Advanced Database Systems (ADBS), University of Edinburgh, 2024/25

# **Conjunctive Queries: Fast Evaluation**

(Chapter 18 of DBT)

#### **Complexity of Query Evaluation**

Theorem: CQ-Evaluation is NP-complete and in PTIME in data complexity

#### **Proof:**

(NP-membership) Guess-and-check:

- Consider a database D, a CQ  $Q(x_1,...,x_k)$ :- body, and a tuple  $(a_1,...,a_k)$  of values
- Guess a substitution h : terms(body) → terms(D)
- Verify that h is a match of Q in D, i.e.,  $h(body) \subseteq D$  and  $(h(x_1),...,h(x_k)) = (a_1,...,a_k)$

(NP-hardness) Reduction from 3-colorability

(in PTIME) For every substitution h : terms(body)  $\rightarrow$  terms(D), check if h(body)  $\subseteq$  D and (h(x<sub>1</sub>),...,h(x<sub>k</sub>)) = (a<sub>1</sub>,...,a<sub>k</sub>)

# **Complexity of Query Evaluation**

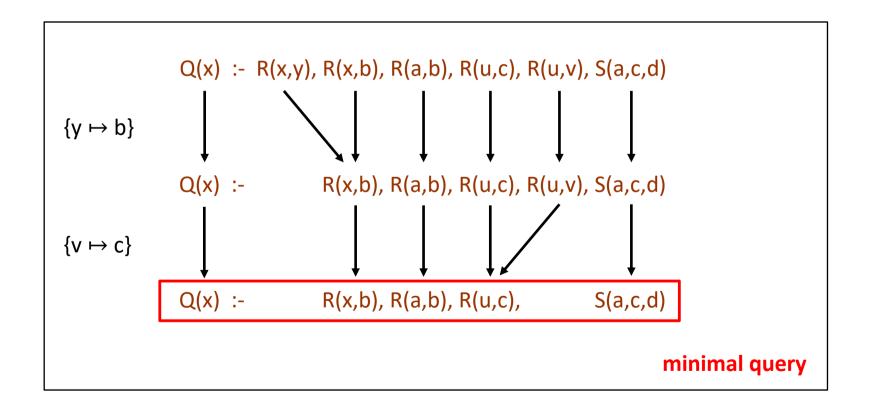
Theorem: CQ-Evaluation is NP-complete and in PTIME in data complexity

Evaluating a CQ Q over a database D takes time ||D||O(||Q||)

#### Minimizing Conjunctive Queries

Database theory has developed principled methods for optimizing CQs:

- Find an equivalent CQ with minimal number of atoms (the core)
- Provides a notion of "true" optimality



#### Minimizing Conjunctive Queries

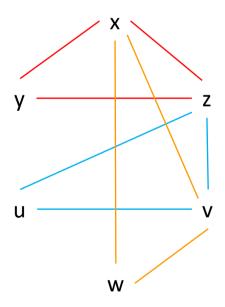
• But, a minimal equivalent CQ might not be easier to evaluate - remains NP-hard

- "Good" classes of CQs for which query evaluation is tractable (in combined complexity):
  - Graph-based
  - Hypergraph-based

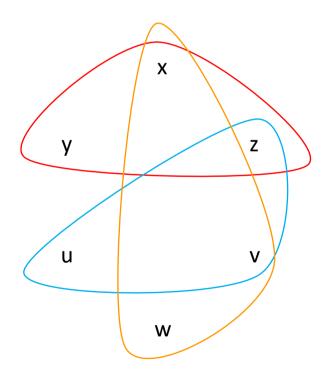
# (Hyper)graph of Conjunctive Queries

$$Q := R(x,y,z), R(z,u,v), R(v,w,x)$$

graph of Q - G(Q)



hypergraph of Q - H(Q)



