

Data streaming algorithms (2)

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Recall: streaming algorithms

- The **input** of a streaming algorithm is given as a **data stream**, which is a sequence of data

$$\mathcal{S} = s_1, s_2, \dots, s_m, \dots,$$

and every s_i belongs to the universe U of size n .

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(ϵ, δ) -APPROXIMATION

For confidence parameter ϵ and approximation parameter δ , the algorithm's output **Output** and the exact answer **Exact** satisfies

$$\mathbb{P} [\text{Output} \in (1 - \epsilon, 1 + \epsilon) \cdot \text{Exact}] \geq 1 - \delta.$$

Recall: two models of streaming algorithms

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Turnstile model: every item s_i in S associates with “+” or “-”, which indicates if s_i is added into or deleted from S .

- “+” indicates that s_i is added into the dataset;
- “-” indicates that s_i is deleted from the dataset.

Why turnstile model?

- Data may be added or deleted over time, e.g. Facebook graph.
- We need *robust* algorithms to handle this situation.

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THEOREM

The medium of the returned values from $\Theta(\log(1/\delta))$ independent copies of the BJKST algorithm gives an (ε, δ) -approximation of F_0 .

Last lecture: algorithms in the cash register model

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- Sampling probability for the current item usually depends on the whole data stream that algorithm has seen so far.
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Sampling techniques are usually non-applicable in the turnstile model.

- Approximating F_2 -norm in the turnstile model
- Frequency estimation in the turnstile model

Algorithm to approximate F_2 in the turnstile model

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Hence, we can (ϵ, δ) -approximate F_2 , by **running multiple copies of the algorithm in parallel and return the average value.**

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ANOTHER ALGORITHM TO APPROXIMATE F_0

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- 7: **return** $\frac{1}{t} \cdot \sum_{i=1}^t Z_i$, where $Z_i = y_i^2$

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THEOREM

With constant probability, the returned value of the algorithm is in $(1 - \varepsilon, 1 + \varepsilon) \cdot F_2$. Moreover, the algorithm's space complexity is $O((1/\varepsilon^2) \log n)$ bits.

Our current status:

- We run t independent copies in parallel and return $(\sum_{i=1}^t Z_i) / t$.
- The key lemma tells us that $\mathbb{E}[Z_i] = F_2$, and $\mathbb{V}[Z_i] \leq 2 \cdot F_2^2$.

Algorithm analysis: space complexity (upper bounding t)

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To derive an upper bound on t to ensure an (ϵ, δ) -approximation, we apply the Law of Large Numbers:

$$\begin{aligned} \mathbb{P} \left[\left| \frac{Z_1 + \dots + Z_t}{t} - \mathbb{E}[Z_i] \right| \geq \epsilon \mathbb{E}[Z_i] \right] &= \mathbb{P} \left[\left| \frac{Z_1 + \dots + Z_t}{t} - F_2 \right| \geq \epsilon F_2 \right] \\ &\leq \frac{2 \cdot F_2^2}{t \cdot (\epsilon \mathbb{E}[Z_i])^2} \\ &= \frac{2 \cdot F_2^2}{t \cdot \epsilon^2 \cdot F_2^2}. \end{aligned}$$

Hence, choosing $t = \lceil 6/\epsilon^2 \rceil$ suffices for our purpose.

Proving the key lemma: $\mathbb{E}[Z] = F_2$, where $Z = Z_i$

By the algorithm description, we have $y = \sum_{x \in \mathcal{S}} m_x \cdot h(x)$, where m_x is the number of occurrences of x .

