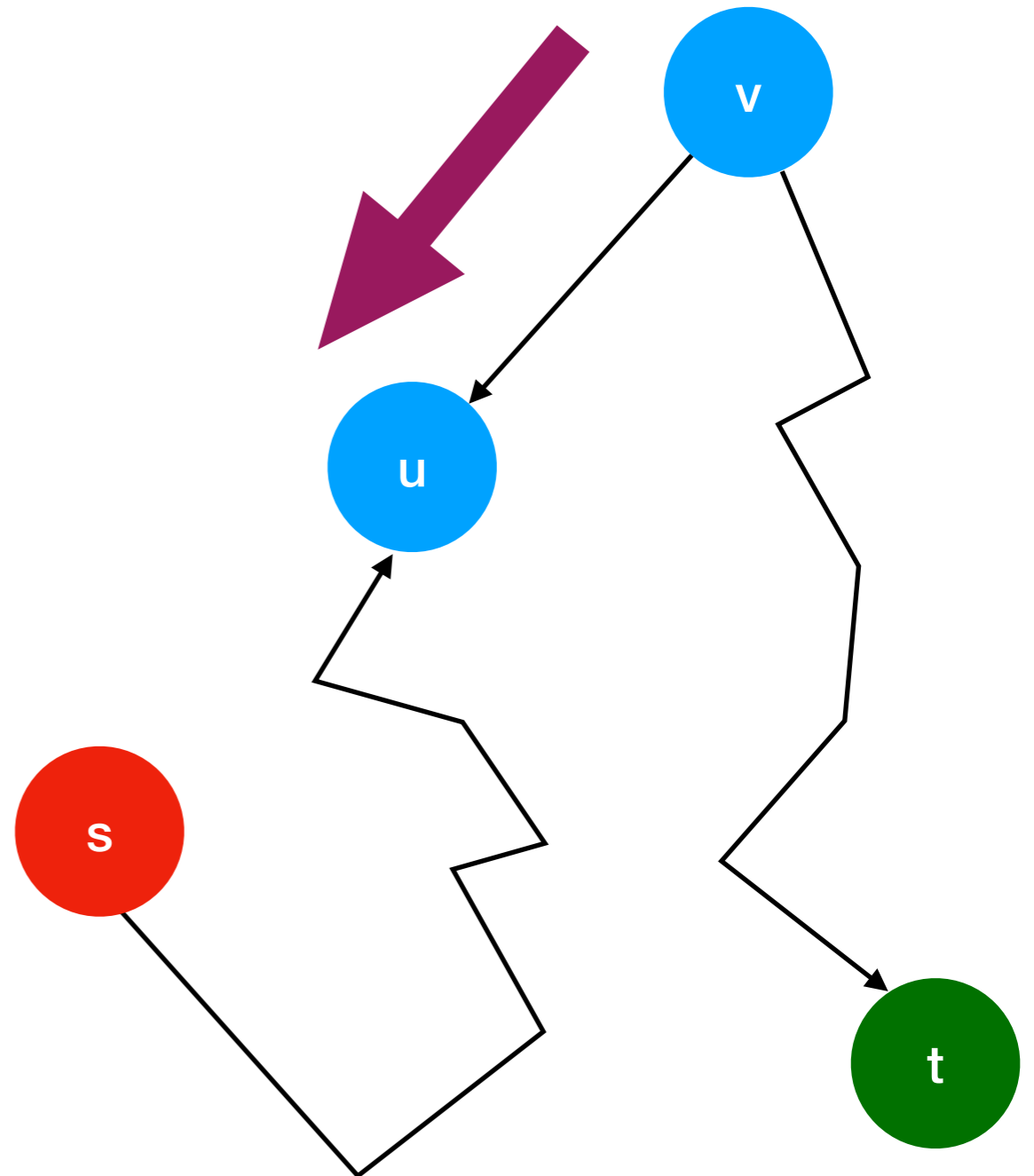


Edmonds-Karp Running Time

We now augment f to f' , and (u, v) disappears from $G_{f'}$.

What needs to happen for it to reappear?

We need to route flow from v to u .

