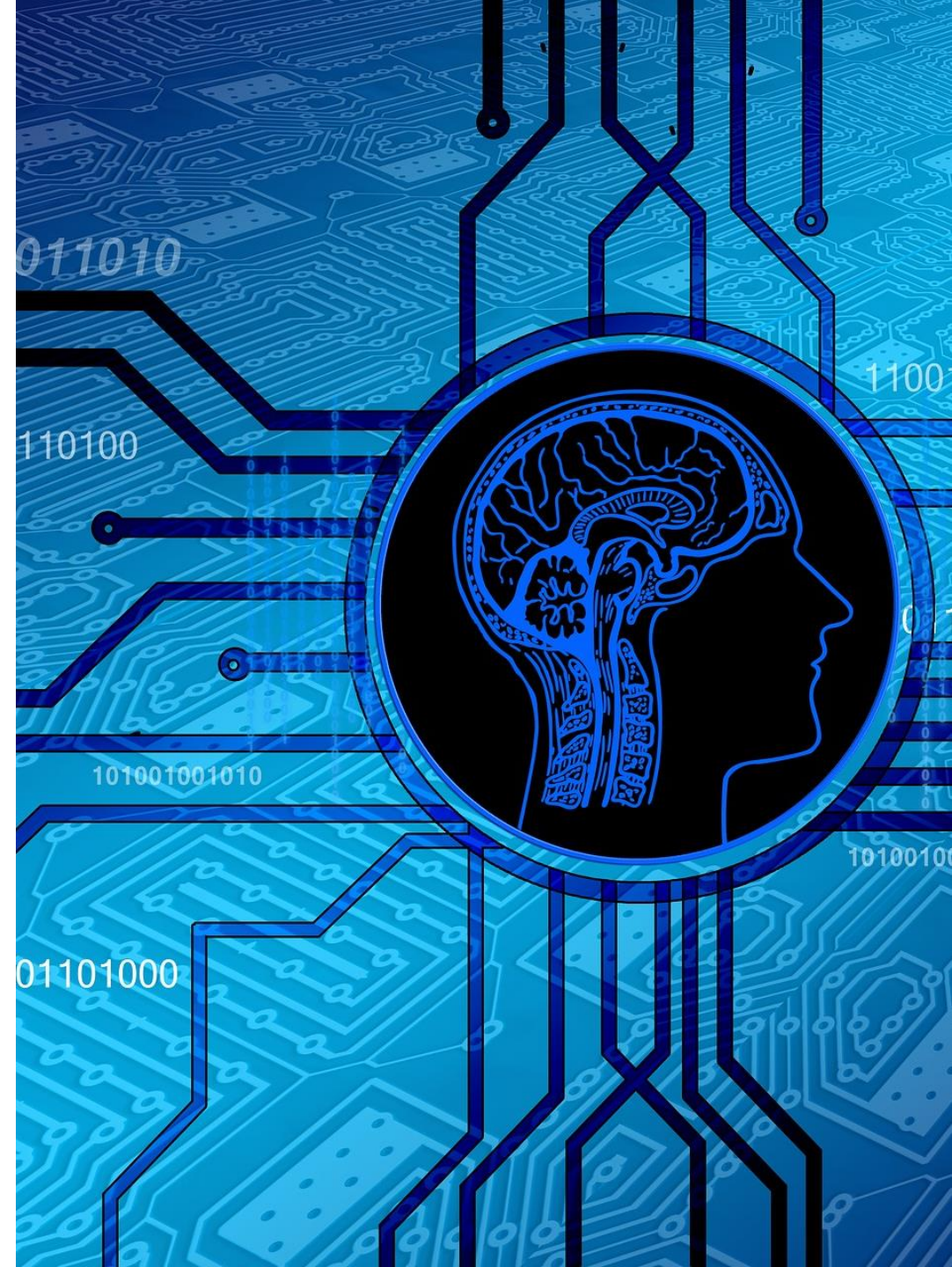


# Revision (Logic)

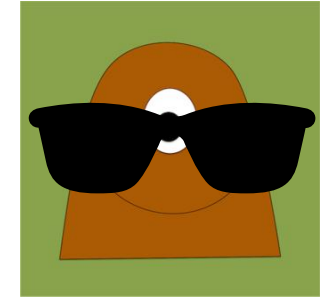
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Informatics 2D: Reasoning and Agents



# Logical Agents: KBs

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- Logical agents apply **inference** to a knowledge base to derive new information and make decisions.
- Basic concepts of logic:
  - **syntax**: formal structure of sentences
  - **semantics**: truth of sentences with respect to models
  - **entailment**: necessary truth of one sentence given another
  - **inference**: deriving sentences from other sentences
  - **soundness**: derivations produce only entailed sentences
  - **completeness**: derivations can produce all entailed sentences
- Wumpus world requires the ability to represent **partial** and **negated information**
- Propositional logic solves many problems but **lacks expressive power**.

