



THE UNIVERSITY
of EDINBURGH

Methods for Causal Inference

Lecture 12: PC Algorithm

Ava Khamseh

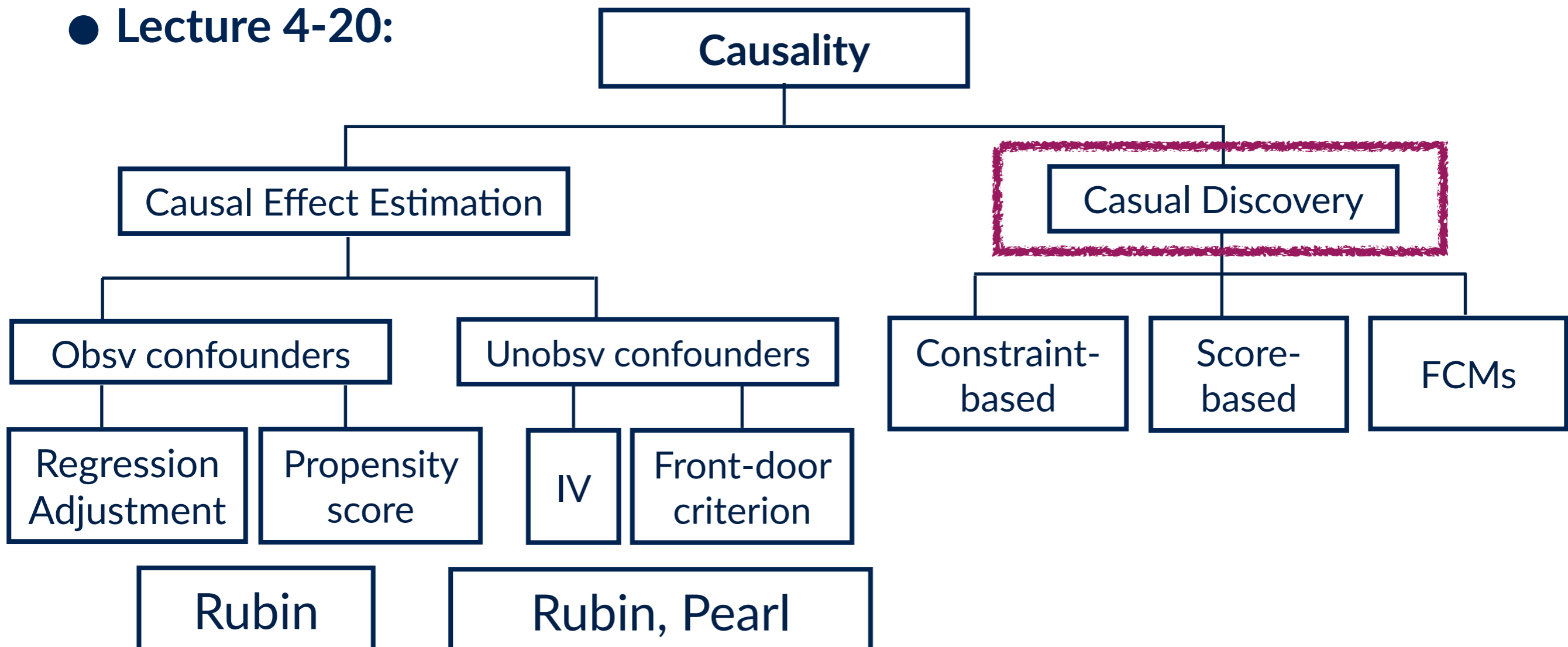
School of Informatics
2023-2024

Do Calculus

- Do-calculus: Contains, as subsets:
 - Backdoor criterion
 - Front-door criterion
- Allows analysis of more intricate structure beyond back- and front-door
- Uncovers **all** causal effects that can be identified from a given causal graph
- Power of causal graphs is not just representation but towards **discovery** of causal information (though with many assumptions and caveats ...)

Overview of the course

- **Lecture 1:** Introduction & Motivation, why do we care about causality? Why deriving causality from observational data is non-trivial.
- **Lecture 2:** Recap of probability theory, variables, events, conditional probabilities, independence, law of total probability, Bayes' rule
- **Lecture 3:** Recap of regression, multiple regression, graphs, SCM
- **Lecture 4-20:**