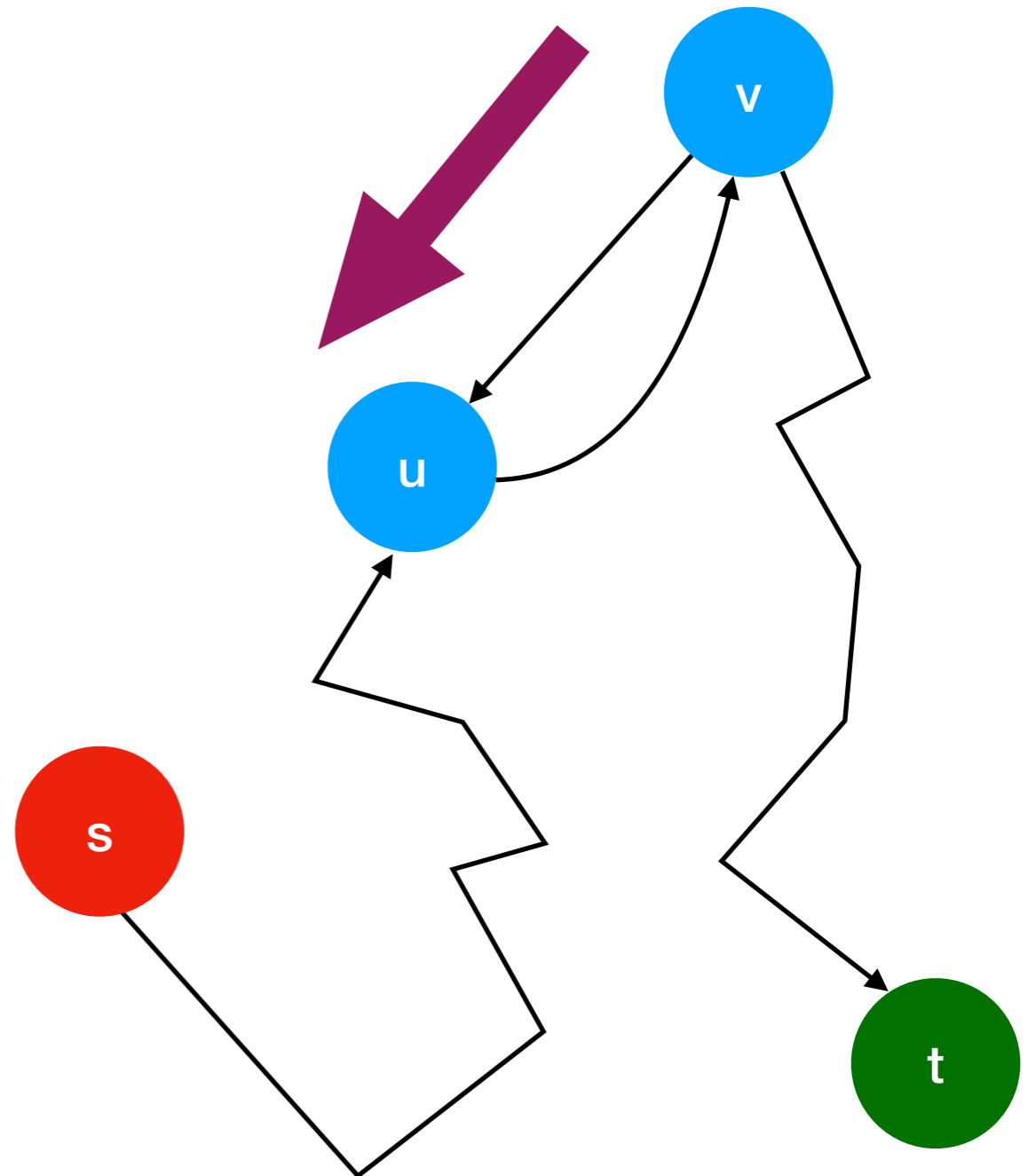


Edmonds-Karp Running Time

We now augment f to f' , and (u, v) disappears from $G_{f'}$.

What needs to happen for it to reappear?

We need to route flow from v to u .



