

Simulation, Analysis, and Validation of Computational Models

— Bonus I: PINN



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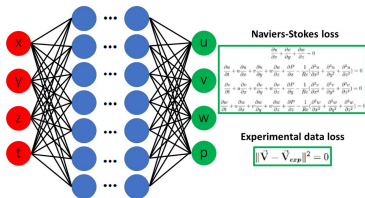
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- Neural Networks
- Physics
- PINN

Last time: Physics-informed neural networks

Physics-informed ML

- Efficient machine learning
- Physics-informed reinforcement learning, active learning
- Physics-informed regularisation



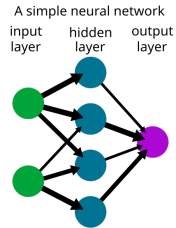
Understanding system physics

- Qualitative modelling by identification of underlying regularities
- Learning to simulate complex phenomena from sparse data based on physics priors (PDE).
- Closed loop systems to perform process optimization

see e.g. <https://www.youtube.com/watch?v=ISp-hq6AH3Q>

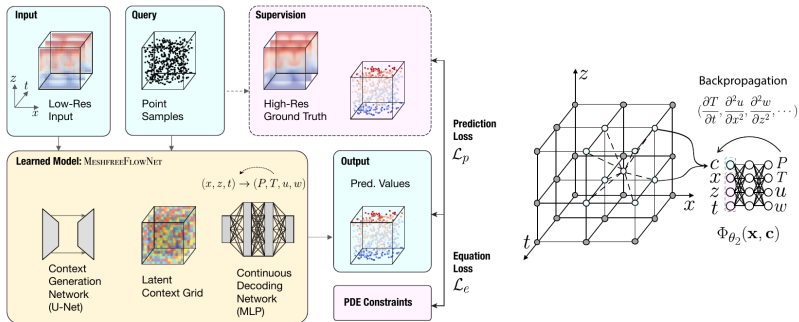
Neural networks

- Hardware:
 - ① Generation of NN (1958):
Electronic computers
 - ② Gen. NN (1986): VLSI
 - ③ Gen. NN (2012): GPUs
- Function approximation, data generation, novelty detection
- Hyperparameters: Batch size, learning rate, regularisation, unit type, architecture, cost function
- Problems:
 - High sample complexity and long training time
 - Efficiency, complexity, theory, verifiability
 - Explainability, unlearnability, robustness to adversarial attacks
 - Insight, understanding, intelligence



- Physics is the study motion and behavior of matter in space and time.
- Reduction of the RW complexity to essential and repeatable aspects.
- Regularity of continuous trajectories (or probabilities or wave functions) can be described by differential equations which are usually derived from the principle of least action.
- In addition to dynamics, also symmetry and conservation laws can be incorporated.
- Extrapolation of known regularities can be used to make testable predictions, which may lead to an insight in more complex regularities.

Weather and climate modelling



Esmailzadeh e.a. (2020) MeshFreeFlowNet: A physics-constrained deep continuous space-time super-resolution framework. In SC20: Int. Conf. HPCNSA, p. 1-15.

see also Kashinath e.a. (2021) APhysics-informed machine learning: case studies for weather and climate modelling. Phil. Trans. R. Soc. A379, 202000093.

What is a physics-informed neural network?

- Machine learning can solve a scientific problem using data alone.
- Do these algorithms “understand” the scientific problems they are trying to solve?
- Minimising MSE of NN output and true values

$$\min \frac{1}{N} \sum_{i=1}^N (u_{\text{NN}}(x_i, \theta) - u_{\text{true}}(x_i))^2$$

does not mean that the neural network can generalise well.

- The question is not how to improve generalisation, but to describe sets of possible data, e.g. for temporal data by a relation

$$\dot{x} = F(x)$$

Ben Moseley (<https://benmoseley.blog>)

- *Big data* (by definition): all relevant structure can be inferred from the data
- *Small data* can be as useful, if underlying principles (“physics”) are known (e.g. as initial values)
- What can be achieved for “some data” with “some physics”?
- Add the known differential equations directly into the loss function when training the neural network.

$$m \frac{d^2 u}{dx^2} + \mu \frac{du}{dx} + ku = 0 \quad \text{and} \quad \frac{1}{N} \sum_i (u_{\text{NN}}(x_i) - u_i)^2$$