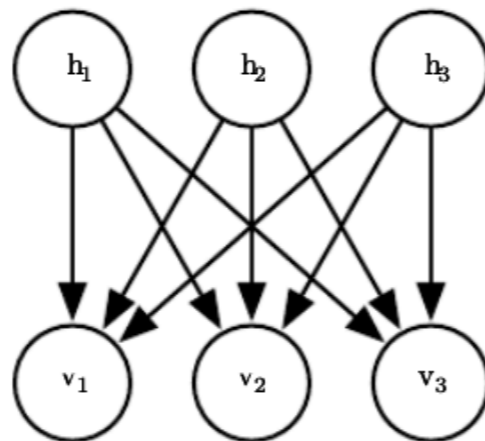
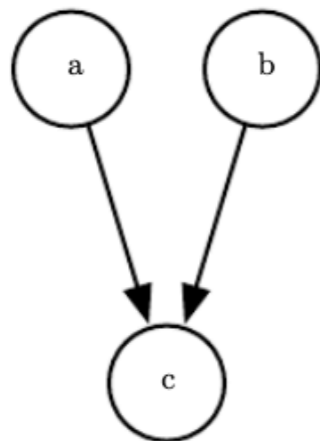
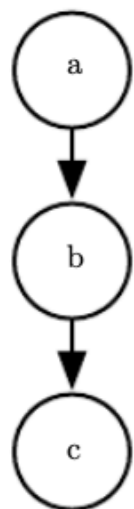
Directed vs Undirected Aside

Undirected vs Directed Graphs

Converting directed models to undirected models (cannot be represented perfectly)

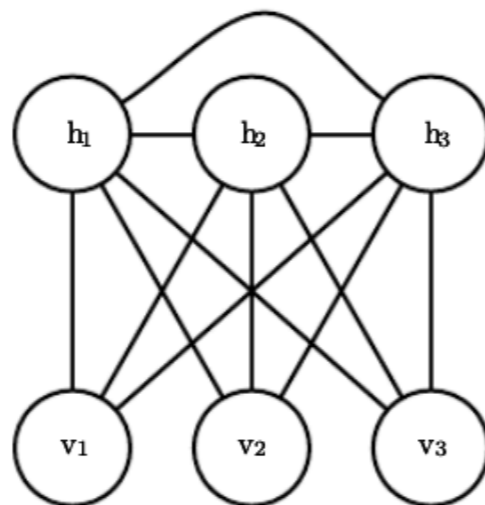
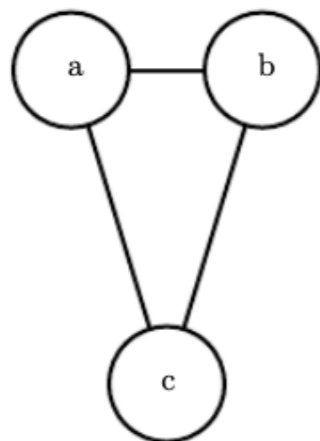
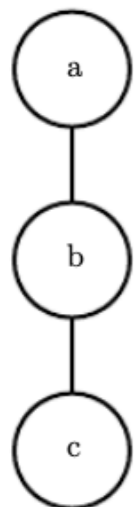
For every pair of variable x and y add an undirected edge (a moralised graph):

- if there is a directed edge, or,
- if x and y are parents of a node.



Same (conditional) independencies

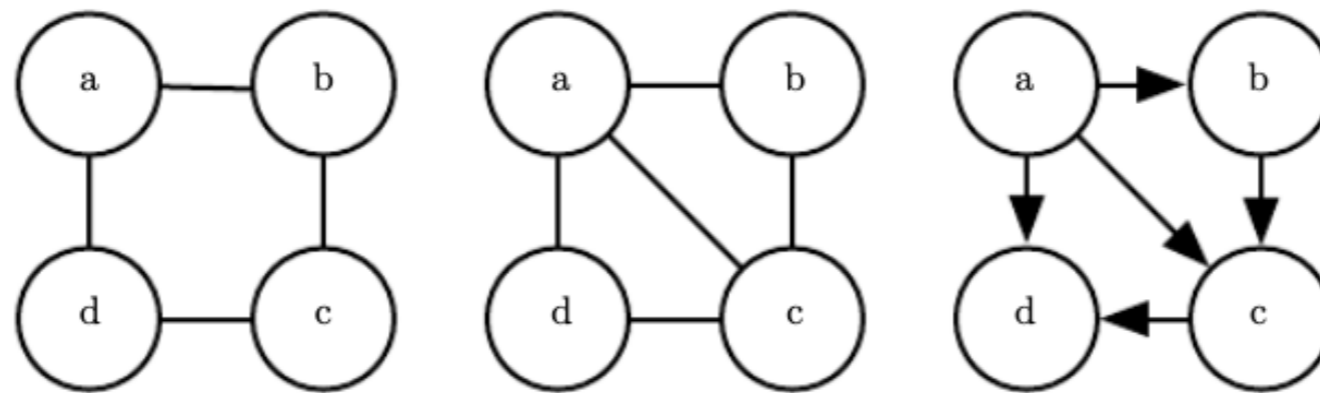
Not the same (cond.) independencies



Many edge are added, hence losing many implied conditional independencies.