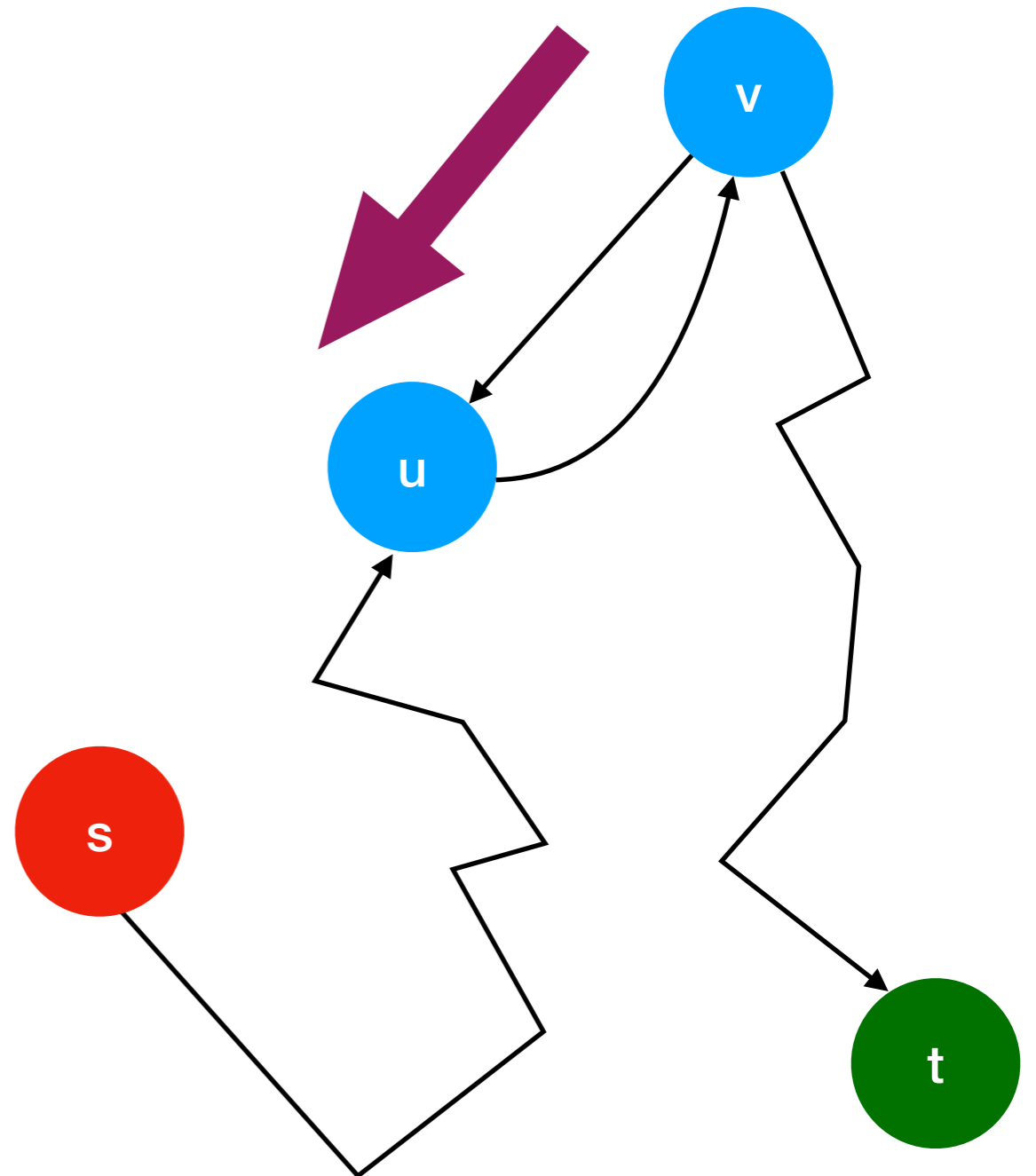
Edmonds-Karp Running Time

We now augment f to f' , and (u, v) disappears from $G_{f'}$.

What needs to happen for it to reappear?