#### "Good" Classes of Conjunctive Queries

measures how close a graph is to a tree

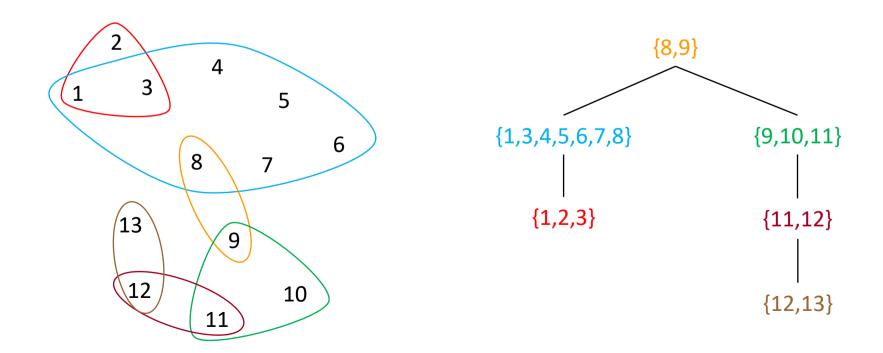
- Graph-based
  - CQs of bounded treewidth their graph has bounded treewidth

measures how close a hypergraph is to an acyclic one

- Hypergraph-based:
  - CQs of bounded hypertree width their hypergraph has bounded hypertree width
  - Acyclic CQs their hypergraph has hypertree width 1

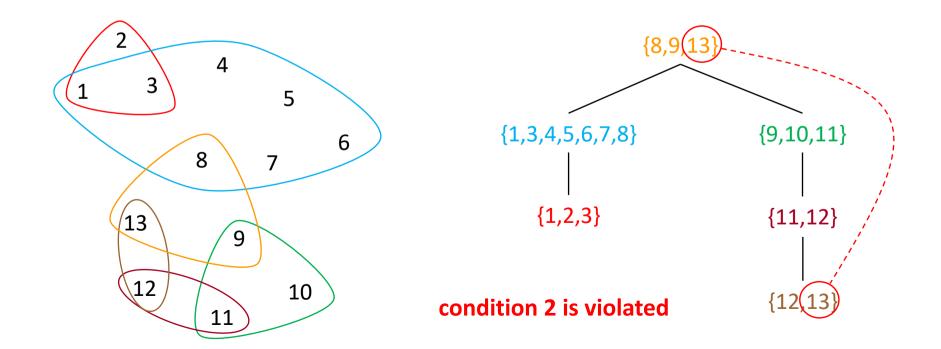
A join tree of a hypergraph  $\mathbf{H} = (V,E)$  is a labeled tree  $\mathbf{T} = (N,F,L)$ , where  $L: N \to E$  such that:

- 1. For each hyperedge  $e \in E$  of **H**, there exists  $n \in N$  such that e = L(n)
- 2. For each node  $u \in V$  of H, the set  $\{n \in N \mid u \in L(n)\}$  induces a connected subtree of T



A join tree of a hypergraph  $\mathbf{H} = (V,E)$  is a labeled tree  $\mathbf{T} = (N,F,L)$ , where  $L: N \to E$  such that:

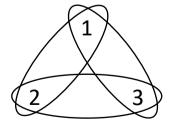
- 1. For each hyperedge  $e \in E$  of H, there exists  $n \in N$  such that e = L(n)
- 2. For each node  $u \in V$  of **H**, the set  $\{n \in N \mid u \in L(n)\}$  induces a connected subtree of **T**



A join tree of a hypergraph  $\mathbf{H} = (V,E)$  is a labeled tree  $\mathbf{T} = (N,F,L)$ , where  $L: N \to E$  such that:

- 1. For each hyperedge  $e \in E$  of **H**, there exists  $n \in N$  such that e = L(n)
- 2. For each node  $u \in V$  of H, the set  $\{n \in N \mid u \in L(n)\}$  induces a connected subtree of T

**Definition:** A hypergraph is acyclic if it has a join tree

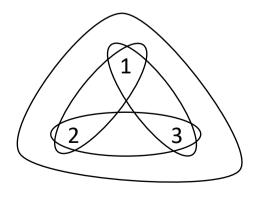


prime example of a cyclic hypergraph

A join tree of a hypergraph  $\mathbf{H} = (V,E)$  is a labeled tree  $\mathbf{T} = (N,F,L)$ , where  $L: N \to E$  such that:

- 1. For each hyperedge  $e \in E$  of **H**, there exists  $n \in N$  such that e = L(n)
- 2. For each node  $u \in V$  of H, the set  $\{n \in N \mid u \in L(n)\}$  induces a connected subtree of T

