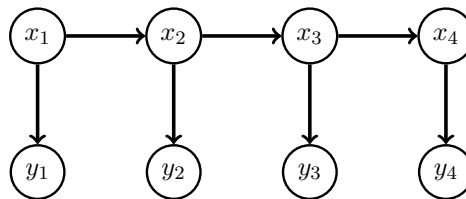


Exercises for the tutorials: 2(a-c) and 4(a-b).

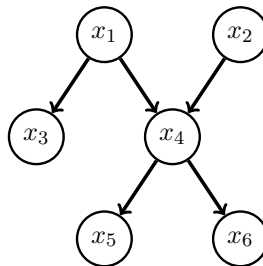
The other exercises are for self-study and exam preparation. All material is examinable unless otherwise mentioned.

Exercise 1. Conversion to factor graphs

- (a) Draw an undirected factor graph for the directed graphical model defined by the graph below.

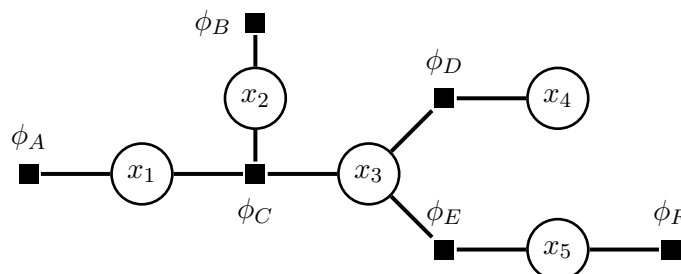


- (b) Draw an undirected factor graph for directed graphical models defined by the graph below (this kind of graph is called a polytree: there are no loops but a node may have more than one parent).



Exercise 2. Sum-product message passing

We here re-consider the factor tree from the lecture on exact inference.



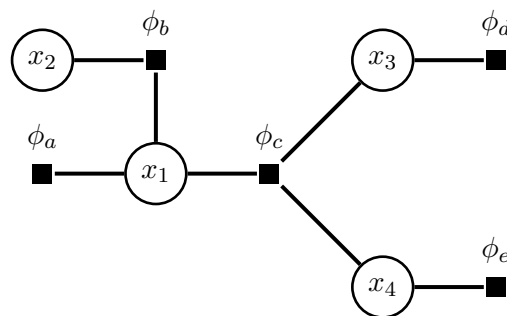
Let all variables be binary, $x_i \in \{0, 1\}$, and the factors be defined as follows:

		<hr/>				<hr/>			<hr/>			<hr/>	
		x_1	x_2	x_3	ϕ_C	x_3	x_4	ϕ_D	x_3	x_5	ϕ_E	x_5	ϕ_F
		0	0	0	4	<hr/>			<hr/>			<hr/>	
x_1	ϕ_A	1	0	0	2	0	0	8	0	0	3	0	1
0	2	0	1	0	2	1	0	2	1	0	6	1	8
1	4	1	1	0	6	0	1	2	0	1	6	<hr/>	
<hr/>		1	0	1	6	1	1	6	1	1	3	<hr/>	
		0	1	1	6	<hr/>			<hr/>				
		1	1	1	4	<hr/>			<hr/>				

- (a) Mark the graph with arrows indicating all messages that need to be computed for the computation of $p(x_1)$.
- (b) Compute the messages that you have identified.
Assuming that the computation of the messages is scheduled according to a common clock, group the messages together so that all messages in the same group can be computed in parallel during a clock cycle.
- (c) What is $p(x_1 = 1)$?
- (d) Draw the factor graph corresponding to $p(x_1, x_3, x_4, x_5 | x_2 = 1)$ and provide the numerical values for all factors.
- (e) Compute $p(x_1 = 1 | x_2 = 1)$, re-using messages that you have already computed for the evaluation of $p(x_1 = 1)$.

Exercise 3. Sum-product message passing

The following factor graph represents a Gibbs distribution over four binary variables $x_i \in \{0, 1\}$.



The factors ϕ_a, ϕ_b, ϕ_d are defined as follows:

<hr/>		<hr/>			<hr/>	
x_1	ϕ_a	x_1	x_2	ϕ_b	x_3	ϕ_d
0	2	0	0	5	0	1
1	1	1	0	2	1	2
<hr/>		0	1	2	<hr/>	
		1	1	6	<hr/>	

and $\phi_c(x_1, x_3, x_4) = 1$ if $x_1 = x_3 = x_4$, and is zero otherwise.