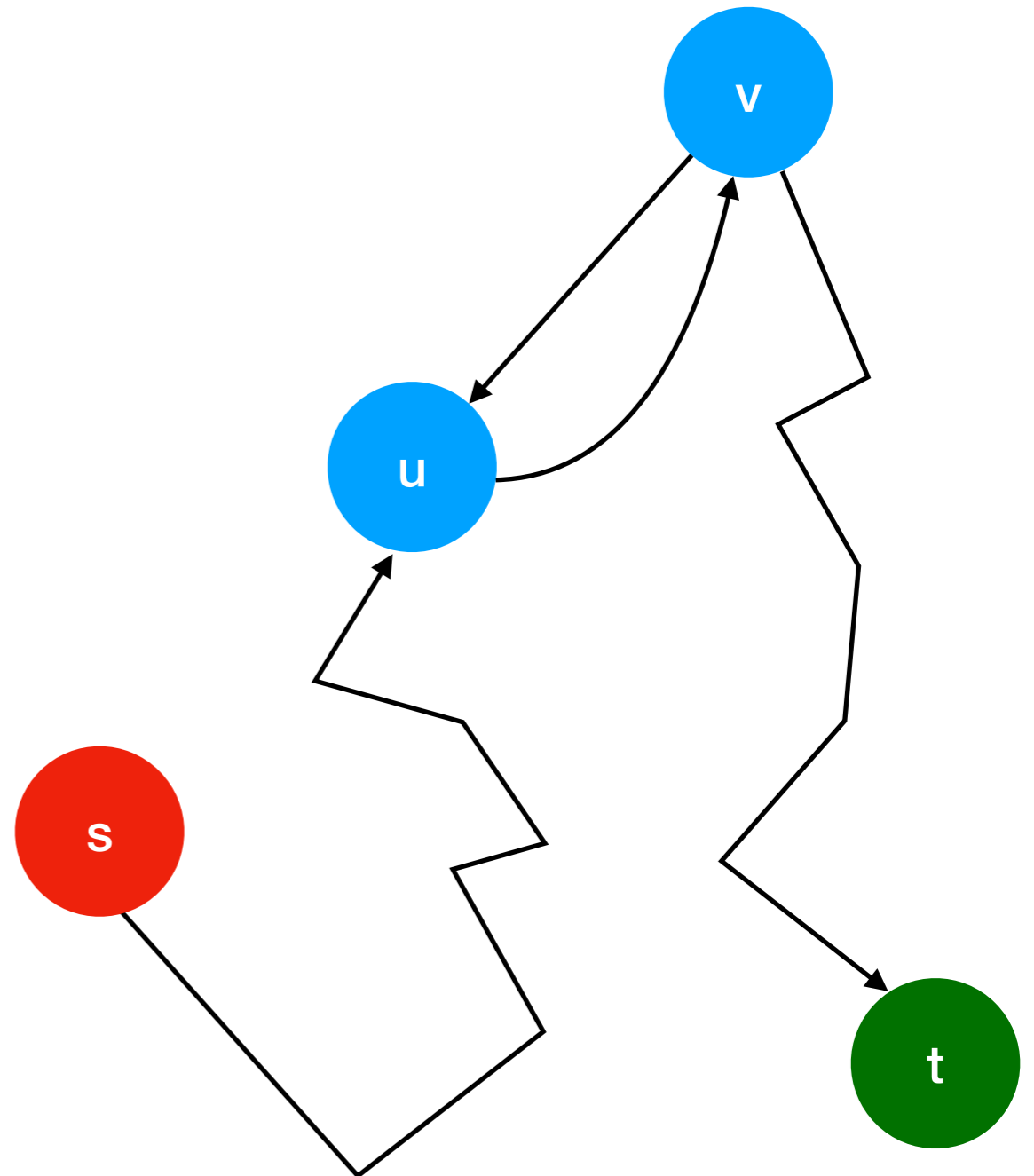
We need to route flow from v to u .

Let \hat{f} be the flow when this occurs, and $G_{\hat{f}}$ be the corresponding residual graph.