**Definition:** A hypergraph is acyclic if it has a join tree



but this is acyclic

# Relevant Algorithmic Tasks

#### **ACYCLICITY**

**Input:** a conjunctive query **Q** 

**Question:** is **Q** acyclic? or is H(Q) acyclic?

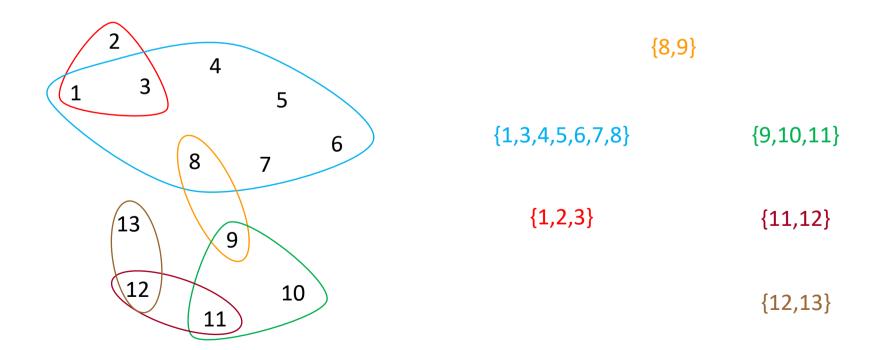
 ${Q \in CQ \mid H(Q) \text{ is acyclic}}$ 

#### **ACQ**-Evaluation

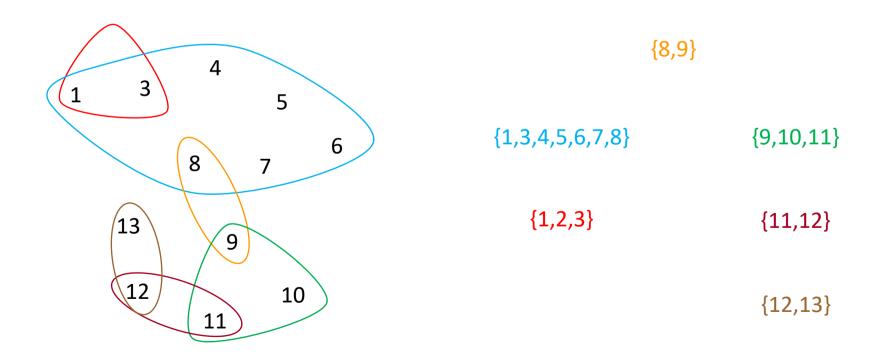
**Input:** a database D, an acyclic conjunctive query  $\mathbb{Q}$ , and a tuple  $(a_1,...,a_k)$  of values

Question:  $(a_1,...,a_k) \in \mathbb{Q}(D)$ ?

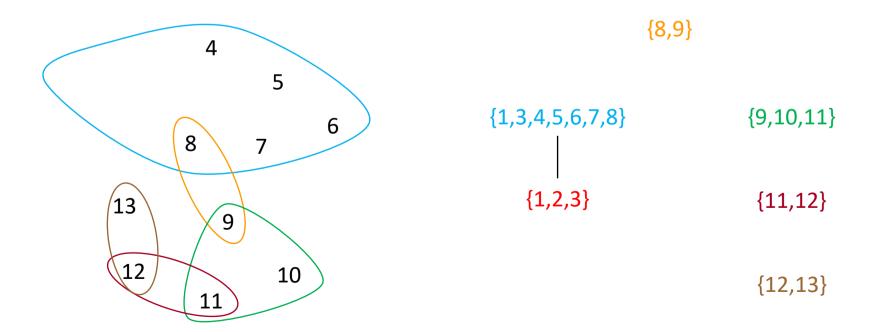
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



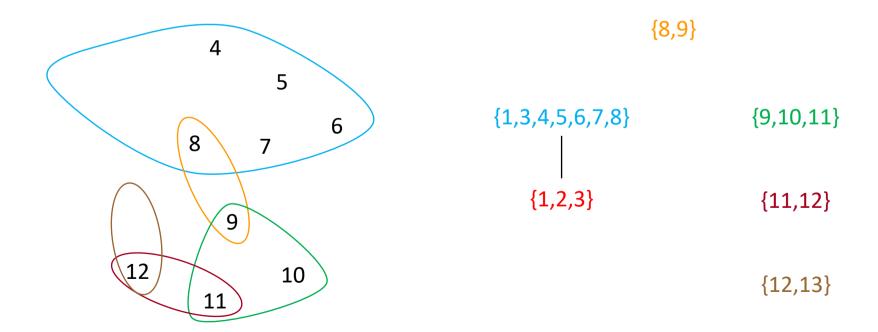
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