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$$Z = \left(\sum_{x \in \mathcal{S}} m_x \cdot h(x) \right)^2 = \sum_{x \in \mathcal{S}} m_x^2 \cdot h^2(x) + \sum_{\substack{x, y \in \mathcal{S} \\ x \neq y}} m_x \cdot h(x) \cdot m_y \cdot h(y).$$

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By linearity of expectation, we have

$$\begin{aligned} \mathbb{E}[Z] &= \sum_{x \in \mathcal{S}} m_x^2 \cdot \mathbb{E}[h^2(x)] + \sum_{\substack{x, y \in \mathcal{S} \\ x \neq y}} m_x \cdot m_y \cdot \mathbb{E}[h(x)] \mathbb{E}[h(y)] \\ &= \sum_{x \in \mathcal{S}} m_x^2 = F_2. \end{aligned}$$

Here we use the fact that

$$\mathbb{E}[h(x)] = 0, \quad \mathbb{E}[h^2(x)] = 1.$$

The key: different powers of h and $\mathbb{E}(\cdot)$ give magical cancellation!

Proving the key lemma: $\mathbb{V}[Z] \leq 2F_2^2$, where $Z = Z_i$

We have

$$\begin{aligned}\mathbb{E}[Z^2] &= \mathbb{E}\left[\left(\sum_{x \in \mathcal{S}} m_x \cdot h(x)\right)^4\right] \\ &= \sum_{x,y,u,v} m_x \cdot m_y \cdot m_u \cdot m_v \cdot \mathbb{E}[h(x) \cdot h(y) \cdot h(u) \cdot h(v)].\end{aligned}$$

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$$\mathbb{E}[Z^2] = \sum_{x \in S} m_x^4 \cdot \mathbb{E}[h^4(x)] + \sum_{\substack{x,y \in S \\ x \neq y}} \frac{1}{2} \cdot \binom{4}{2} \cdot m_x^2 \cdot m_y^2 \cdot \mathbb{E}[h^2(x)] \mathbb{E}[h^2(y)]$$

only variables with even degrees survive!

$$\begin{aligned}&= \sum_{x \in S} m_x^4 + \sum_{\substack{x,y \in S \\ x \neq y}} \frac{1}{2} \cdot \binom{4}{2} \cdot m_x^2 \cdot m_y^2 \\ &\leq 2 \cdot \left(\sum_{x \in S} m_x^2\right)^2 = 2 \cdot F_2^2.\end{aligned}$$

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 3. Apply Chebyshev's inequality and Chernoff bound to show the number of copies needed to run in parallel in order to have (ϵ, δ) -approximation.
 - Sadly, applications of these inequalities always introduce a factor of $O(1/\epsilon^2)$.
 - Is the $1/\epsilon^2$ -dependency always needed?

- Approximating F_2 -norm in the turnstile model
- Frequency estimation in the turnstile model

Frequency estimation

Let S be a multiset, and S is empty initially. The data stream consists of a sequence of update operations, and each operation is one of the follows:

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We need to design an algorithm running in the turnstile model!

The Count-Min sketch

Cormode and Muthukrishnan (2005) introduced the Count-Min sketch for the frequency estimation problem.

The Count-Min sketch

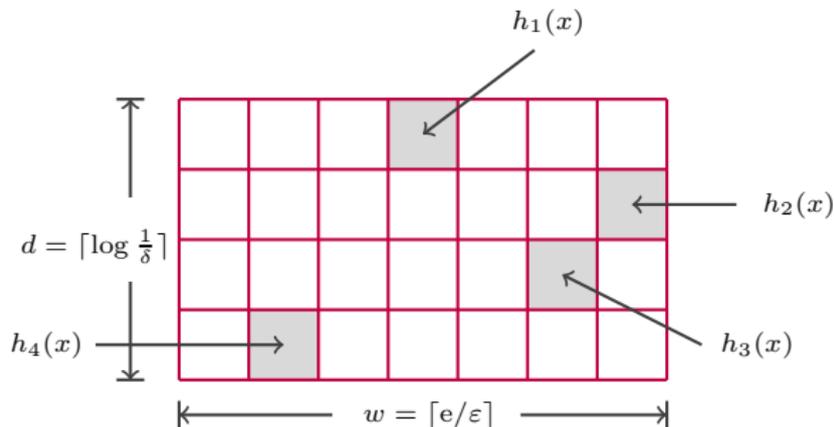
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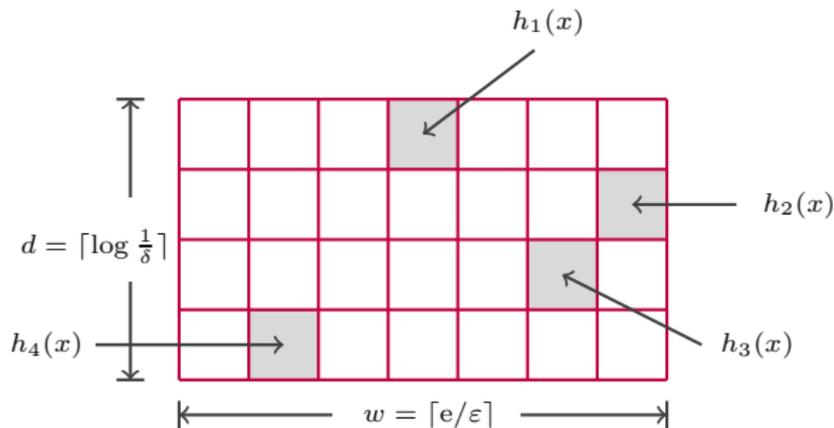
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The space complexity only depends on ϵ and δ .