Edmonds-Karp Running Time

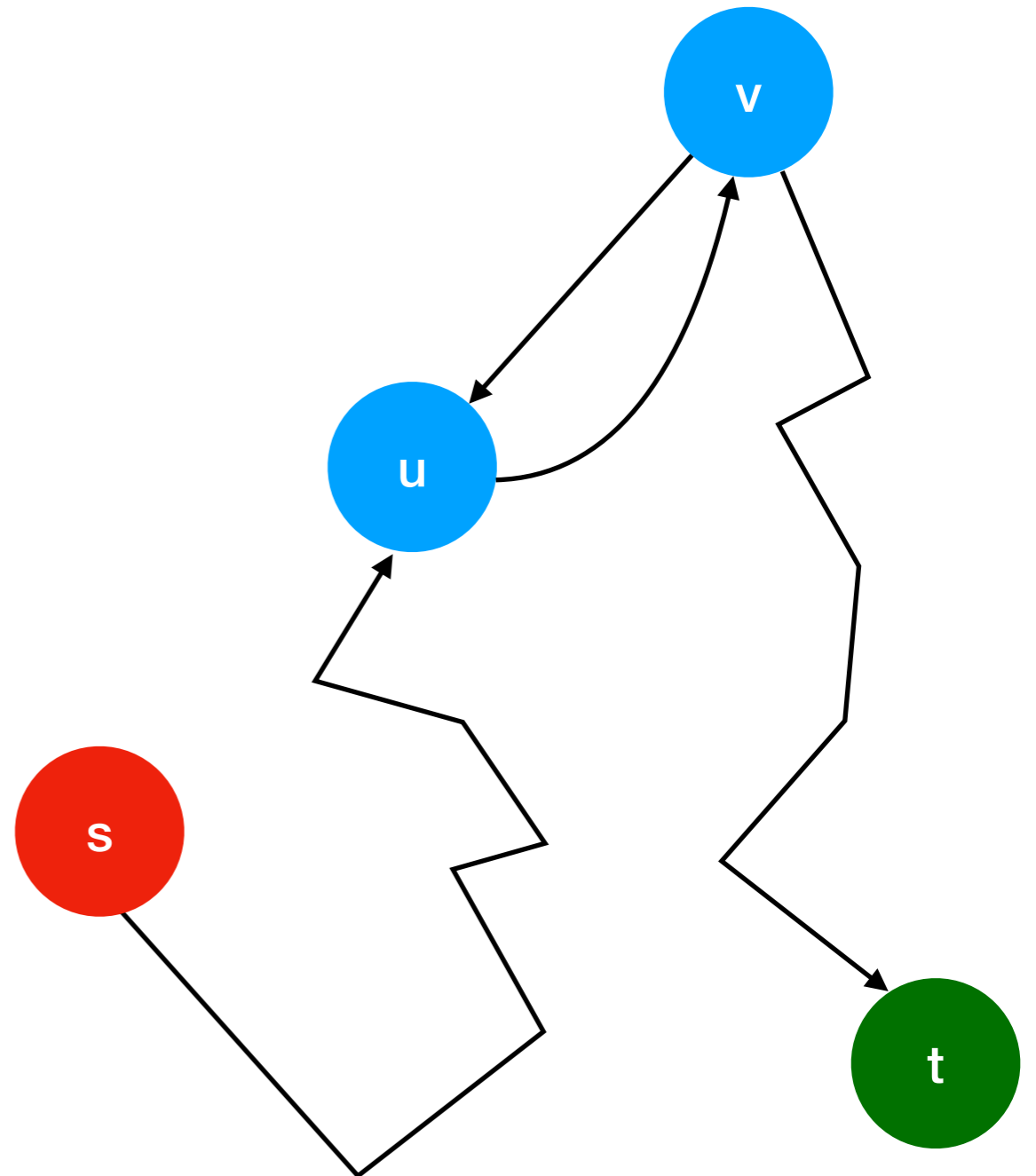
Let \hat{f} be the flow when this occurs,
and $G_{\hat{f}}$ be the corresponding residual
graph.



Edmonds-Karp Running Time

Let \hat{f} be the flow when this occurs,
and $G_{\hat{f}}$ be the corresponding residual
graph.