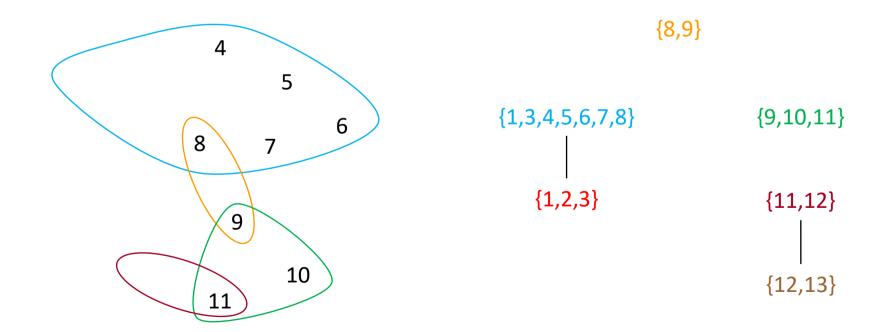
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



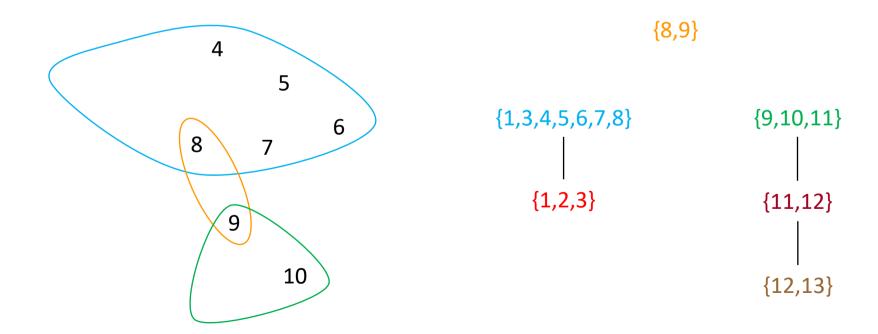
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



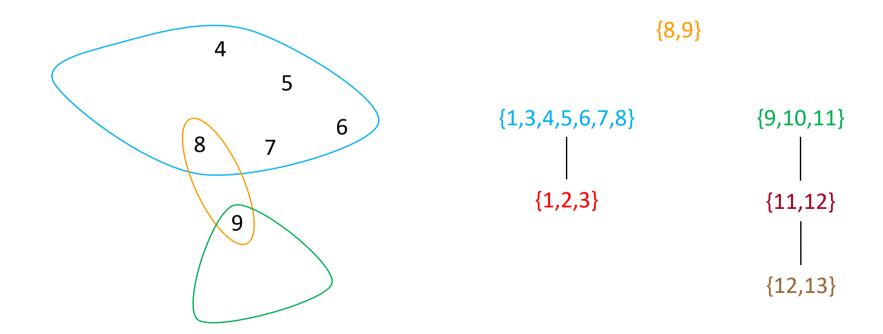
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



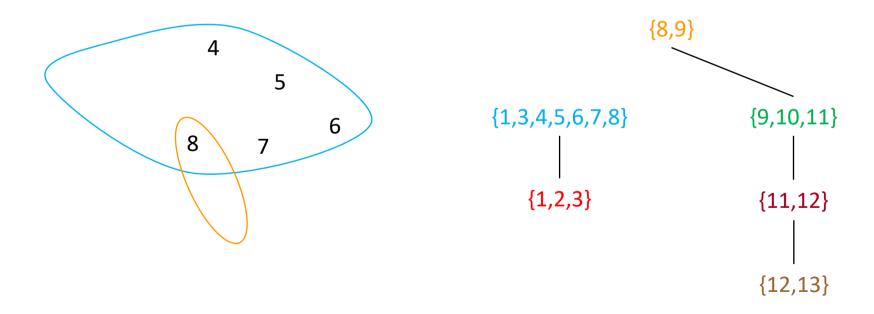
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