Undirected vs Directed Graphs

Similarly, undirected models can contain substructures that no directed model can represent (i.e., the latter cannot represent all conditional independencies in the former)



Undirected model (left) simultaneously has $a \perp\!\!\!\perp c \mid \{b, d\}$ and $b \perp\!\!\!\perp d \mid \{a, c\}$

No directed model can capture this.

Instead triangulate (centre) and derive graph on the right, ensuring it remains a DAG (e.g. here use alphabetical ordering)

In conclusion: directed and undirected graphs encode strictly different (conditional) independence information

Markov blanket & Markov boundary

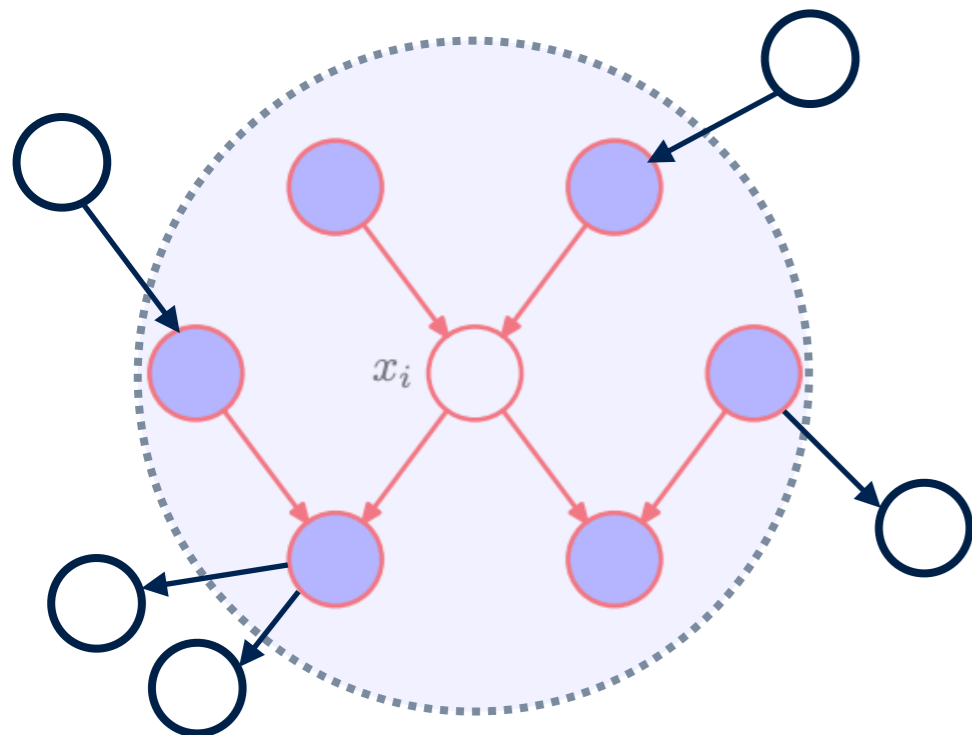
A Markov blanket of a random variable X_i in a random variable set $S=\{X_1, \dots, X_n\}$ is any subset S_1 of S , conditioned on which X_i is independent of all other variables outside of S_1 :

$$X_i \perp\!\!\!\perp S \setminus S_1 \mid S_1$$

In other words, S_1 contains all the information needed to infer X_i , and the variables in $S \setminus S_1$ add no further information.

A Markov blanket need not be unique. Any set in S that contains a Markov blanket is also a Markov blanket itself.

- Parents
- Children
- Coparents



A **Markov boundary** is a Markov blanket none of whose subsets are Markov blankets themselves

Causal Discovery

Learning causal relationships: Learn set of edges

- A causal structure **constrains** the possible types of probability distribution that can be generated from that structure

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Learning causal relationships: Learn set of edges

- A causal structure **constrains** the possible types of probability distribution that can be generated from that structure
- Reverse: Obtain causal structures from probability distributions via causal inference
- Types of constraints: **Conditional independencies** (all parametric distributions), Vanishing determinants of partial covariance matrices (linear Gaussian with unobserved confounders), **Unequal dependence on residuals** (Non-linear additive noise, or linear non-Gaussian), **interventions/perturbations**, time-series ...

Causal Discovery Methods (based on graphical models)

| Class of Algorithm | Name | Assumptions | Shortcomings | Input |
|---------------------------------|-------------|--|---|---------------------------------------|
| Constraint-based | PC (oldest) | Any distribution, No unobsv. confounders, Markov cond, faithfulness | Causal info only up to equivalence classes, Non bivariate | Complete undirected graph |
| | FCI | Any distribution, Asymptotically correct with confounders, Markov cond, faithfulness | | |
| Score-based | GES | No unobsv. confounders | Non-bivariate | Empty graph, adds edges, removes some |
| Functional Causal Models (FCMs) | LinGAM/ANM | Asymmetry in data | Requires additional assumptions (not general), harder for discrete data | Structural Equation Model |

