

### Advanced Database Systems Spring 2024

Lecture #20: Query Optimisation: Plan Space

R&G: Chapter 15

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# QUERY OPTIMISATION

The bridge between a **declarative** domain-specific language...

"What" you want as an answer

... and custom **imperative** computer programs "How" to compute the answer

A lot of effort has been spent on this problem! Huge optimisation problem Big impact on performance!



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### QUERY OPTIMISATION: THE GOAL

For a given query, find a <u>correct</u> execution plan that has the lowest "cost"

This is the part of a DBMS that is the hardest to implement well Proven to be NP-hard

No optimizer truly produces the "optimal" plan

Use estimation techniques to guess real plan cost

Use heuristics to limit the search space

At the very least, avoid really bad plans!

### QUERY OPTIMISATION STRATEGIES

We will focus on **IBM's System R** optimisers Invented in 1979 by Pat Selinger et al.

A lot of the concepts from System R's optimiser still used today in most DB systems

Other optimisation strategies

Volcano / Cascades (SQL Server, Greenplum) Stratified search (IBM DB2, Oracle) Randomised search (PostgreSQL) Al-driven optimisation



Notable differences, but similar big picture



## QUERY PARSER

Performs syntactic & semantic analysis

Builds internal representation of the input query SELECT-FROM-WHERE clauses translated into query blocks



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QUERY REWRITER

Two relational algebra expressions are **equivalent** if they generate the same set of tuples on any given database instance

The query rewriter applies heuristics & RA rules, without looking into the actual database state (no info about cardinalities, indices, etc.)

Separated from cost-based optimisation to reduce search space

Often only a few, very useful rules are applied

Typically too expensive to explore all possibilities

Rule-system often not confluent







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# QUERY OPTIMISATION: THE COMPONENTS Three (mostly) orthogonal concerns:

#### Plan space

For a given query, what plans are considered?

Larger the plan space, more likely to find a cheaper plan, but harder to search

#### Cost estimation

How is the cost of a plan estimated? Want to find the cheapest plan

#### Search strategy

How do we "search" in the "plan space"?

### **PLAN SPACE**

To generate a space of candidate plans, we need to think about how to rewrite relational algebra expressions into other ones

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Therefore, need a set of equivalence rules

Relational Algebra Eq	UIVALENCES	15
Selections		
$\boldsymbol{\sigma}_{c1 \land c2 \land \land cn}(R) \equiv \boldsymbol{\sigma}_{c1} \left( \boldsymbol{\sigma}_{c2} \left( \boldsymbol{\sigma}_{cn}(R) \right) \right)$	(cascade)	
$\boldsymbol{\sigma}_{c1}(\boldsymbol{\sigma}_{c2}(R)) \equiv \boldsymbol{\sigma}_{c2}(\boldsymbol{\sigma}_{c1}(R))$	(commute)	
Projections		
$\pi_{a1}((R)) \equiv \pi_{a1}((\pi_{a1,,an-1}(R)))$	(cascade)	
Essentially, allows partial projection earlier in the expression As long as we're keeping a1 (and everything else we need outside) we're OK		

#### **R**ELATIONAL **A**LGEBRA **E**QUIVALENCES Selections $\mathbf{\sigma}_{c1 \land c2 \land ... \land cn}(R) \equiv \mathbf{\sigma}_{c1} \left( \mathbf{\sigma}_{c2} \left( ... \mathbf{\sigma}_{cn}(R) \right) \right)$ (cascade) $\sigma_{c1}(\sigma_{c2}(R)) \equiv \sigma_{c2}(\sigma_{c1}(R))$ (commute) Projections $\pi_{a1}(...(R)...) \equiv \pi_{a1}(...(\pi_{a1,...,an-1}(R))...)$ (cascade) Cartesian products $R \times (S \times T) \equiv (R \times S) \times T$ (associative) $R \times S \equiv S \times R$ (commutative) Recall that the ordering of attributes doesn't matter

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## ARE JOINS ASSOCIATIVE AND COMMUTATIVE?

Not legal!

The same!

(join on A not allowed)

Not the same! (no condition on A)

After all, just Cartesian products with selections

You can think of them as associative and commutative ... but beware of joins turning into cross-products!