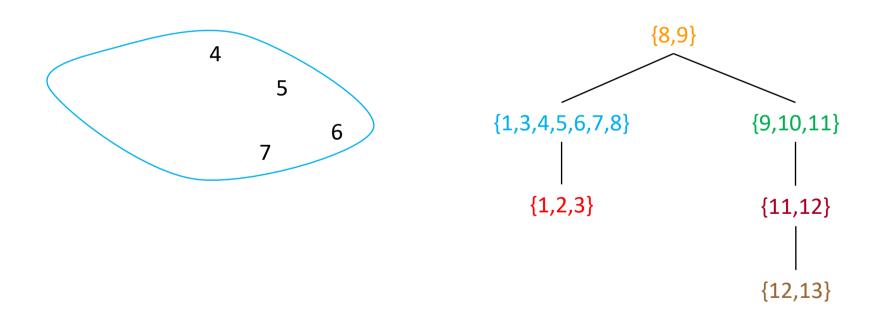
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



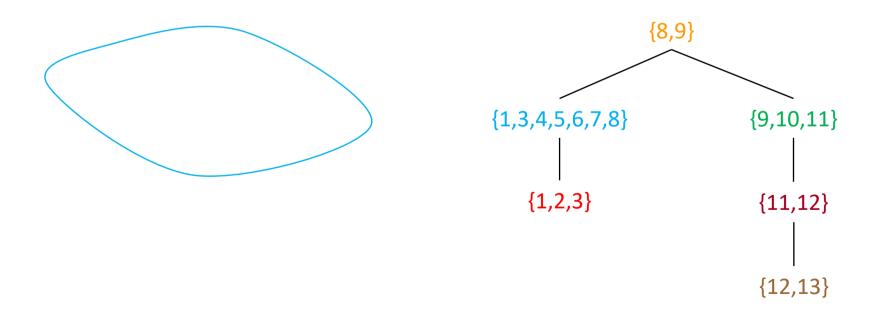
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



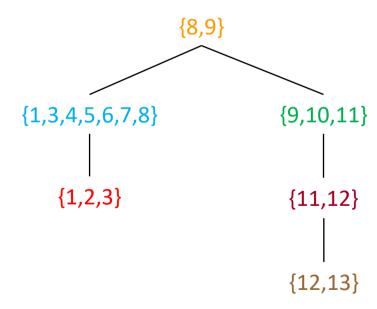
- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges



Via the GYO-reduction (Graham, Yu and Ozsoyoglu)

- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges

empty hypergraph



Via the GYO-reduction (Graham, Yu and Ozsoyoglu)

- 1. Eliminate nodes occurring in at most one hyperedge
- 2. Eliminate hyperedges that are empty or contained in other hyperedges

**Theorem:** A hypergraph **H** is acyclic iff  $GYO(H) = \emptyset$ 

 $\downarrow$ 

the case, a join tree can be found in polynomial time.