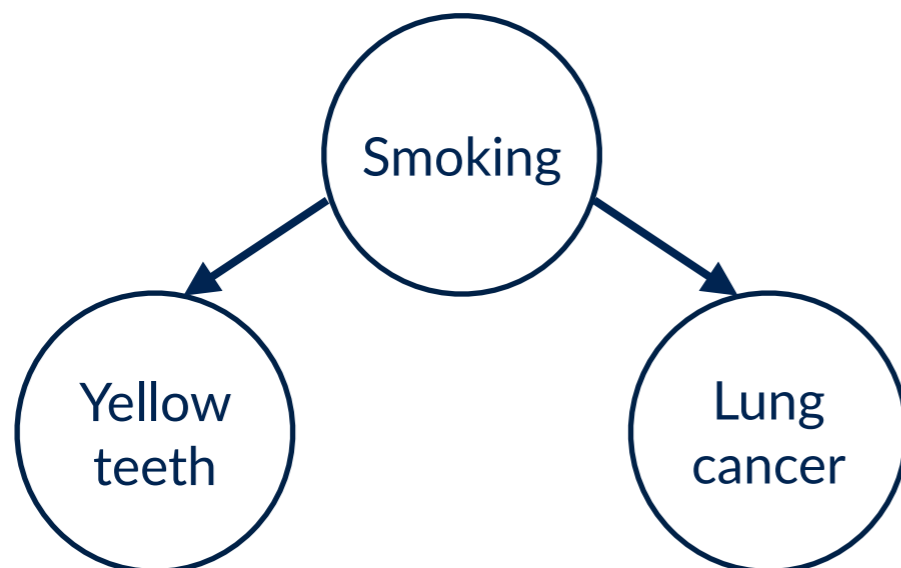
Assumption 1: The Markov Condition

Any variable X is independent of all other variables, conditional on its parents (PA) and unobserved variables (noise):

$$P(x_1, \dots, x_n) = \prod_{j=1}^J P(x_j | PA_j, \epsilon_j)$$

- Absent edge implies conditional independence (**CI**)
- Observing conditional dependence implies an edge

For example: Yellow teeth, lung cancer, smoking



An edge is wrongly inferred, when parent is omitted



Assumptions 2 & 3: Causal sufficiency & Faithfulness

- **Causal sufficiency:** For any pair of variables X, Y , if there exists a variable Z which is a direct cause of both X and Y , then Z is included in the causal graph (Z may be unobserved)
- A probability distribution P is **faithful** to a DAG G if no CI relations other than the ones entailed by the Markov property are present.
 - “Conjugate” to the Markov condition
 - Edge implies conditional dependence
 - Observing CI implies absence of an edge

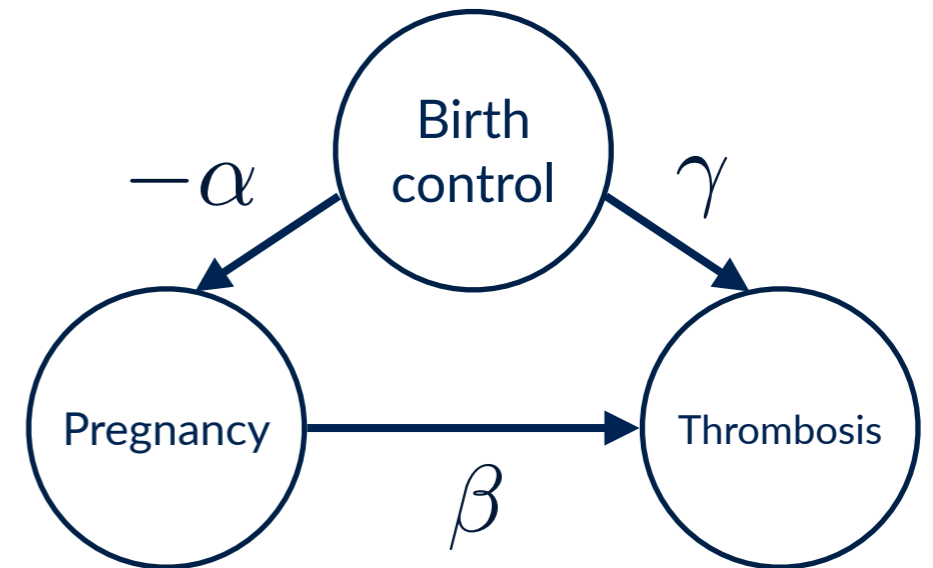
Assumptions 3: Faithfulness

It fails when distributions are set up in such a way that paths exactly cancel:

