

# THE UNIVERSITY of EDINBURGH

# Advanced Database Systems Spring 2024

### Lecture #20: Query Optimisation: Plan Space

R&G: Chapter 15

## **QUERY OPTIMISATION**

The bridge between a **declarative** domain-specific language...

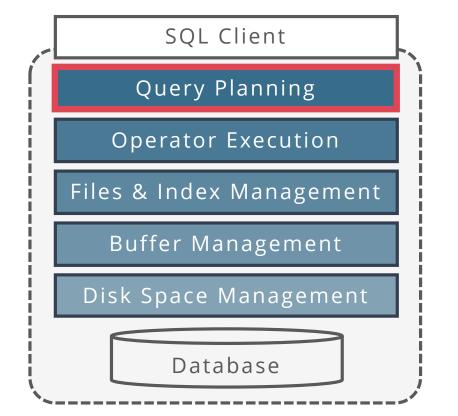
"What" you want as an answer

... and custom **imperative** computer programs "How" to compute the answer

A lot of effort has been spent on this problem!

Huge optimisation problem

Big impact on performance!



### QUERY OPTIMISATION: THE GOAL

For a given query, find a <u>correct</u> execution plan that has the lowest "cost"

This is the part of a DBMS that is the hardest to implement well Proven to be NP-hard

No optimizer truly produces the "optimal" plan

Use estimation techniques to guess real plan cost

Use heuristics to limit the search space

At the very least, avoid really bad plans!

# **QUERY OPTIMISATION STRATEGIES**

We will focus on **IBM's System R** optimisers

Invented in 1979 by Pat Selinger et al.

A lot of the concepts from System R's optimiser still used today in most DB systems

Other optimisation strategies

Volcano / Cascades (SQL Server, Greenplum)

Stratified search (IBM DB2, Oracle)

Randomised search (PostgreSQL)

Al-driven optimisation

Access Path Selection in a Relational Database Management System

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ABSTRACT: In a high level query and data manipulation language such as SQL, requests stated non-procedurally, without reference to access paths. This paper describes how System R chooses access paths for both simple (single relation) and complex queries (such as joins), given a user specification of desired data as a boolean expression of predicates. System R is an experimental database management system developed to carry out research on the relational model of data. System R was designed and built by members of the IBM San Jose Research Laboratory.

retrieval. Nor does a user specify in what order joins are to be performed. The System R optimizer chooses both join order and an access path for each table in the SQL statement. Of the many possible choicer, the optimizer chooses the one which minimizes "total access cost" for performing the entire statement.

This paper will address the issues of access path selection for queries. Retrieval for data manipulation (UPDATE, DELETE) is treated similarly. Section 2 uill describe the place of the estimizer in