We have $d_{\hat{f}}(s, u) = d_{\hat{f}}(s, v) + 1$



Edmonds-Karp Running Time

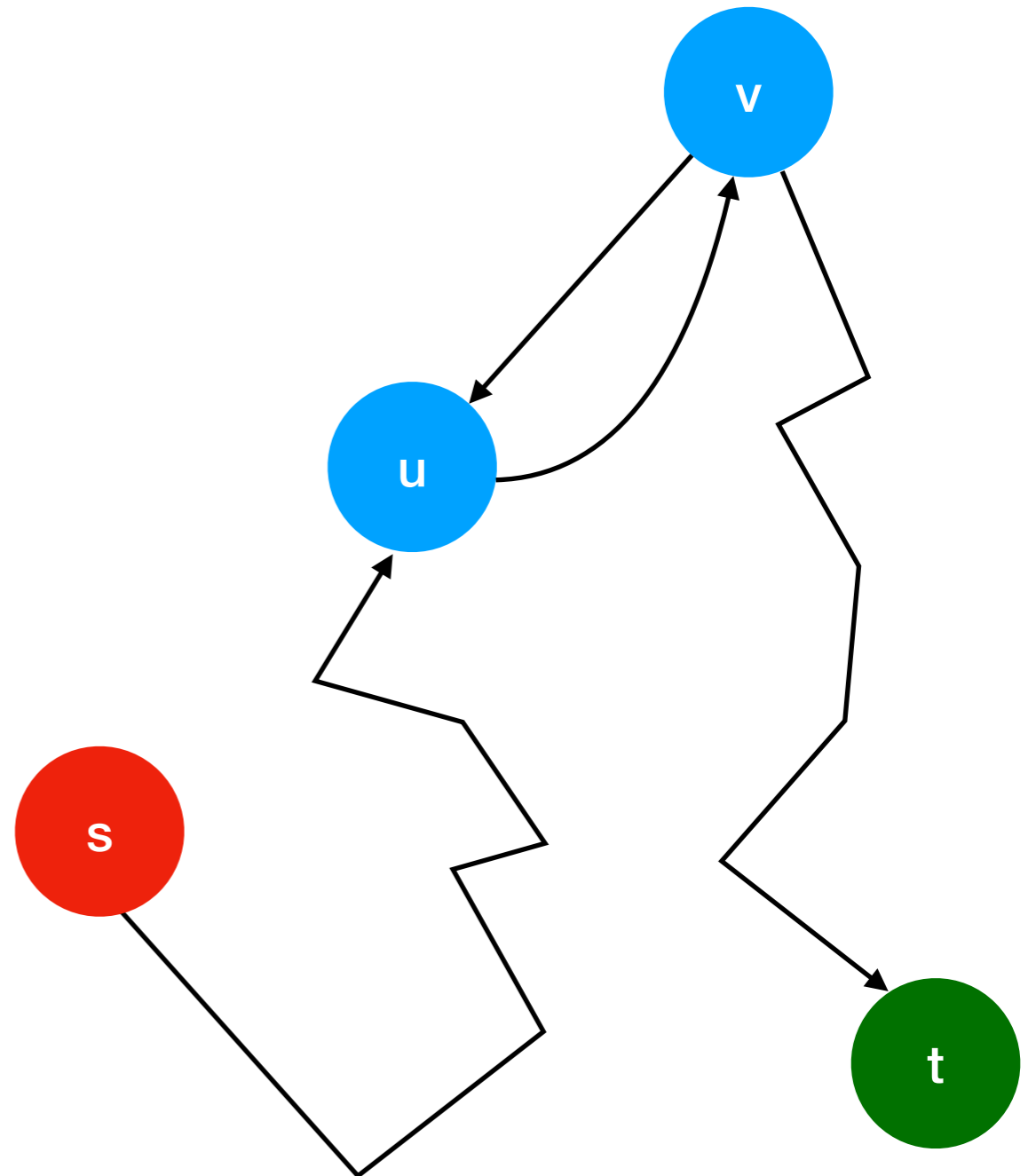
Let \hat{f} be the flow when this occurs,
and $G_{\hat{f}}$ be the corresponding residual
graph.

We have $d_{\hat{f}}(s, u) = d_{\hat{f}}(s, v) + 1$

By the lemma, we have

$$d_f(s, v) \leq d_{\hat{f}}(s, v)$$

(recall: f was the flow when (u, v)
became critical).



Edmonds-Karp Running Time

Let \hat{f} be the flow when this occurs,
and $G_{\hat{f}}$ be the corresponding residual
graph.

