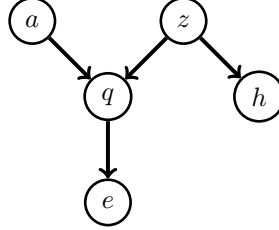


**Exercise 1. Ordered and local Markov properties,  $d$ -separation**

Consider the graph below:



- (a) The ordering  $(z, h, a, q, e)$  is topological to the graph. What are the independencies that follow from the ordered Markov property?

**Solution.** We proceed as in the lecture slides: The predecessor sets are

$$\text{pre}_z = \emptyset, \text{pre}_h = \{z\}, \text{pre}_a = \{z, h\}, \text{pre}_q = \{z, h, a\}, \text{pre}_e = \{z, h, a, q\}$$

The parent sets are independent from the topological ordering chosen. In the lecture, we have seen that they are:

$$\text{pa}_z = \emptyset, \text{pa}_h = \{z\}, \text{pa}_a = \emptyset, \text{pa}_q = \{a, z\}, \text{pa}_e = \{q\},$$

The ordered Markov property reads  $x_i \perp\!\!\!\perp (\text{pre}_i \setminus \text{pa}_i) \mid \text{pa}_i$  where the  $x_i$  refer to the ordered variables, e.g.  $x_1 = z, x_2 = h, x_3 = a$ , etc.

With

$$\text{pre}_h \setminus \text{pa}_h = \emptyset \quad \text{pre}_a \setminus \text{pa}_a = \{z, h\} \quad \text{pre}_q \setminus \text{pa}_q = \{h\} \quad \text{pre}_e \setminus \text{pa}_e = \{z, h, a\}$$

we thus obtain

$$h \perp\!\!\!\perp \emptyset \mid z \quad a \perp\!\!\!\perp \{z, h\} \quad q \perp\!\!\!\perp h \mid \{a, z\} \quad e \perp\!\!\!\perp \{z, h, a\} \mid q$$

The relation  $h \perp\!\!\!\perp \emptyset \mid z$  should be understood as “there is no variable from which  $h$  is independent given  $z$ ” and should thus be dropped from the list. Compared to the relations obtained for the orderings in the lecture, the new one here is  $a \perp\!\!\!\perp \{z, h\}$ . Generally, having a variable later in the topological ordering allows one to possibly obtain a stronger independence relation because the set  $\text{pre} \setminus \text{pa}$  can only increase when the predecessor set  $\text{pre}$  becomes larger.

- (b) What are the independencies that follow from the local Markov property?

**Solution.** The non-descendants are

$$\text{nondesc}(a) = \{z, h\} \quad \text{nondesc}(z) = \{a\} \quad \text{nondesc}(h) = \{a, z, q, e\}$$

$$\text{nondesc}(q) = \{a, z, h\} \quad \text{nondesc}(e) = \{a, q, z, h\}$$

With the parent sets as before, the independencies that follow from the local Markov property are  $x_i \perp\!\!\!\perp (\text{nondesc}(x_i) \setminus \text{pa}_i) \mid \text{pa}_i$ , i.e.

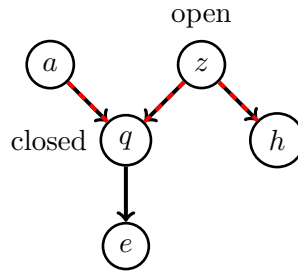
$$a \perp\!\!\!\perp \{z, h\} \quad z \perp\!\!\!\perp a \quad h \perp\!\!\!\perp \{a, q, e\} \mid z \quad q \perp\!\!\!\perp h \mid \{a, z\} \quad e \perp\!\!\!\perp \{a, z, h\} \mid q$$

- (c) The independency relations obtained via the ordered and local Markov property include  $q \perp\!\!\!\perp h \mid \{a, z\}$ . Verify the independency using d-separation.

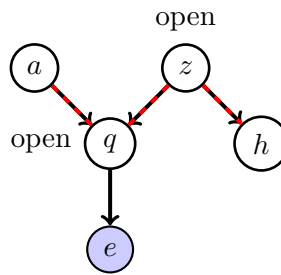
**Solution.** The only trail from  $q$  to  $h$  goes through  $z$  which is in a tail-tail configuration. Since  $z$  is part of the conditioning set, the trail is blocked and the result follows.

- (d) Use d-separation to check whether  $a \perp\!\!\!\perp h \mid e$  holds.

**Solution.** The trail from  $a$  to  $h$  is shown below in red together with the default states of the nodes along the trail.



Conditioning on  $e$  opens the  $q$  node since  $q$  is in a collider configuration on the path.



The trail from  $a$  to  $h$  is thus active, which means that the relationship does not hold because  $a \not\perp\!\!\!\perp h \mid e$  for some distributions that factorise over the graph.

- (e) Assume all variables in the graph are binary. How many numbers do you need to specify, or learn from data, in order to fully specify the probability distribution?

**Solution.** The graph defines a set of probability mass functions (pmf) that factorise as

$$p(a, z, q, h, e) = p(a)p(z)p(q|a, z)p(h|z)p(e|q)$$

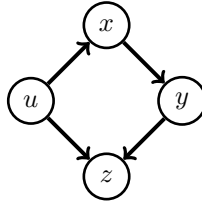
To specify a member of the set, we need to specify the (conditional) pmfs on the right-hand side. The (conditional) pmfs can be seen as tables, and the number of elements that we need to specify in the tables are:

- 1 for  $p(a)$
- 1 for  $p(z)$
- 4 for  $p(q|a, z)$
- 2 for  $p(h|z)$
- 2 for  $p(e|q)$

In total, there are 10 numbers to specify. This is in contrast to  $2^5 - 1 = 31$  for a distribution without independencies. Note that the number of parameters to specify could be further reduced by making parametric assumptions.