For all questions below, justify your answer:

- (a) Compute the values of $\mu_{x_2 \rightarrow \phi_b}(x_2)$ for $x_2 = 0$ and $x_2 = 1$.
 (b) Assume the message $\mu_{x_4 \rightarrow \phi_c}(x_4)$ equals

$$\mu_{x_4 \rightarrow \phi_c}(x_4) = \begin{cases} 1 & \text{if } x_4 = 0 \\ 3 & \text{if } x_4 = 1 \end{cases}$$

Compute the values of $\phi_e(x_4)$ for $x_4 = 0$ and $x_4 = 1$.

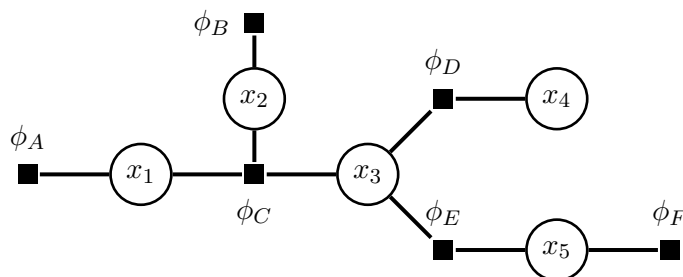
- (c) Compute the values of $\mu_{\phi_c \rightarrow x_1}(x_1)$ for $x_1 = 0$ and $x_1 = 1$.
 (d) The message $\mu_{\phi_b \rightarrow x_1}(x_1)$ equals

$$\mu_{\phi_b \rightarrow x_1}(x_1) = \begin{cases} 7 & \text{if } x_1 = 0 \\ 8 & \text{if } x_1 = 1 \end{cases}$$

What is the probability that $x_1 = 1$, i.e. $p(x_1 = 1)$?

Exercise 4. *Max-sum message passing*

We here compute most probable states for the factor graph and factors below.



Let all variables be binary, $x_i \in \{0, 1\}$, and the factors be defined as follows:

		x_1	x_2	x_3	ϕ_C										
		0	0	0	4										
		1	0	0	2										
x_1	ϕ_A	x_2	ϕ_B	0	1	0	2	x_3	x_4	ϕ_D	x_3	x_5	ϕ_E	x_5	ϕ_F
0	2	0	4	1	1	0	6	1	0	2	1	0	6	0	1
1	4	1	4	0	0	1	2	0	1	2	0	1	6	1	8
		1	0	1	6				1	1	6				
		0	1	1	6										
		1	1	1	4										

- (a) Will we need to compute the normalising constant Z to determine $\text{argmax}_{\mathbf{x}} p(x_1, \dots, x_5)$?

- (b) Compute $\operatorname{argmax}_{x_1, x_2, x_3} p(x_1, x_2, x_3 | x_4 = 0, x_5 = 0)$ via max-sum message passing.
- (c) Compute $\operatorname{argmax}_{x_1, \dots, x_5} p(x_1, \dots, x_5)$ via max-sum message passing with x_1 as root.
- (d) Compute $\operatorname{argmax}_{x_1, \dots, x_5} p(x_1, \dots, x_5)$ via max-sum message passing with x_3 as root.

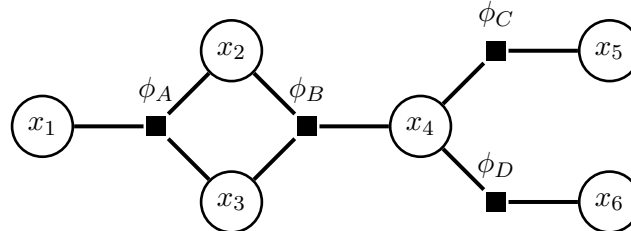
Exercise 5. Inference for two linearly dependent Gaussian RVs

You have prior knowledge that an unknown variable $X \sim N(0, 1)$. You can make an observation of the variable Y which is related to X by $Y = wX + \mu_y + \epsilon$, with w and μ constants, and $\epsilon \sim N(0, \sigma^2)$ independent of X . The graphical model is $X \rightarrow Y$. (The factor w might arise e.g. because you want to measure X in centimeters, but your ruler is in inches. μ_y may arise due to an offset between the origins of the coordinates in the X and Y spaces.)