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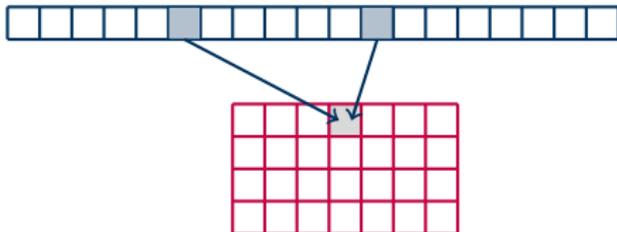
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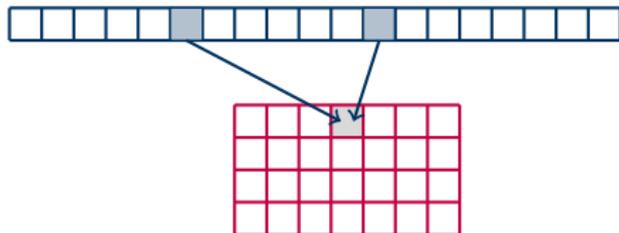
- 1: If $\text{Insert}(x)$ arrives
- 2: for $j = 1$ to d do
- 3: $C[j, h_j(x)] = C[j, h_j(x)] + 1$
- 4: If $\text{Delete}(x)$ arrives
- 5: for $j = 1$ to d do
- 6: $C[j, h_j(x)] = C[j, h_j(x)] - 1$
- 7: If $\text{Query}(x)$ arrives, then
- 8: return $m'_x \triangleq \min_{1 \leq i \leq d} C[j, h_j(x)]$



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Theorem: The estimate m'_x satisfies $m'_x \geq m_x$, and w. p. at least $1 - \delta$ it holds $m'_x \leq m_x + \varepsilon \cdot F_1$, where F_1 is the first moment of the multiset S .

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Analysis of Count-Min Sketch

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Markov inequality

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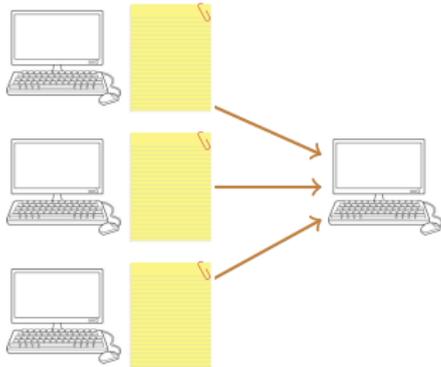
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A communication-efficient way:



- The sites communicate initially to use the same hash functions.
- All the sites maintains their own CM sketch;
- The sites send their CM sketches to the host.

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- Since each entry is non-negative, the CM Sketch returns the *minimum* value instead of the *medium* value.
- The error bound is **one-sided**. This feature is crucial for many applications.
- The paper introducing the CM sketch has received more than 1,100 citations (checked in October 2018), which is very unusual for a theory paper.
- For further discussion, see <https://sites.google.com/site/countminsketch/home>

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 - and much more...