Notable differences, but similar big picture



# QUERY LIFECYCLE

#### SQL Parser

Checks correctness, authorisation

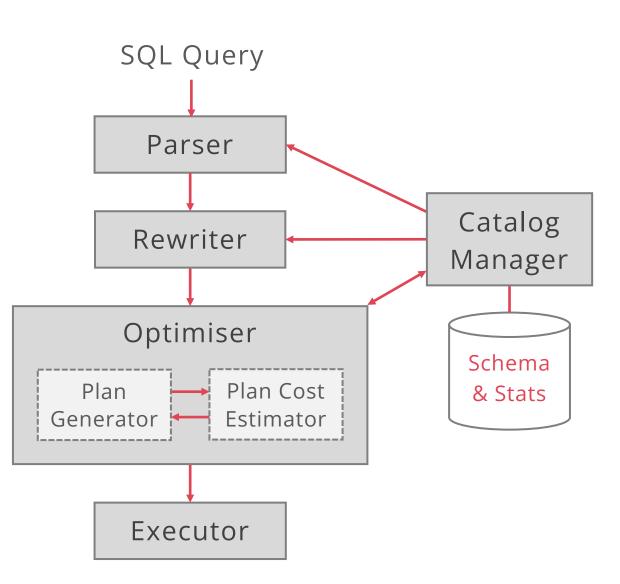
Generates a parse tree

#### Heuristics/rule-based rewriting

Remove stupid / inefficient things Apply equivalence rules of RA

#### **Cost-based optimisation**

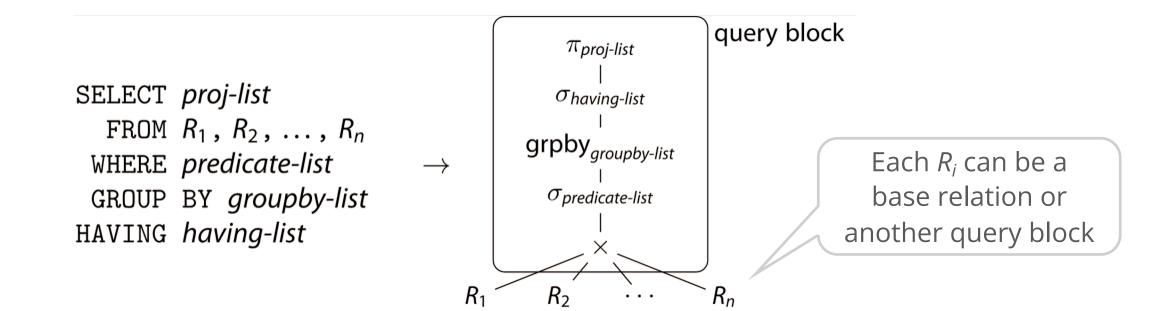
Enumerate multiple equivalent plans Using a **cost model** pick the cheapest plan



### QUERY PARSER

Performs syntactic & semantic analysis

Builds internal representation of the input query SELECT-FROM-WHERE clauses translated into **query blocks** 



## QUERY REWRITER

Two relational algebra expressions are **equivalent** if they generate the same set of tuples on any given database instance

The query rewriter applies heuristics & RA rules, without looking into the actual database state (no info about cardinalities, indices, etc.)

Separated from cost-based optimisation to reduce search space

Often only a few, very useful rules are applied

- Typically too expensive to explore all possibilities
- Rule-system often not confluent

## SOME SIMPLIFICATIONS

CREATE TABLE R (
 id INT PRIMARY KEY,
 val INT NOT NULL )

Impossible / unnecessary predicates

**SELECT** \* **FROM** R WHERE 1 = 0

**SELECT** \* **FROM** R WHERE 1 = 1





Join elimination

SELECT R1.\*
FROM R AS R1 JOIN R AS R2
ON R1.id = R2.id



SELECT \* FROM R

## MORE SIMPLIFICATIONS

CREATE TABLE R (
 id INT PRIMARY KEY,
 val INT NOT NULL )

Ignoring nested subquery

```
SELECT * FROM R AS R1
WHERE EXISTS (SELECT * FROM R AS R2
WHERE R1.id = R2.id);
```



**SELECT** \* **FROM** R

Merging predicates

SELECT \* FROM R
WHERE val BETWEEN 1 AND 100
OR val BETWEEN 50 AND 150



SELECT \* FROM R WHERE val BETWEEN 1 AND 150

# QUERY OPTIMISER

Optimises one query block at a time

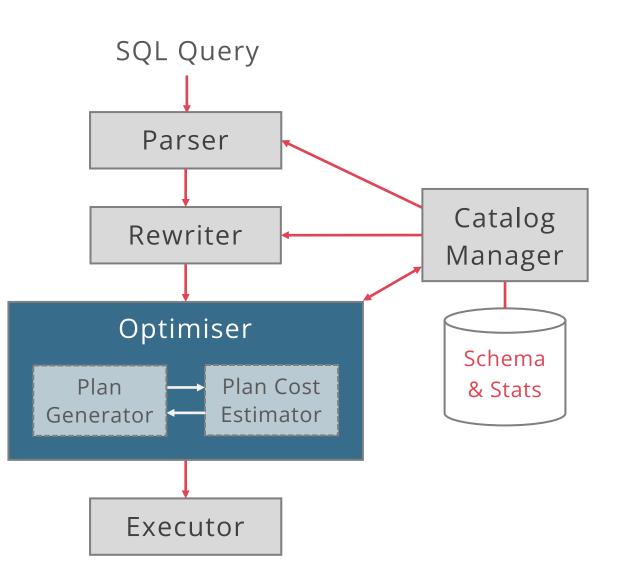
#### Enumerates all possible plans

If this yields too many plans, at least enumerate "promising" plan candidates

Determines the **cost** of each plan

... using a cost model and catalog statistics

Chooses the **best** plan per query block Often not truly "optimal"



# QUERY OPTIMISATION: THE COMPONENTS

#### Three (mostly) orthogonal concerns:

#### **Plan space**

For a given query, what plans are considered?