$$P = -\alpha B + U_P$$

$$T = \beta P + \gamma B + U_T$$

$$\Rightarrow T = (-\alpha\beta + \gamma)B + U$$



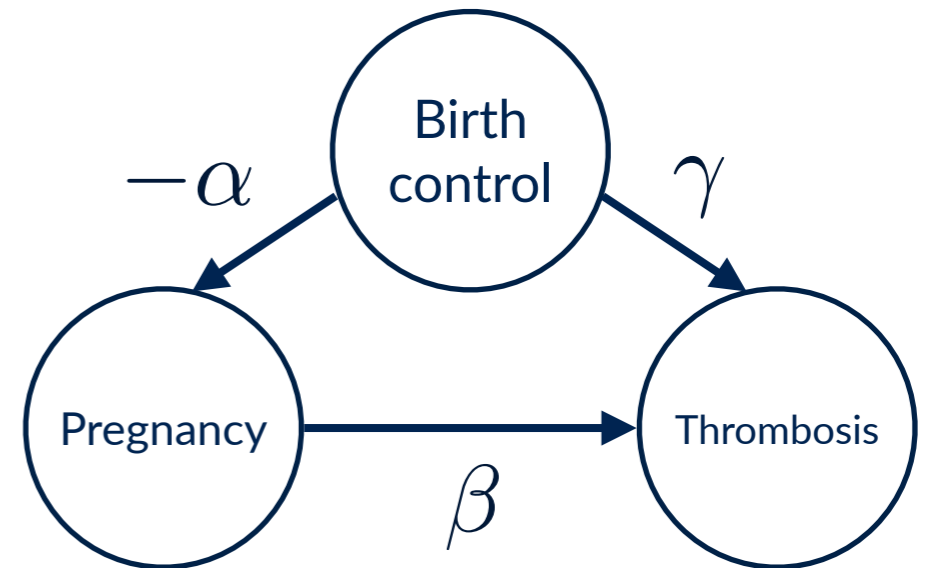
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So if $\gamma = \alpha\beta$, no dependency between T and B will be observed!

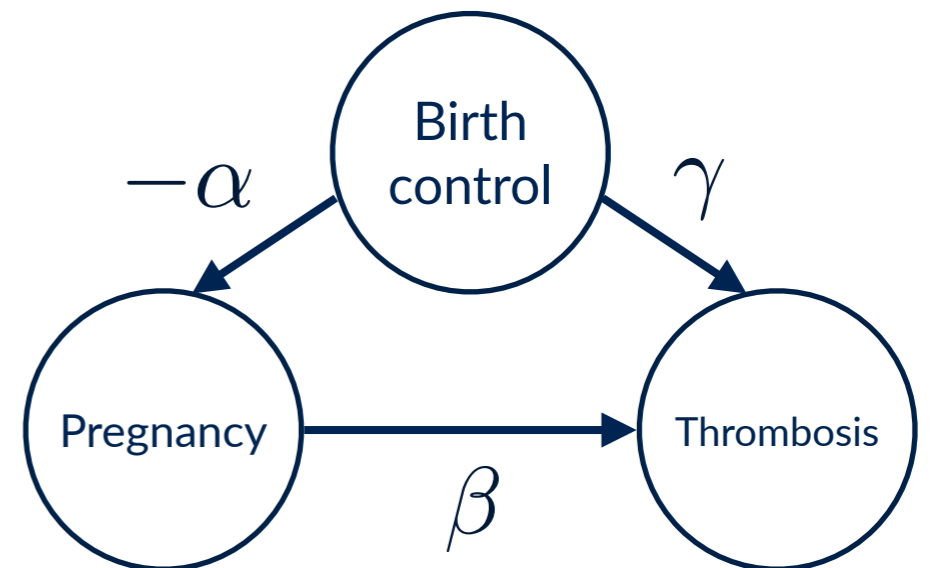
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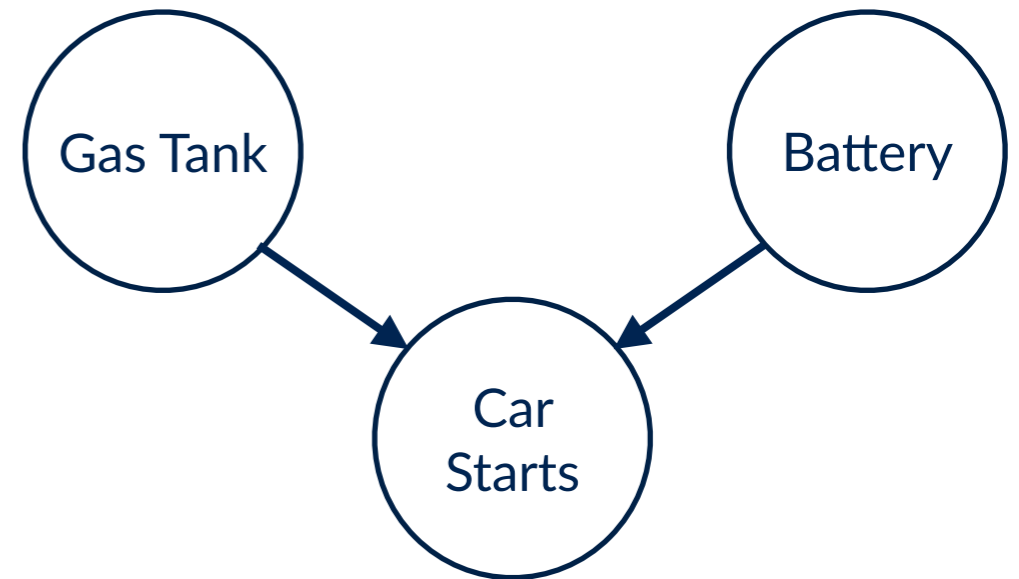
- Fails in **regulatory systems**, e.g. home temperature, outside temp, thermostat: By design, thermostat keeps the inside temp independent of outside, always fixed at T^*
- **Biology and homeostasis!**
Often keep the assumption and argue that most distributions are multimodal and will not cancel each other exactly ...

