Algorithmic Game Theory and Applications

(Approximate) Mechanism Design on Restricted Domains

The Gibbard-Satterthwaite Theorem

<u>Theorem (Gibbard 73 - Satterthwaite 75)</u>: In the unrestricted domain, when there are $m \ge 3$ candidates, a voting rule is truthful and onto if and only if it is dictatorial.

What if there are only 2 candidates?

If there are two candidates a and b, then for every voter $i \in N$, either $a \succ_i b$ or $b \succ_i a$.

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Majority is Threshold(1).

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<u>Proof</u>: A simple monotonicity argument: Assume a is the winner, and consider a voter i.

- If $a \succ_i b$, then *i* already has its top choice elected.
- If $b \succ_i a$, then if voter *i* misreports $a \succ'_i b$, *a* would still be elected, since it is still "above the threshold".

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By the GS Theorem, this voting rule cannot be truthful, as it is onto, but not a dictatorship.

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Caroll: $c \succ a \succ b$

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Bob could instead report: c > b > a

c would be the (Condorcet) winner.

Cardinal vs Ordinal (Randomised) Rules

In simple words: A cardinal voting rule is ordinal if it disregards the numbers and only keeps the information about the relative ranking between the candidates.
<u>Theorem (Gibbard 73 - Satterthwaite 75)</u>: In the unrestricted domain, when there are $m \ge 3$ candidates, an ordinal, deterministic voting rule is truthful and onto if and only if it is dictatorial.

 The GS Theorem still applies even if we look at cardinal rules. This is because every truthful cardinal rule has to be ordinal (tutorial).

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- The GS Theorem still applies even if we look at cardinal rules. This is because every truthful cardinal rule has to be ordinal (tutorial).
- The GS Theorem does <u>not</u> apply if we have randomised voting rules which are truthful-in-expectation. There are however some other theorems that apply (maybe tutorial).

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Unrestricted Domain

A social choice function, or <u>voting rule</u>, or mechanism is a function $f: (\succ)^n \to A$ mapping preference profiles to candidates,

where \succ^{n} is the space of all possible preference profiles.

<u>The unrestricted domain</u>: $>^{n}$ can contain any preference profile.

i.e., for any voter $i \in N$, \succ_i is the set of *all permutations* of $\{1, \ldots, m\}$.

Assume that we have a set of possible temperatures for the thermostat, e.g., $\{-10, -5, 0, 5, 10, 15, 20, 25, 30, 35, 40\}$.

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Introduced by Black in 1948, as a domain for which Condorcet winners always exist.

<u>Recall:</u> A Condorcet winner wins a pairwise majority election against any other candidate.

 $x_1 \quad x_2 \quad x_3$

 x_5

 X_4

 X_7

 x_6

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 x_4 is a Condorcet winner among the peaks.

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$$\begin{array}{rcl} \hline x_1 & x_2 & x_3 & \hline x_4 & x_5 & x_6 & x_7 \\ \hline x_4 \text{ is a Condorcet winner among the peaks.} & \mathsf{What else is } x_4? \end{array}$$

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Proof: Easy, we've seen it before.

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Proof: Virtually identical to before, check at home.

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e.g., "A voting rule is truthful and onto if and only if it is a k-th order statistic voter rule."

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We can also have any k-th ordered statistic among all the candidates.

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Theorem (Moulin 1980): A voting rule f is truthful, onto, and anonymous if and only if there exist $y_1, y_2, \ldots, y_{n-1}$ such that for all \succ , it holds that

 $f(\succ) = \text{med}\{p_1, p_2, ..., p_n, y_1, ..., y_{n-1}\}$

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There is also a characterisation without the anonymity property, which is slightly more complicated ("Generalised Median Voter Schemes").

Towards a characterisation

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If you are interested, check the AGT book Definition 10.3.

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In computer science, we usually aim to optimise some global objective, e.g., maximise the social welfare, or minimise the social cost.

Obviously we still want the voting rule to be robust to incentives, so we are still interested in truthfulness.

General Question: Among all the truthful voting rules, which one is the best with respect to the global objective?

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Refined Question: Among all the truthful voting rules, or, in this context, *mechanisms*, what is the one with the smallest possible approximation ratio?

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Example 2: Setting the temperature

The reports shown in the picture are the peaks, but any temperature is a possible outcome.



Single-Peaked Preferences

Assume that we have a set of possible temperatures for the thermostat, e.g., $\{-10, -5, 0, 5, 10, 15, 20, 25, 30, 35, 40\}$.

Let's say that your ideal temperature would be 20 degrees.

It is reasonable to assume that you would also prefer 25 degrees to 30 degrees, and likewise, 15 degrees to 10 degrees.

Generally, the "farther away" we move from your ideal temperature, the less happy you become.



Single-Peaked Preferences

How is the facility location setting different from this?

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Let's use the median voter rule for the TFL problem.

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x_2	Consider this example though.	$\frac{x_6}{x_7}$	
(x_4)	What is the maximum cost of x_4 ?		

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x_4	What is the maximum cost of x_4 ?	7	

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The mechanism is truthful for the same reason as before. What is the optimal location (the one that minimises the maximum cost)? How far can the median be from the optimal location?

It looks fairly close in the example!





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The approximation ratio of any k-th order statistic is exactly 2.



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 x_5 brings the facility closer to its true peak.



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It could be the case that x'_5 is the true peak and x_5 is the misreport. In that case the misreport would bring the facility exactly on the true peak.

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What is the ratio on this instance?

Truthful Facility Location, max cost objective

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Theorem (Procaccia and Tennenholtz 2010): The best possible approximation ratio achieved by any truthful mechanism for the maximum cost objective is 2. This is achieved by any k-th ordered statistic mechanism.