# Logical equivalence

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$(\alpha \wedge \beta) \equiv (\beta \wedge \alpha)$	commutativity of $\wedge$
$(\alpha \vee \beta) \equiv (\beta \vee \alpha)$	commutativity of $\vee$
$((\alpha \wedge \beta) \wedge \gamma) \equiv (\alpha \wedge (\beta \wedge \gamma))$	associativity of $\wedge$
$((\alpha \vee \beta) \vee \gamma) \equiv (\alpha \vee (\beta \vee \gamma))$	associativity of $\vee$
$\neg(\neg\alpha) \equiv \alpha$	double-negation elimination
$(\alpha \rightarrow \beta) \equiv (\neg\beta \rightarrow \neg\alpha)$	contraposition
$(\alpha \rightarrow \beta) \equiv (\neg\alpha \vee \beta)$	implication elimination
$(\alpha \leftrightarrow \beta) \equiv ((\alpha \rightarrow \beta) \wedge (\beta \rightarrow \alpha))$	biconditional elimination
$\neg(\alpha \wedge \beta) \equiv (\neg\alpha \vee \neg\beta)$	de Morgan
$\neg(\alpha \vee \beta) \equiv (\neg\alpha \wedge \neg\beta)$	de Morgan
$(\alpha \wedge (\beta \vee \gamma)) \equiv ((\alpha \wedge \beta) \vee (\alpha \wedge \gamma))$	distributivity of $\wedge$ over $\vee$
$(\alpha \vee (\beta \wedge \gamma)) \equiv ((\alpha \vee \beta) \wedge (\alpha \vee \gamma))$	distributivity of $\vee$ over $\wedge$

Two sentences are **logically equivalent** iff **true** in the same models:

$$\alpha \equiv \beta \text{ iff } \alpha \models \beta \text{ and } \beta \models \alpha$$

# Validity and Satisfiability

A sentence is **valid** if it is true in *all models*

- *true*,  $A \vee \neg A$ ,  $A \Rightarrow A$ ,  $(A \wedge (A \Rightarrow B)) \Rightarrow B$

Validity is connected to inference via the **Deduction Theorem**

- $KB \models \alpha$  if and only if  $(KB \Rightarrow \alpha)$  is valid

A sentence is **satisfiable** if it is true in *some model*

- e.g.,  $A \vee B$ ,  $C$

A sentence is **unsatisfiable** if it is true in *no models*

- e.g.,  $A \wedge \neg A$

Satisfiability is connected to inference via the following:

- $KB \models \alpha$  if and only if  $(KB \wedge \neg \alpha)$  is unsatisfiable
- prove  $\alpha$  by *reductio ad absurdum*

# Effective Propositional Inference

---

- Two algorithms: **DPLL & WalkSAT**
  - DPLL is a decision procedure, i.e., it will return true (yes) or false (no) for a set of propositional clauses (cf. complete algorithm)
  - They work with **Conjunctive Normal Form (CNF)**

# The DPLL algorithm

---

Determine if an input propositional logic sentence (in CNF) is *satisfiable*.

**Improvements** over truth table enumeration:

1. Early termination
2. Pure symbol heuristic
3. Unit clause heuristic

# The WalkSAT algorithm

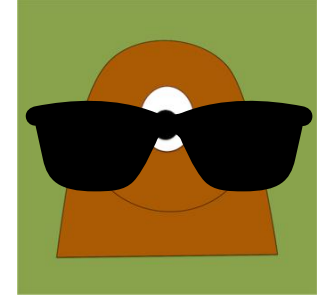
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- **Incomplete**, local search algorithm
- **Evaluation function**:
  - The **min-conflict heuristic** of minimizing the number of unsatisfied clauses
- Algorithm checks for satisfiability by **randomly** flipping the **values** of variables
- Balance between **greediness** and **randomness**

# First-Order Logic

---



- **objects** and **relations** are semantic primitives
- **syntax**: constants, functions, predicates, equality, quantifiers.
- **Predicates** (applied to terms) have a truth value (i.e., true or false)
  - e.g.,  $<$  (less than) is a predicate so,  $x < 3 + 5$  is either true or false
- **Functions** just construct new terms out of other terms
- **Increased expressive power**: sufficient to define Wumpus world.
  - Quantifiers, Equality ...



# Unification and Generalised Modus Ponens



Rules for quantifiers

UI, EI etc.



Reducing FOL to PL



Unification



Generalised modus ponens (GMP)

# Most General Unifier (MGU)

---

Unifying  $Knows(John, x)$  and  $Knows(y, z)$

$$\theta = \{y/John, x/z\} \quad \text{or} \quad \theta = \{y/John, x/John, z/John\}$$

The first unifier is **more general** than the second.

