Estimation



Learning outcomes

How to choose the **right data** for estimation Implications of **ergodicity** on estimation Use the **method of simulated moments**

Calibration vs estimation

Calibration: minimise the difference between **R** and **M** Estimation: find the true values of the variables

Calibration vs estimation

Real world output

Calibration: minimise the difference between **R** and **M Estimation:** find the true values of the variables

Model output

Comparing apples with apples

How do we compare the **model**produced data with the real-worldproduced data?

Comparing apples with apples

How do we compare the **model**produced data with the real-worldproduced data?

Look for equilibria!

The importance of ergodicity

- Our model generates y_t , which becomes
- stationary with mean $\mu^* = r\theta$
- Say the model is non-ergodic, so μ^* changes at every run, for the same θ

The importance of ergodicity

Our model generates y_t, which

We need to understand the properties μ^* of the model and of the data before the estimation phase

changes at every run, for the same θ

Preliminary tests

Stationarity is easy to test but things can be tricky if the data is not stationary

Ergodicity cannot be tested unless we observe many realisations of the same process

Example JVC - vhs Sony - betamax



Conclusion

If we, somehow, get to be fairly positive about the ergodicity of the system, then we can use that for estimation.

Otherwise there are other methods to deal with estimation (just wait a few slides)

Simulated minimum distance

We want to minimise the distance between the summary statistics of the real-world system and those of our model

We can use the method of simulated moments

Method of simulated moments

$\hat{\theta} = argmin_{\theta}[\mu^{*}(\theta) - \mu_{R}]'W^{-1}[\mu^{*}(\theta) - \mu_{R}]$ fWeights











Method of simulated moments

 $\hat{\theta} = argmin_{\theta}[w_1(\hat{\kappa} - \kappa) + w_2(\hat{a}(0) - a(0)) + w_3(\hat{x} - \langle x \rangle)]$

Method of simulated moments

$$\hat{\theta} = argmin_{\theta}[w_1(\hat{\kappa} - \kappa) + w_2(\hat{a}(0) - a(0)) + w_3(\hat{x} - \langle x \rangle)]$$

$$\hat{\theta} = argmin_{\theta}[w_1(\hat{\kappa} - \kappa) + w_2(\hat{\lambda}_a - \lambda_a) + w_3(\hat{x} - \langle x \rangle)]$$

Bayesian estimation

More appropriate when:

- inference is needed
- there are prior and posterior distributions

Tesco example - Recap One type of agents with heterogeneous variables Variables: shopping habits, expenditure, bias on deals, etc.

Actions: buy (last year people also suggested "steal") Interactions: recommend products to others, interact with store



How would you use the data? What summary statistics would you use for estimation/calibration?

How to build abms cheat sheet

Nature of agents List of variables describing their state List of actions the agents can perform Structure of their interaction with other agents

Definition of output variables of interest Appropriate experimental design Analysis of equilibria Sensitivity analysis



Agent design

How to build abms cheat sheet

Select the appropriate data Input validation Output validation

Select the appropriate data Test for stationarity and ergodicity Methods of simulated distances



Estimation

Congratulations! Now you know how to build an agent-based model