Larger the plan space, more likely to find a cheaper plan, but harder to search

#### **Cost estimation**

How is the cost of a plan estimated?

Want to find the cheapest plan

#### Search strategy

How do we "search" in the "plan space"?

### PLAN SPACE

To generate a space of candidate plans, we need to think about how to rewrite relational algebra expressions into other ones

Therefore, need a set of **equivalence rules** 

## Relational Algebra Equivalences

Selections

 $\sigma_{c1 \land c2 \land ... \land cn}(R) \equiv \sigma_{c1} (\sigma_{c2} (... \sigma_{cn}(R)))$ (cascade)  $\sigma_{c1} (\sigma_{c2}(R)) \equiv \sigma_{c2} (\sigma_{c1}(R))$ (commute)

Projections

 $\pi_{a1}(...(R)...) \equiv \pi_{a1}(...(\pi_{a1,...,an-1}(R))...)$ 

(cascade)

Essentially, allows partial projection earlier in the expression

As long as we're keeping a1 (and everything else we need outside) we're OK

# **Relational Algebra Equivalences**

#### Selections

 $\sigma_{c1 \land c2 \land ... \land cn}(R) \equiv \sigma_{c1} (\sigma_{c2} (... \sigma_{cn}(R))) \qquad (cascade)$   $\sigma_{c1} (\sigma_{c2}(R)) \equiv \sigma_{c2} (\sigma_{c1}(R)) \qquad (commute)$ Projections  $\pi_{a1} (... (R) ...) \equiv \pi_{a1} (... (\pi_{a1, ..., an-1} (R)) ... ) \qquad (cascade)$ Cartesian products  $R \times (S \times T) \equiv (R \times S) \times T \qquad (associative)$ 

 $\mathsf{R} \mathbf{x} \mathsf{S} \equiv \mathsf{S} \mathbf{x} \mathsf{R}$ 

Recall that the ordering of attributes doesn't matter

(associative) (commutative)

# ARE JOINS ASSOCIATIVE AND COMMUTATIVE?

After all, just Cartesian products with selections

You can think of them as associative and commutative ... but beware of joins turning into cross-products!

Consider R(A,Y), S(A,B), T(B,Z)

Attempt 1: (S  $\bowtie_{S,B=T,B}$  T)  $\bowtie_{S,A=R,A}$  R  $\neq$  S  $\bowtie_{S,B=T,B}$  (T  $\bowtie_{S,A=R,A}$  R)

Attempt 2: (S  $\bowtie_{S,B=T,B}$  T)  $\bowtie_{S,A=R,A}$  R  $\neq$  S  $\bowtie_{S,B=T,B}$  (T x R)

Attempt 3: (S  $\bowtie_{S,B=T,B}$  T)  $\bowtie_{S,A=R,A}$  R  $\equiv$  S  $\bowtie_{S,B=T,B \land S,A=R,A}$  (T x R)

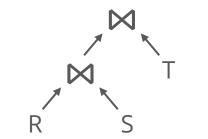
Not legal! (join on A not allowed) Not the same! (no condition on A)

The same!

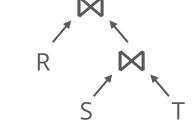
# JOIN ORDERING

Similarly, note that some join orders have cross products, some don't

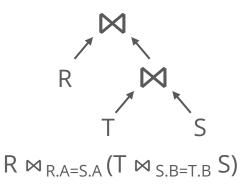
Equivalent for the query on the right:

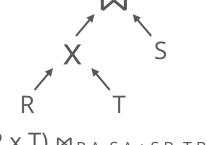


 $(\mathsf{R} \bowtie_{\mathsf{R}.\mathsf{A}=\mathsf{S}.\mathsf{A}}\mathsf{S}) \bowtie_{\mathsf{S}.\mathsf{B}=\mathsf{T}.\mathsf{B}}\mathsf{T}$ 



 $R \bowtie_{R,A=S,A} (S \bowtie_{S,B=T,B} T)$ 





(R x T	) Þ	⊲ <sub>R.A=S.A∧S.B=T.B</sub> S	)
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SELECT	*
FROM	R, S, T
WHERE	R.A = S.A
AND	S.B = T.B

### INTRODUCING ADDITIONAL JOIN CONDITIONS

Implicit join through transitivity...