FOL: There is a **single most general unifier** (MGU) that is unique up to renaming of variables.

$$\text{MGU} = \{y/John, x/z\}$$

Can be viewed as an **equation solving** problem.

- *i.e. solve  $Knows(John, x) \stackrel{?}{=} Knows(y, z)$*



# MGU Exercises

---

- $P(x,A) =?= P(f(y),y)$
- $P(x,g(x)) =?= P(f(y),y)$

- Decomposition
- Conflict
- Eliminate
- Delete
- Switch
- Coalesce
- Occurs Check

# Inference

---

- Forward chaining
  - Informally: Unify all the assumptions in an implication rule with facts in KB to discharge them. If successful, add instantiated conclusion to KB.  
This is like a **discovery process**.
- Backward chaining
  - Informally: Unify conclusion of an implication rule with some fact in KB. If successful, add instantiated assumptions to KB as new goals.  
This is like a **decomposition into sub-problems**.

# Resolution

---

- Formal statements for various types of resolution.
- **Refutation method** works by looking for a contradiction i.e., tries to derive falsity (empty clause).
- Need to **negate the goal** before converting it to clausal form.

# Example

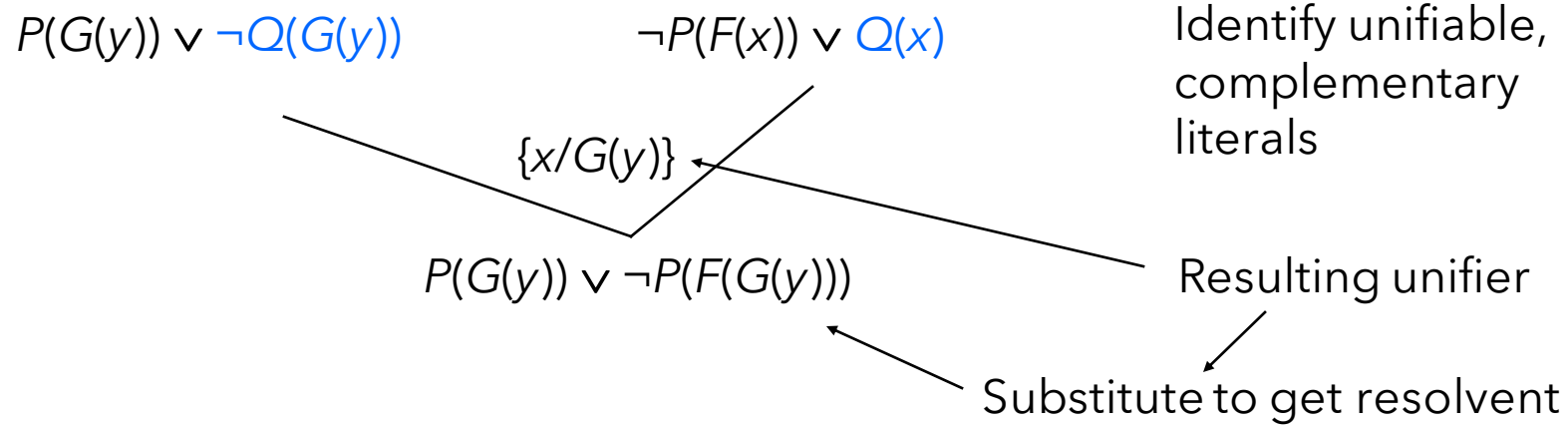


9. Which of the following clauses is the result of resolving clause  $P(G(y)) \vee \neg Q(G(y))$  with clause  $\neg P(F(x)) \vee Q(x)$ , assuming they can be resolved?
- (a)  $P(G(y)) \vee \neg P(F(x))$ .
  - (b)  $Q(y) \vee \neg Q(F(y))$ .
  - (c) Resolution fails.
  - (d)  $P(G(y)) \vee P(F(G(y))) \vee \neg Q(G(y))$ .
  - (e)  $P(G(y)) \vee \neg P(F(G(y)))$ .

# Example

9. Which of the following clauses is the result of resolving clause  $P(G(y)) \vee \neg Q(G(y))$  with clause  $\neg P(F(x)) \vee Q(x)$ , assuming they can be resolved?