We have $d_{\hat{f}}(s, u) = d_{\hat{f}}(s, v) + 1$

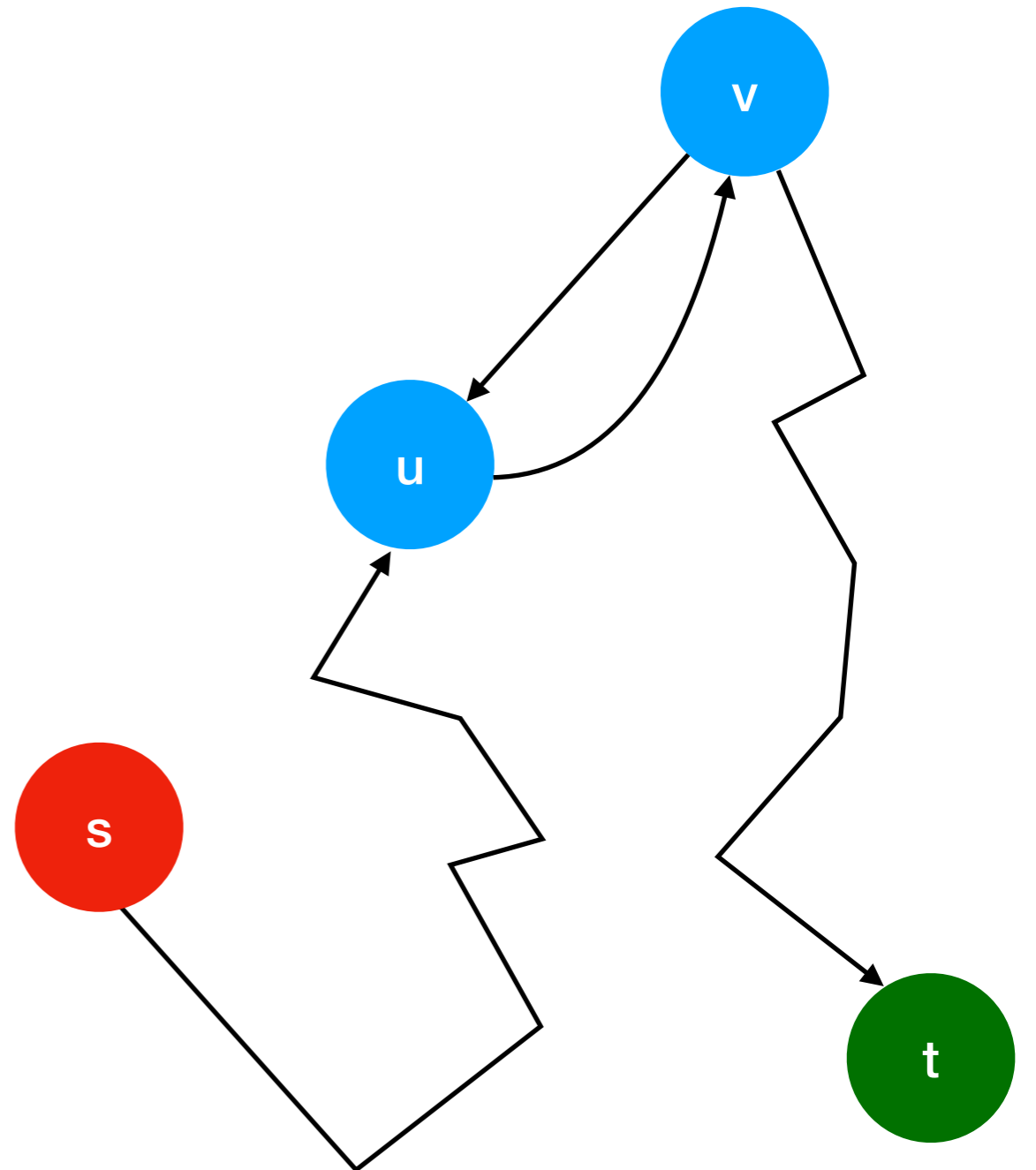
By the lemma, we have

$$d_f(s, v) \leq d_{\hat{f}}(s, v)$$

(recall: f was the flow when (u, v)
became critical).