 $\Downarrow$ 

Theorem: ACYCLICITY is in PTIME

Theorem: ACYCLICITY is in PTIME

**NOTE:** actually, we can check whether a CQ is acyclic in time O(||Q||)

linear time in the size Q

# **Evaluating Acyclic CQs**

**Theorem: ACQ**-Evaluation is in PTIME

**NOTE:** actually, if H(Q) is acyclic, then Q can be evaluated in time  $O(||D|| \cdot ||Q||)$ 

linear time in the size of D and Q

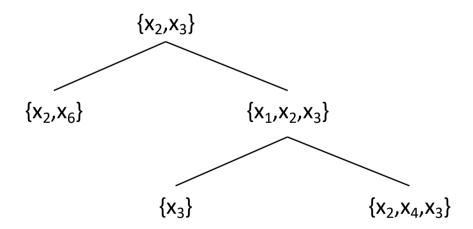
#### Yannakaki's Algorithm

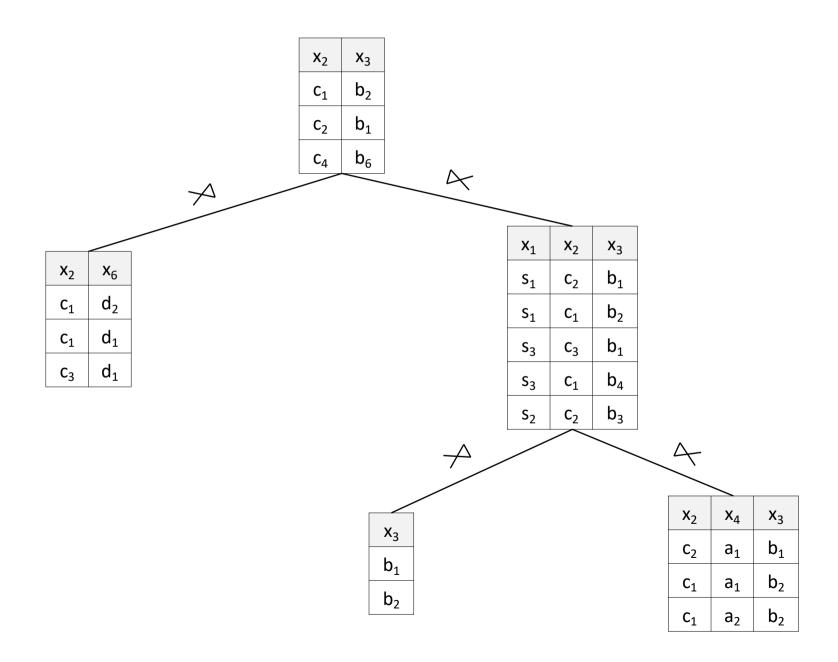
Dynamic programming algorithm over the join tree

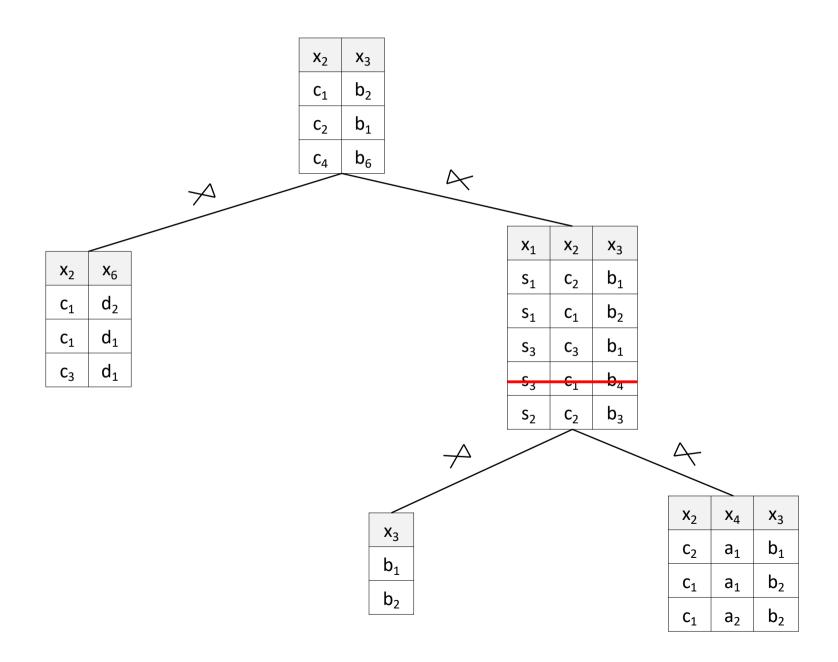
Given a database D and an acyclic Boolean CQ Q

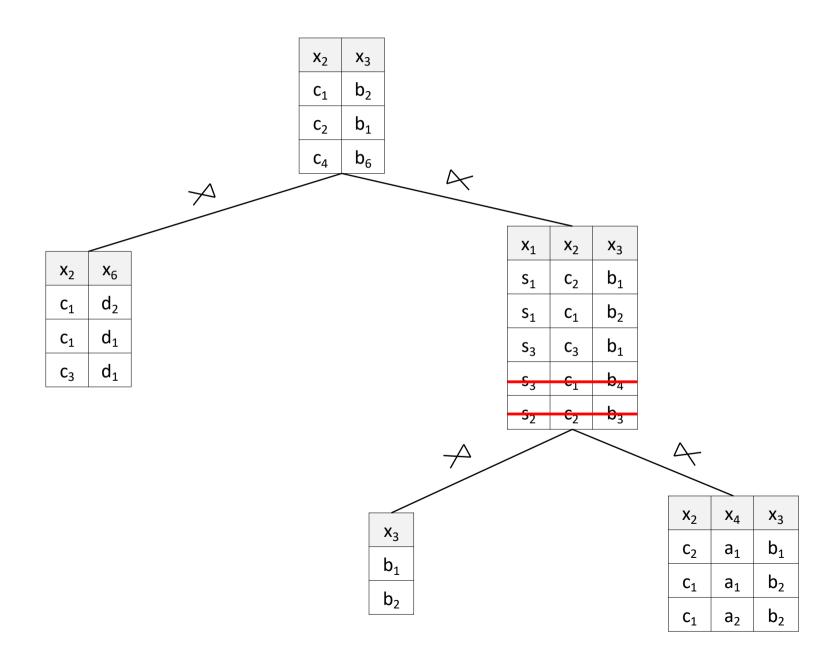
- 1. Compute the join tree **T** of H(Q)
- 2. Assign to each node of **T** the corresponding relation of D
- 3. Compute semi-joins in a bottom up traversal of T
- 4. Return YES if the resulting relation at the root of **T** is non-empty; otherwise, return NO