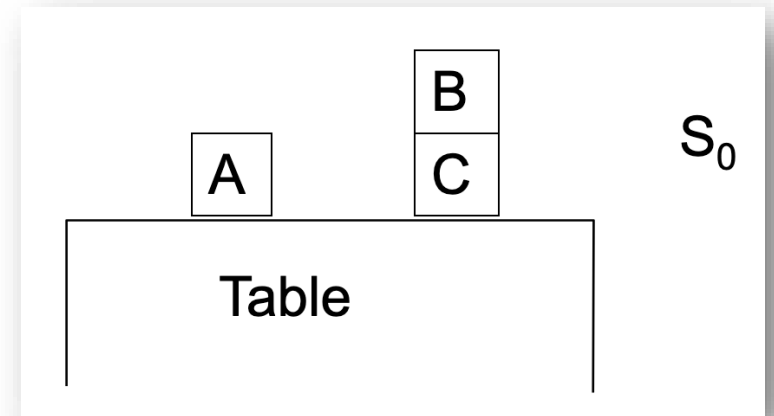
- (a)  $P(G(y)) \vee \neg P(F(x))$ .
- (b)  $Q(y) \vee \neg Q(F(y))$ .
- (c) Resolution fails.
- (d)  $P(G(y)) \vee P(F(G(y))) \vee \neg Q(G(y))$ .
- (e)  $P(G(y)) \vee \neg P(F(G(y)))$ .



# Situation Calculus

---

- We **axiomatize** all our actions, then use a general theorem prover to prove that a situation exists in which our goal is true.
  - **Effect** Axioms
  - **Frame** Axioms
- The actions in the proof would comprise our **plan**.





**Goal:**  $\text{On}(A,B,s') \wedge \text{On}(B,C,s')$

---

- **Effect Axiom:**

$\forall x,y,s.$

$\text{Clear}(x,s) \wedge \text{Clear}(y,s) \Rightarrow \text{On}(x,y,\text{Result}(\text{Move}(x,y),s))$

- **Frame Axiom:**

$\forall x,y,s,a.$

$\text{On}(x,y,s) \wedge (\forall z. a=\text{Move}(x,z) \Rightarrow y=z)$   
 $\Rightarrow \text{On}(x,y,\text{Result}(a,s))$

- **Other axioms:**

**Unique action axioms, unique name axioms**

### Initial State

$\text{On}(A,\text{Table},S_0)$

$\text{On}(B,C,S_0)$

$\text{On}(C,\text{Table},S_0)$

$\text{Clear}(A,S_0)$

$\text{Clear}(B,S_0)$

**Constants:** A, B, C, S0

**Variables:** a, x, y, s



# Convert this KB into CNF Form

- Eliminate implications
- Move negations inwards
- Standardize variables apart
- Skolemize
- Drop Universal Quantifiers
- Create clauses

**Goal:**  $\text{On}(A,B,s') \wedge \text{On}(B,C,s')$

• **Effect Axiom:**

$\forall x,y,s.$

$\text{Clear}(x,s) \wedge \text{Clear}(y,s) \Rightarrow \text{On}(x,y,\text{Result}(\text{Move}(x,y),s))$

• **Frame Axiom:**

$\forall x,y,s,a.$

$\text{On}(x,y,s) \wedge (\forall z. a=\text{Move}(x,z) \Rightarrow y=z)$   
 $\Rightarrow \text{On}(x,y,\text{Result}(a,s))$

• **Other axioms:**

**Unique action axioms, unique name axioms**

**Initial State**

$\text{On}(A,\text{Table},S_0)$

$\text{On}(B,C,S_0)$

$\text{On}(C,\text{Table},S_0)$

$\text{Clear}(A,S_0)$

$\text{Clear}(B,S_0)$

**Constants:** A, B, C, S0

**Variables:** a, x, y, s

# Convert this KB into CNF Form

---

## KB and Axioms as Clauses

Constants: A, B, C, S0  
Variables: a, x, y, s

### Initial State

$\text{On}(A, \text{Table}, S0)$

$\text{On}(B, C, S0)$

$\text{On}(C, \text{Table}, S0)$

$\text{Clear}(A, S0)$

$\text{Clear}(B, S0)$

### Goal

$\neg \text{On}(A, B, s') \vee \neg \text{On}(B, C, s')$

### Effect Axiom

$\neg \text{Clear}(x, s) \vee \neg \text{Clear}(y, s) \vee$

$\text{On}(x, y, \text{Result}(\text{Move}(x, y), s))$

### Frame Axioms

$\neg \text{On}(x, y, s) \vee a = \text{Move}(x, Z(x, y, s, a)) \vee \text{On}(x, y, \text{Result}(a, s))$

$\neg \text{On}(x, y, s) \vee \neg y = Z(x, y, s, a) \vee \text{On}(x, y, \text{Result}(a, s))$

Skolem function



**Unique Action Axioms:**  $\neg \text{Move}(A, B) = \text{Move}(B, z)$ , etc

**Unique Name Axiom:** disequality for every pair of constants in KB



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<https://www.eusa.ed.ac.uk/whatson/awards/teachingawards>

8 years ago today... #AAAI-16



Thank you!

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