Distinguishing causal structures: V-structures

Recall collider example:

Gas tank $\perp\!\!\!\perp$ Battery

Gas tank $\not\perp\!\!\!\perp$ Battery | Car starts = 0

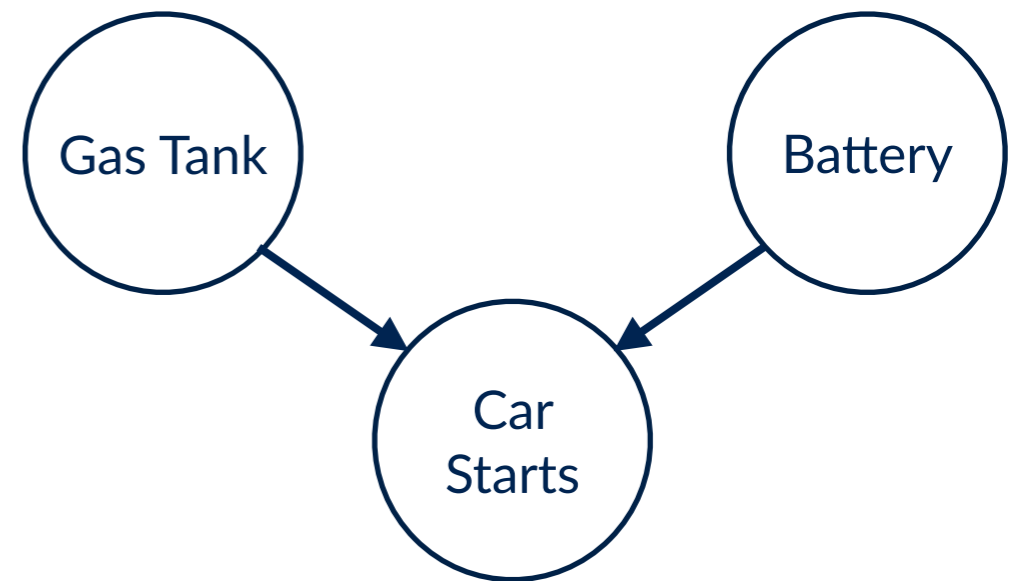


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- **Markov Equivalence Class (MEC):** Two graphs G and G' belong to the same equivalence class iff each conditional independence implied by G is also implied by G' and vice versa.
- We can learn edges/directions using MEC and d-separation.
- D-separations gives all CI implied by graph

Markov Equivalence Class (MEC)

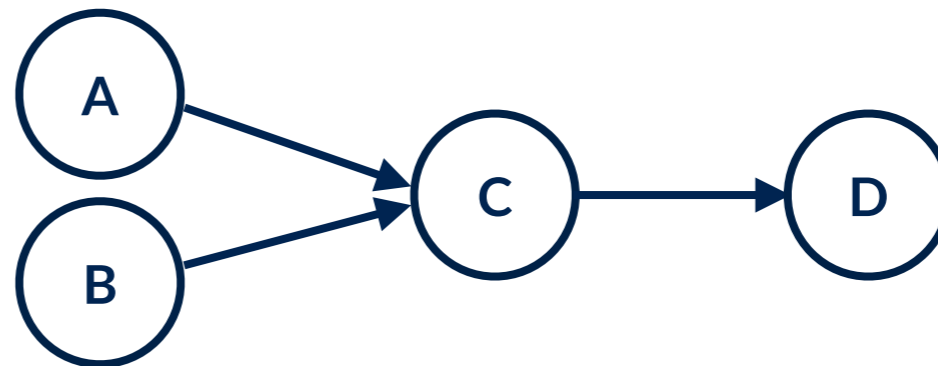
| True DAG | $A \rightarrow B \rightarrow C$ | $A \rightarrow B \leftarrow C$ |
|-----------------------------------|--|------------------------------------|
| All Observed CIs | $A \perp\!\!\!\perp C B$ | $A \perp\!\!\!\perp C \emptyset$ |
| Set of DAGs in MEC | $A \rightarrow B \rightarrow C$ $A \leftarrow B \leftarrow C$ $A \leftarrow B \rightarrow C$ | $A \rightarrow B \leftarrow C$ |
| CPDAG (complete partially DAG) | $A - B - C$ | $A \rightarrow B \leftarrow C$ |