- (a) Show that $\mathbb{E}[Y] = \mu_y$.
- (b) You now want to make inferences for X given the observation $Y = y$. The conditional distribution $p(X = x | Y = y)$ is Gaussian. Compute its posterior mean and variance.
HINT: You cause the conditioning formula for Gaussians given in the slides, or manipulate the expressions for the Gaussians $p(x)$ and $p(y|x)$ directly.

Exercise 6. Choice of elimination order in factor graphs

Consider the following factor graph, which contains a loop:



Let all variables be binary, $x_i \in \{0, 1\}$, and the factors be defined as follows:

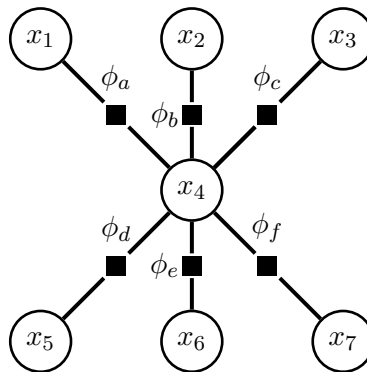
x_1	x_2	x_3	ϕ_A	x_2	x_3	x_4	ϕ_B	x_4	x_5	ϕ_C	x_4	x_6	ϕ_D
0	0	0	4	0	0	0	2	0	0	8	0	0	3
1	0	0	2	1	0	0	2	1	0	2	1	0	6
0	1	0	2	0	1	0	4	0	1	2	0	1	6
1	1	0	6	1	1	0	2	1	1	6	1	1	3
0	0	1	2	0	0	1	6						
1	0	1	6	1	0	1	8						
0	1	1	6	0	1	1	4						
1	1	1	4	1	1	1	2						

- (a) Draw the factor graph corresponding to $p(x_2, x_3, x_4, x_5 | x_1 = 0, x_6 = 1)$ and give the tables defining the new factors $\phi_A^{x_1=0}(x_2, x_3)$ and $\phi_D^{x_6=1}(x_4)$ that you obtain.

- (b) Find $p(x_2 \mid x_1 = 0, x_6 = 1)$ using the elimination ordering (x_4, x_5, x_3) :
- (i) Draw the graph for $p(x_2, x_3, x_5 \mid x_1 = 0, x_6 = 1)$ by marginalising x_4
Compute the table for the new factor $\tilde{\phi}_4(x_2, x_3, x_5)$
 - (ii) Draw the graph for $p(x_2, x_3 \mid x_1 = 0, x_6 = 1)$ by marginalising x_5
Compute the table for the new factor $\tilde{\phi}_{45}(x_2, x_3)$
 - (iii) Draw the graph for $p(x_2 \mid x_1 = 0, x_6 = 1)$ by marginalising x_3
Compute the table for the new factor $\tilde{\phi}_{453}(x_2)$
- (c) Now determine $p(x_2 \mid x_1 = 0, x_6 = 1)$ with the elimination ordering (x_5, x_4, x_3) :
- (i) Draw the graph for $p(x_2, x_3, x_4 \mid x_1 = 0, x_6 = 1)$ by marginalising x_5
Compute the table for the new factor $\tilde{\phi}_5(x_4)$
 - (ii) Draw the graph for $p(x_2, x_3 \mid x_1 = 0, x_6 = 1)$ by marginalising x_4
Compute the table for the new factor $\tilde{\phi}_{54}(x_2, x_3)$
 - (iii) Draw the graph for $p(x_2 \mid x_1 = 0, x_6 = 1)$ by marginalising x_3
Compute the table for the new factor $\tilde{\phi}_{543}(x_2)$
- (d) Which variable ordering, (x_4, x_5, x_3) or (x_5, x_4, x_3) do you prefer?

Exercise 7. Choice of elimination order in factor graphs

We would like to compute the marginal $p(x_1)$ by variable elimination for a joint pmf represented by the following factor graph. All variables x_i can take K different values.



- (a) A friend proposes the elimination order $x_4, x_5, x_6, x_7, x_3, x_2$, i.e. to do x_4 first and x_2 last. Explain why this is computationally inefficient.
- (b) Propose an elimination ordering that achieves $O(K^2)$ computational cost per variable elimination and explain why it does so.