SELECT \* FROM R, S, T WHERE R.A = S.B AND S.B = T.C

... can be turned into

SELECT \* FROM R, S, T WHERE R.A = S.B AND S.B = T.C AND R.A = T.C

... making the join ordering (R 🛛 T) 🖂 S possible (avoids a Cartesian product)

### PLAN SPACE

To generate a space of candidate plans, we need to think about how to rewrite relational algebra expressions into other ones

Therefore, need a set of **equivalence rules – done** 

Need **heuristics** to restrict attention to plans that are mostly better

We have already seen one of these in the relational algebra lecture

### **COMMON HEURISTICS: SELECTIONS**

Filter as early as possible

**Reorder** predicates so that the DBMS applies the most selective one first

Break complex predicates and push down

 $\boldsymbol{\sigma}_{c1 \wedge c2 \wedge ... \wedge cn} \left( \mathsf{R} \right) = \boldsymbol{\sigma}_{c1} \left( \boldsymbol{\sigma}_{c2} \left( \dots \boldsymbol{\sigma}_{cn} \left( \mathsf{R} \right) \right) \right)$ 

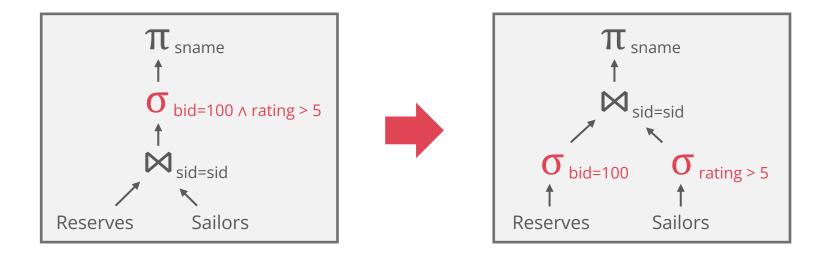
Simplify complex predicates

 $X = Y AND Y = 3 \implies X = 3 AND Y = 3$ 

L.TAX \* 100 < 5  $\Rightarrow$  L.TAX < 0.05

### HEURISTICS: SELECTION PUSHDOWN

Apply selections as soon as you have the relevant columns



#### Why is this an improvement?

Selection is essentially free, joins are expensive

Side effect is that the intermediate inputs to joins are smaller

### **COMMON HEURISTICS: PROJECTIONS**

**Perform** them early to create smaller tuples and reduce intermediate results (if duplicates are eliminated)

**Project out** all attributes except the ones requested or required (e.g., joining keys)

This is not important for column stores...

### HEURISTICS: PROJECTION PUSHDOWN

Keep only the columns you need to evaluate downstream operators



Other rewritings exist! (reorder selection and projection)

### **COMMON HEURISTICS**

#### Avoid Cartesian products

Given a choice, do theta-joins rather than cross-products

Consider R(A, B), S(B, C), T(C, D)

Favour ( $R \bowtie S$ )  $\bowtie T$  over ( $R \ge T$ )  $\bowtie S$ 



Case where this doesn't quite improve things:

If R x T is small (e.g., R & T are very small and S is relatively large) Still it's a good enough heuristic that we will use it

### PLAN SPACE

To generate a space of candidate plans, we need to think about how to rewrite relational algebra expressions into other ones

Therefore, need a set of **equivalence rules – done** 

Need **heuristics** to restrict attention to plans that are mostly better – **done** 

Both of these were logical equivalences, need also physical equivalences

### Physical Equivalences

#### Base table access

Heap scan

Index scan (if available on referenced columns)

#### Equijoins

Block Nested Loops: simple, exploits extra memory

Index Nested Loops: often good if 1 table is small and the other indexed properly

Sort-Merge Join: good with small memory, equal-size tables

Grace Hash Join: even better than sort with 1 small table

#### Non-Equijoins

Block Nested Loops

### SUMMARY

#### There are lots of plans

- Even for a relatively simple query
- Manual query planning can be tedious, technical
- Machines are better at enumerating options than people

#### Query rewriting

DBMSs can identify better query plans even without a cost model Filtering as early as possible is usually a good choice