The Search Space of Causal Graphs

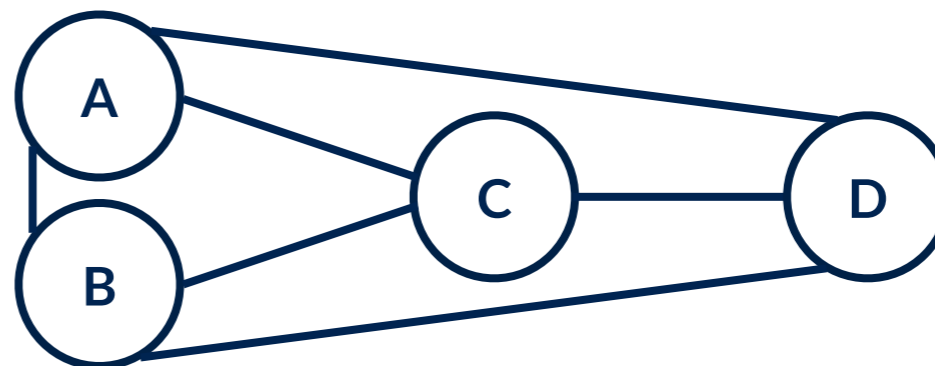
- For $|V|=n$ nodes there are $\binom{n}{2} = \frac{1}{2}(n-1)n$ distinct pairs of variables
- There are at least $2^{\frac{1}{2}(n-1)n}$ possible graphs where between any two pairs there is either an edge or no edge.
- There are at most $3^{\frac{1}{2}(n-1)n}$ possible graphs since we may have either of: $A \rightarrow B$, $A \leftarrow B$, $A \quad B$
- Grows super exponentially in the number of nodes
- Requires efficient causal discovery algorithms: PC algorithm

Peter-Clark (PC) Algorithm

True causal graph:

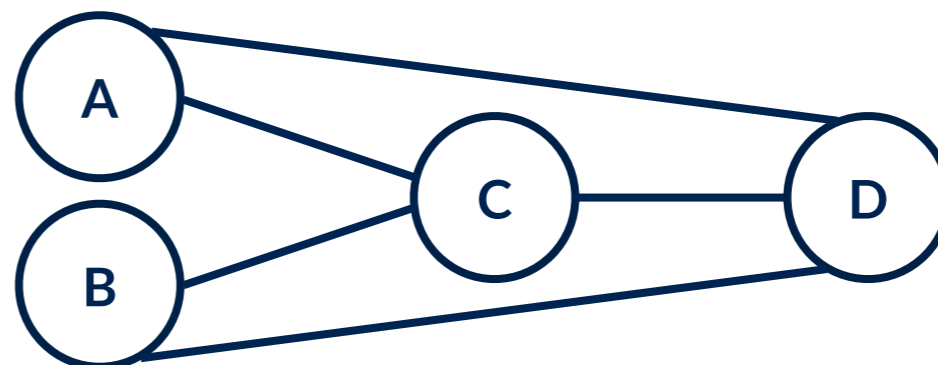


1. Start with the complete graph



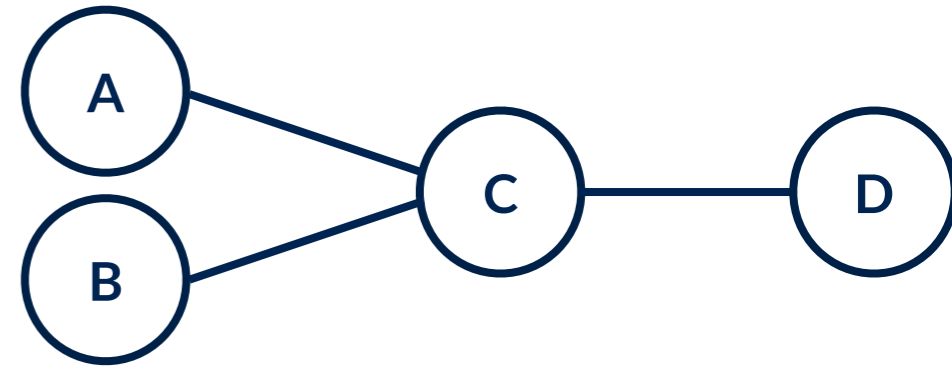
2. Zeroth order CI, $A \perp\!\!\!\perp B$ by faithfulness:

Need statistical independence testing.