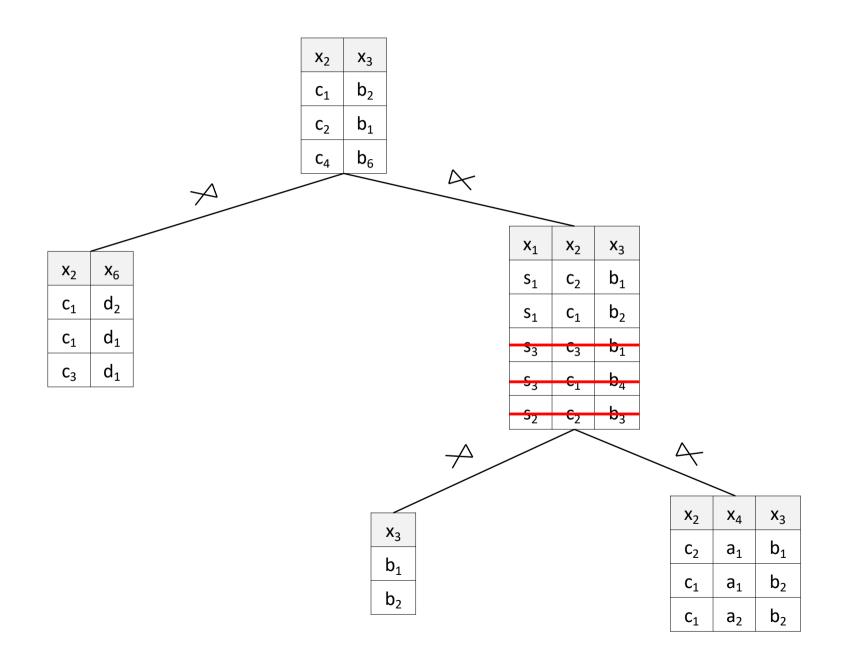
Q :-  $R_1(x_1,x_2,x_3)$ ,  $R_2(x_2,x_3)$ ,  $R_3(x_2,x_6)$ ,  $R_4(x_3)$ ,  $R_5(x_2,x_4,x_3)$ 