## Exercise 2. *Flipping arrows*

Consider the following graph:



(a) How does the corresponding directed graphical model factorise?

**Solution.**  $p(u, x, y, z) = p(u)p(x|u)p(y|x)p(z|y, u)$

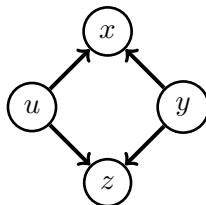
(b) List all independencies encoded by the graph.

**Solution.** Variable  $u$  cannot be independent of  $x$  and  $z$  since they are connected. Since  $z$  is in a collider configuration, we have that  $u \perp\!\!\!\perp y|x$ .

Variable  $x$  cannot be independent of  $y$  (and  $u$ ) since they are connected. Conditioning on  $u$  and  $y$  makes  $x$  independent of  $z$ :  $x \perp\!\!\!\perp z|u, y$

(c) How do the independencies change when we flip the arrow from  $x$  to  $y$  so that it points the other way around, i.e.  $y \rightarrow x$ ?

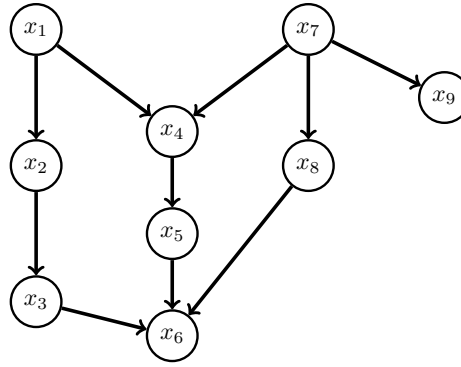
**Solution.** With the change, we obtain the following graph



which has two colliders blocking all paths between  $u$  and  $y$ . Hence  $u \perp\!\!\!\perp y$ . However, conditioning on  $x$  would open the path so that  $u \not\perp\!\!\!\perp y|x$ . The independency  $x \perp\!\!\!\perp z|u, y$  still holds.

## Exercise 3. *Independencies in directed graphical models*

Consider the following directed acyclic graph.



For each of the statements below, determine whether it holds for all probabilistic models that factorise over the graph. Provide a justification for your answer.

(a)  $p(x_7|x_2) = p(x_7)$

**Solution.** Yes, it holds.  $x_2$  is a non-descendant of  $x_7$ ,  $\text{pa}(x_7) = \emptyset$ , and hence, by the local Markov property,  $x_7 \perp\!\!\!\perp x_2$ , so that  $p(x_7|x_2) = p(x_7)$ .

(b)  $x_1 \not\perp\!\!\!\perp x_3$

**Solution.** No, does not hold.  $x_1$  and  $x_3$  are d-connected, which only implies independence for *some* and not all distributions that factorise over the graph. The graph generally only allows us to read out independencies and not dependencies.

(c)  $p(x_1, x_2, x_4) \propto \phi_1(x_1, x_2)\phi_2(x_1, x_4)$  for some non-negative functions  $\phi_1$  and  $\phi_2$ .

**Solution.** Yes, it holds. The statement is equivalent to  $x_2 \perp\!\!\!\perp x_4 \mid x_1$ . There are three trails from  $x_2$  to  $x_4$ , which are all blocked:

1.  $x_2 - x_1 - x_4$ : this trail is blocked because  $x_1$  is in a tail-tail connection and it is observed, which closes the node.
2.  $x_2 - x_3 - x_6 - x_5 - x_4$ : this trail is blocked because  $x_3, x_6, x_5$  is in a collider configuration, and  $x_6$  is not observed (and it does not have any descendants).
3.  $x_2 - x_3 - x_6 - x_8 - x_7 - x_4$ : this trail is blocked because  $x_3, x_6, x_8$  is in a collider configuration, and  $x_6$  is not observed (and it does not have any descendants).

Hence, by the global Markov property (d-separation), the independency holds.

(d)  $x_2 \perp\!\!\!\perp x_9 \mid \{x_6, x_8\}$

**Solution.** No, does not hold. Conditioning on  $x_6$  opens the collider node  $x_4$  on the trail  $x_2 - x_1 - x_4 - x_7 - x_9$ , so that the trail is active.

(e)  $x_8 \perp\!\!\!\perp \{x_2, x_9\} \mid \{x_3, x_5, x_6, x_7\}$

**Solution.** Yes, it holds.  $\{x_3, x_5, x_6, x_7\}$  is the Markov blanket of  $x_8$ , so that  $x_8$  is independent of remaining nodes given the Markov blanket.

(f)  $\mathbb{E}[x_2 \cdot x_3 \cdot x_4 \cdot x_5 \cdot x_8 \mid x_7] = 0$  if  $\mathbb{E}[x_8 \mid x_7] = 0$

**Solution.** Yes, it holds.  $\{x_2, x_3, x_4, x_5\}$  are non-descendants of  $x_8$ , and  $x_7$  is the parent of  $x_8$ , so that  $x_8 \perp\!\!\!\perp \{x_2, x_3, x_4, x_5\} \mid x_7$ . This means that  $\mathbb{E}[x_2 \cdot x_3 \cdot x_4 \cdot x_5 \cdot x_8 \mid x_7] = \mathbb{E}[x_2 \cdot x_3 \cdot x_4 \cdot x_5 \mid x_7] \mathbb{E}[x_8 \mid x_7] = 0$ .