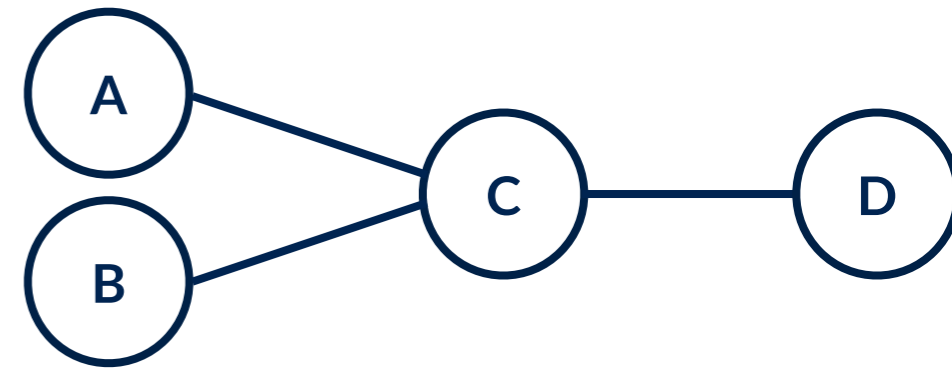
Peter-Clark (PC) Algorithm

3. 1st order CI, $A \perp\!\!\!\perp D|C$, by faithfulness:
 $B \perp\!\!\!\perp D|C$



Peter-Clark (PC) Algorithm

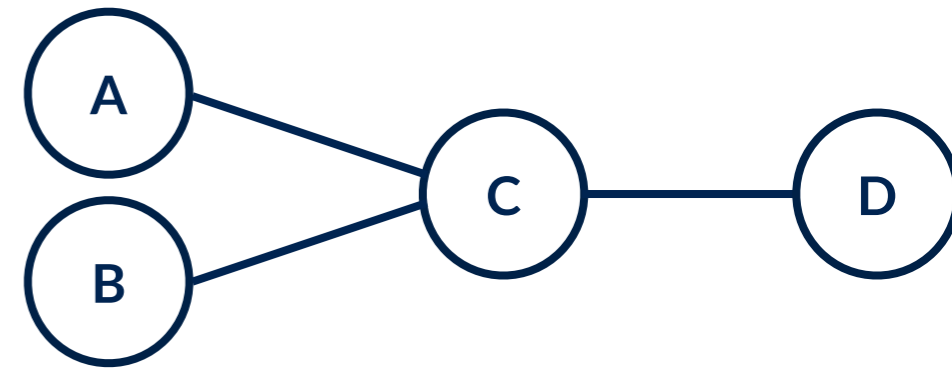
3. 1st order CI, $A \perp\!\!\!\perp D|C$, by faithfulness:
 $B \perp\!\!\!\perp D|C$



4. No higher order CI observed. Notice that conditioning sets only need to contain **neighbours** for the two nodes due to the Markov condition. We do not know the parents but parents are a subsets of neighbours. As the graph becomes sparser, the number of tests to be performed decreases. This makes PC very efficient.

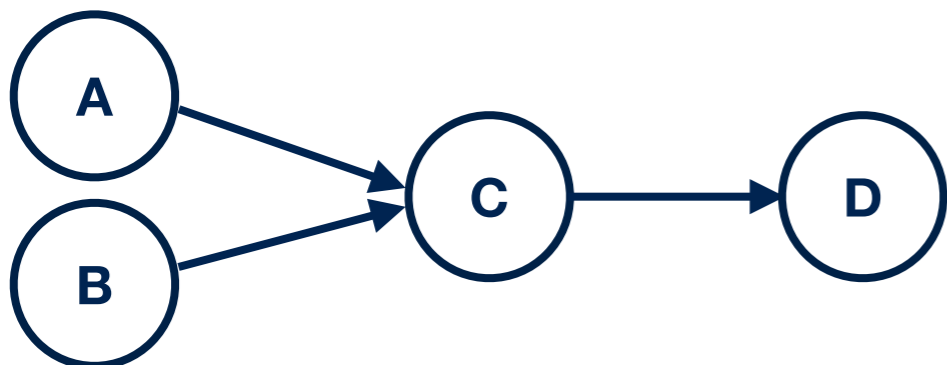
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5. Orient V-structures (colliders): take triplets where 2 nodes are connected to the 3rd: $A \not\perp\!\!\!\perp B|C$ only.



Note $C \leftarrow D$ cannot be as it would have been a collider (not detected in 5)

Remarks

- Missing/unobserved variables could lead to wrong/biased graphs
- Conditional independence tests are subject of active research
- Parallelised PC
- PC for heterogeneous data etc.
- PC + score-based

Nevertheless, the assumptions behind these are very strong!





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