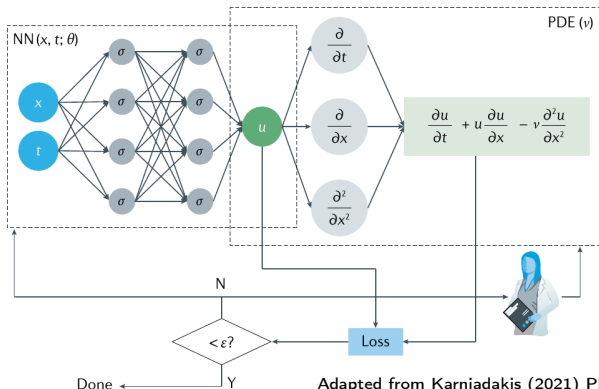
- PINN started 2017, but there is earlier work of similar flavour.

Lagaris (1998) Artificial Neural Networks for Solving Ordinary and Partial Differential Equations.
IEEE Transact. Neural Networks 9, 987

Given: PDE $\frac{\partial u}{\partial t} = -u \frac{\partial u}{\partial x} + v \frac{\partial^2 u}{\partial x^2}$ and data (x_i, t_i, u_i) , $i = 1, \dots, N_{\text{data}}$

Loss: $\mathcal{L} = w_{\text{data}} \mathcal{L}_{\text{data}} + w_{\text{PDE}} \mathcal{L}_{\text{PDE}}$ where w_{data} and w_{PDE} are weights and

$$\mathcal{L}_{\text{data}} = \frac{1}{N_{\text{data}}} \sum_{i=1}^{N_{\text{data}}} (u(x_i, t_i) - u_i)^2, \quad \mathcal{L}_{\text{PDE}} = \frac{1}{N_{\text{PDE}}} \sum_{j=1}^{N_{\text{PDE}}} \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} - v \frac{\partial^2 u}{\partial x^2} \right)^2 \Big|_{x=x_j(t)}$$



Adapted from Karniadakis (2021) Physics-informed machine learning. *Nat. Rev. Phys.* 3, 422

Given: PDE $\frac{\partial u}{\partial t} = -u \frac{\partial u}{\partial x} + v \frac{\partial^2 u}{\partial x^2}$ and data (x_i, t_i, u_i) , $i = 1, \dots, N_{\text{data}}$

Loss: $\mathcal{L} = w_{\text{data}} \mathcal{L}_{\text{data}} + w_{\text{PDE}} \mathcal{L}_{\text{PDE}}$ where w_{data} and w_{PDE} are weights and

$$\mathcal{L}_{\text{data}} = \frac{1}{N_{\text{data}}} \sum_{i=1}^{N_{\text{data}}} (u(x_i, t_i) - u_i)^2, \quad \mathcal{L}_{\text{PDE}} = \frac{1}{N_{\text{PDE}}} \sum_{j=1}^{N_{\text{PDE}}} \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} - v \frac{\partial^2 u}{\partial x^2} \right)^2 \Bigg|_{x=x_j(t)}$$

- PDE data (x_j, t_j) can be different from training data (x_i, t_i, u_i) .
E.g. trivial case: $N_{\text{data}} = 1$ just check whether initial value is met.
- Trust in PDE and in data can be in different (weights!).
- Error components can be in different ranges (weights!).
- PDE and data can be spatially heterogeneous.
- PDE and data have different stiffness (Edit PDE?)

Karniadakis (2021) Physics-informed machine learning. *Nat. Rev. Phys.* 3, 422

- **Numerical differentiation:** Calculate differences between data points. As this tends to amplify errors, it is usually combined with a smoothing scheme, e.g. “five-point stencil”:

$$\frac{df(x)}{dx} \approx \frac{-f(x+2h) + 8f(x+h) - 8f(x-h) + f(x-2h)}{12h}$$

- **Symbolic differentiation:** Manipulation of expressions by rewriting rules e.g. $h(g(x))' = h'(g(x)) \cdot g'(x)$.
- **Automatic differentiation¹:** Computational form of symbolic differentiation that emphasises computability. Classic example:

$$\frac{d \tanh x}{dx} = 1 - x^2$$

Automatic differentiation

- A function $y = f[x]$ (in any programming language) receives argument x and returns the value y .
- In addition, another function calculates

$$\frac{dy}{dx} = \left. \frac{f[z]}{dz} \right|_{z=x}$$

- Represent f as computational graph and calculate derivative by

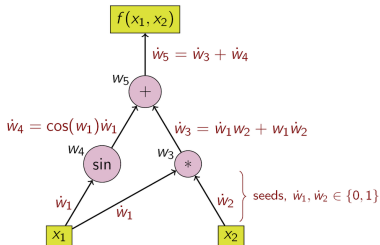
$$\delta w_i = \sum_{j \in \{\text{predecessors of } i\}} \frac{\partial w_i}{\partial w_j} \delta w_j$$

- Focus on “computational” functions (cos, exp, tanh etc.)