Consider R(A,Y), S(A,B), T(B,Z)

Attempt 1: (S  $\bowtie_{S,B=T,B}$  T)  $\bowtie_{S,A=R,A}$  R  $\neq$  S  $\bowtie_{S,B=T,B}$  (T  $\bowtie_{S,A=R,A}$  R)

Attempt 2: (S  $\bowtie_{S,B=T,B}$  T)  $\bowtie_{S,A=R,A}$  R  $\neq$  S  $\bowtie_{S,B=T,B}$  (T x R)

Attempt 3: (S  $\bowtie_{S,B=T,B}$  T)  $\bowtie_{S,A=R,A}$  R  $\equiv$  S  $\bowtie_{S,B=T,B \land S,A=R,A}$  (T x R)

### JOIN ORDERING

Similarly, note that some join orders have cross products, some don't

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SELECT \* FROM R, S, T

Equivalent for the query on the right:



### INTRODUCING ADDITIONAL JOIN CONDITIONS

Implicit join through transitivity...

SELECT \* FROM R, S, T WHERE R.A = S.B AND S.B = T.C

... can be turned into

SELECT \* FROM R, S, T WHERE R.A = S.B AND S.B = T.C AND R.A = T.C

... making the join ordering (**R**  $\bowtie$  **T**)  $\bowtie$  **S** possible (avoids a Cartesian product)

## PLAN SPACE

To generate a space of candidate plans, we need to think about how to rewrite relational algebra expressions into other ones

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Therefore, need a set of **equivalence rules – done** 

Need heuristics to restrict attention to plans that are mostly better We have already seen one of these in the relational algebra lecture

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**COMMON HEURISTICS: SELECTIONS** 

Filter as early as possible

Reorder predicates so that the DBMS applies the most selective one first

Break complex predicates and push down

 $\boldsymbol{\sigma}_{c1 \wedge c2 \wedge ... \wedge cn} \left( \mathsf{R} \right) = \boldsymbol{\sigma}_{c1} \left( \boldsymbol{\sigma}_{c2} \left( ... \boldsymbol{\sigma}_{cn} \left( \mathsf{R} \right) \right) \right)$ 

#### Simplify complex predicates

 $X = Y AND Y = 3 \implies X = 3 AND Y = 3$ 

 $\text{L.TAX} * 100 < 5 \ \Rightarrow \ \text{L.TAX} < 0.05$ 



### **COMMON HEURISTICS: PROJECTIONS**

**Perform** them early to create smaller tuples and reduce intermediate results (if duplicates are eliminated)

**Project out** all attributes except the ones requested or required (e.g., joining keys)

This is not important for column stores...

# HEURISTICS: PROJECTION PUSHDOWN

Keep only the columns you need to evaluate downstream operators

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Other rewritings exist! (reorder selection and projection)

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## **COMMON HEURISTICS**

Avoid Cartesian products

Given a choice, do theta-joins rather than cross-products Consider R(A, B), S(B, C), T(C, D) Favour (R  $\bowtie$  S)  $\bowtie$  T over (R x T)  $\bowtie$  S



Case where this doesn't quite improve things: If R x T is small (e.g., R & T are very small and S is relatively large) Still it's a good enough heuristic that we will use it

### PLAN SPACE

To generate a space of candidate plans, we need to think about how to rewrite relational algebra expressions into other ones

Therefore, need a set of **equivalence rules – done** 

Need heuristics to restrict attention to plans that are mostly better - done

Both of these were logical equivalences, need also physical equivalences

# PHYSICAL EQUIVALENCES

#### Base table access

Heap scan

Index scan (if available on referenced columns)

#### Equijoins

Block Nested Loops: simple, exploits extra memory Index Nested Loops: often good if 1 table is small and the other indexed properly Sort-Merge Join: good with small memory, equal-size tables Grace Hash Join: even better than sort with 1 small table

#### Non-Equijoins

Block Nested Loops

### SUMMARY

#### There are lots of plans

Even for a relatively simple query

Manual query planning can be tedious, technical Machines are better at enumerating options than people

#### Query rewriting

DBMSs can identify better query plans even without a cost model Filtering as early as possible is usually a good choice

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