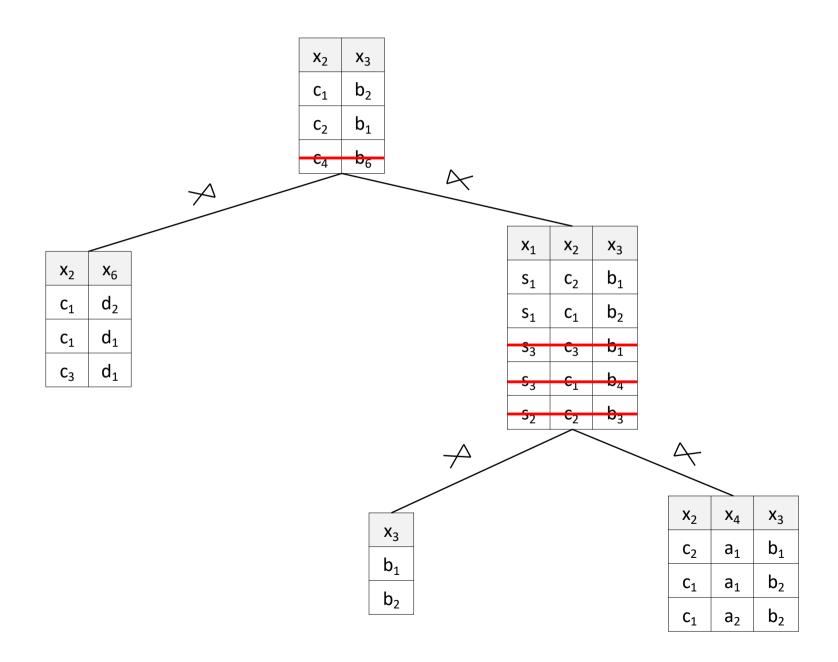


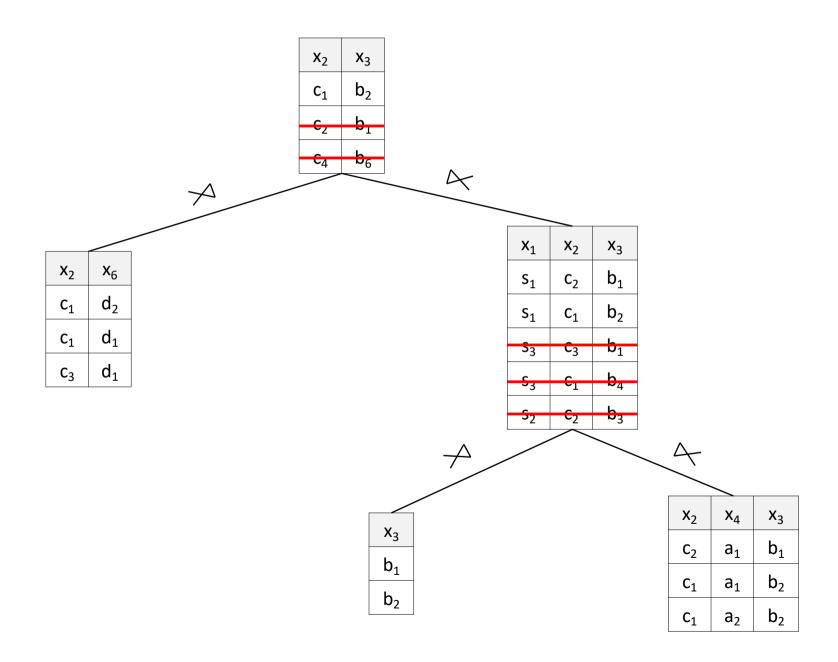


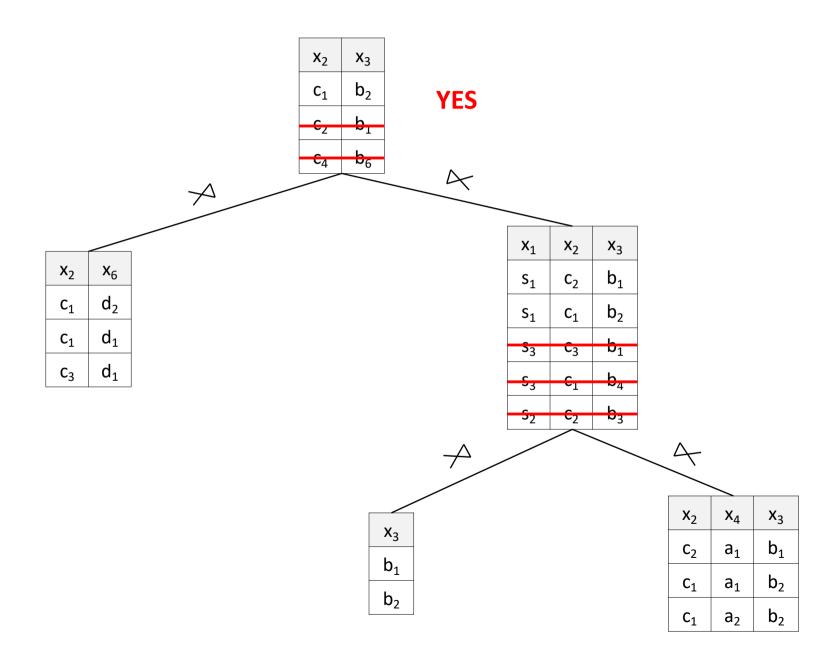












#### Recap

 "Good" classes of CQs for which query evaluation is tractable - conditions based on the graph or hypergraph of the CQ

• Acyclic CQs - their hypergraph is acyclic, can be checked in linear time

• Evaluating acyclic CQs is feasible in linear time (Yannakaki's algorithm)