Hence,

$$d_{\hat{f}}(s, u) \geq d_f(s, v) + 1 = d_f(s, u) + 2$$



Edmonds-Karp Running Time

By the lemma, we have $d_f(s, v) \leq d_{\hat{f}}(s, v)$

(recall: f was the flow when (u, v) became critical).

Hence, $d_{\hat{f}}(s, u) \geq d_f(s, v) + 1 = d_f(s, u) + 2$

Edmonds-Karp Running Time

By the lemma, we have $d_f(s, v) \leq d_{\hat{f}}(s, v)$

(recall: f was the flow when (u, v) became critical).

Hence, $d_{\hat{f}}(s, u) \geq d_f(s, v) + 1 = d_f(s, u) + 2$

Therefore, between two times when e becomes critical, the distance from s increased by at least 2.

Edmonds-Karp Running Time

By the lemma, we have $d_f(s, v) \leq d_{\hat{f}}(s, v)$

(recall: f was the flow when (u, v) became critical).

Hence, $d_{\hat{f}}(s, u) \geq d_f(s, v) + 1 = d_f(s, u) + 2$

Therefore, between two times when e becomes critical, the distance from s increased by at least 2.

In the shortest path from s to t there are at most $n - 1$ edges besides s .

Edmonds-Karp Running Time

By the lemma, we have $d_f(s, v) \leq d_{\hat{f}}(s, v)$

(recall: f was the flow when (u, v) became critical).

Hence, $d_{\hat{f}}(s, u) \geq d_f(s, v) + 1 = d_f(s, u) + 2$

Therefore, between two times when e becomes critical, the distance from s increased by at least 2.

In the shortest path from s to t there are at most $n - 1$ edges besides s .

So how many times can $e = (u, v)$ become critical?

Edmonds-Karp Running Time

By the lemma, we have $d_f(s, v) \leq d_{\hat{f}}(s, v)$

(recall: f was the flow when (u, v) became critical).

Hence, $d_{\hat{f}}(s, u) \geq d_f(s, v) + 1 = d_f(s, u) + 2$

Therefore, between two times when e becomes critical, the distance from s increased by at least 2.

In the shortest path from s to t there are at most $n - 1$ edges besides s .

So how many times can $e = (u, v)$ become critical?

At most $(n + 1)/2$ times.

Edmonds-Karp Running Time

So how many times can e become **critical**?

At most $(n + 1)/2$ times.

Edmonds-Karp Running Time

So how many times can e become **critical**?

At most $(n + 1)/2$ times.

How many edges in total?

Edmonds-Karp Running Time

So how many times can e become **critical**?

At most $(n + 1)/2$ times.

How many edges in total?

At most m .

Edmonds-Karp Running Time

So how many times can e become **critical**?

At most $(n + 1)/2$ times.

How many edges in total?

At most m .

Total number of critical edge occurrences?

Edmonds-Karp Running Time

So how many times can e become **critical**?

At most $(n + 1)/2$ times.

How many edges in total?

At most m .

Total number of critical edge occurrences?

$O(mn)$.

Edmonds-Karp Running Time

So how many times can e become **critical**?

At most $(n + 1)/2$ times.

How many edges in total?

At most m .

Total number of critical edge occurrences?

$O(mn)$.

How many flow augmentations?

Edmonds-Karp Running Time

So how many times can e become **critical**?

At most $(n + 1)/2$ times.

How many edges in total?

At most m .

Total number of critical edge occurrences?

$O(mn)$.

How many flow augmentations?

$O(mn)$.

Edmonds-Karp Running Time

How many flow augmentations?

Edmonds-Karp Running Time

How many flow augmentations?

$O(mn)$.

Edmonds-Karp Running Time

How many flow augmentations?

$O(mn)$.

How much time for each flow augmentation?

Edmonds-Karp Running Time

How many flow augmentations?

$O(mn)$.

How much time for each flow augmentation?

$O(m + n) = O(m)$.

Edmonds-Karp Running Time

How many flow augmentations?

$O(mn)$.

How much time for each flow augmentation?

$O(m + n) = O(m)$.

Total running time?

Edmonds-Karp Running Time

How many flow augmentations?

$$O(mn).$$

How much time for each flow augmentation?

$$O(m + n) = O(m).$$

Total running time?

$$O(nm^2).$$