Automatic differentiation: Example

$$\begin{aligned}y &= f(x_1, x_2) = x_1 x_2 + \sin x_1 \\ &= w_1 w_2 + \sin w_1 \\ &= w_3 + w_4 \\ &= w_5\end{aligned}$$

$$\frac{dy}{dx_1} = x_2 + \cos x_1$$



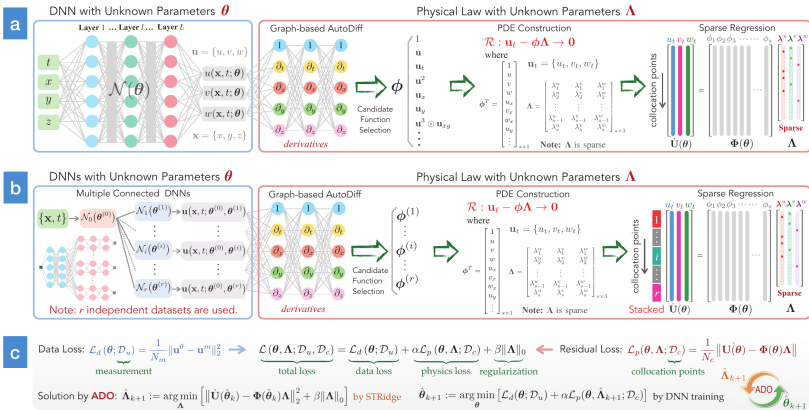
Construct a corresponding structure for a computational derivative.
Seed determines what derivative is taken (here x_1)

| value | derivative |
|-----------------------|--|
| $w_1 = x_1$ | $\delta w_1 = 1$ (seed) |
| $w_2 = x_2$ | $\delta w_2 = 0$ (seed) |
| $w_3 = w_1 \cdot w_2$ | $\delta w_3 = w_2 \cdot \delta w_1 + w_1 \cdot \delta w_2$ |
| $w_4 = \sin w_1$ | $\delta w_4 = \cos w_1 \cdot \delta w_1$ |
| $w_5 = w_3 + w_4$ | $\delta w_5 = \delta w_3 + \delta w_4$ |

Automatic differentiation: Pseudocode

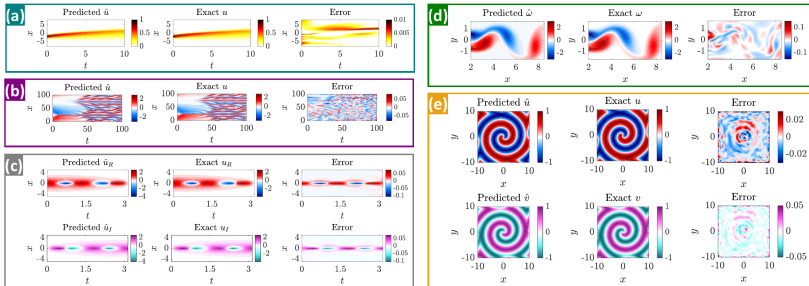
```
<float,float> evaluate_derive(expr Z, var V) {  
    if is_var(Z)  
        if (Z = V) return {value_of(Z), 1};  
        else return {value_of(Z), 0};  
    else if (Z = A + B)  
        {a, da} = evaluate_derive(A, V);  
        {b, db} = evaluate_derive(B, V);  
        return {a + b, da + db};  
    else if (Z = A - B)  
        {a, da} = evaluate_derive(A, V);  
        {b, db} = evaluate_derive(B, V);  
        return {a - b, da - db};  
    else if (Z = A * B)  
        {a, da} = evaluate_derive(A, V);  
        {b, db} = evaluate_derive(B, V);  
        return {a * b, b * da + a * db};  
}
```

PINN for learning equations from scarce data



Chen e.a. (2021) Physics-informed learning of governing equations from scarce data. *Nature comm.* 12, 6136.

PINN for learning equations from scarce data



(a) Burgers equation, (b) Kuramoto-Sivashinsky equation, (c) nonlinear Schrödinger equation, (d) Navier-Stokes equation, and (e) $\lambda - \omega$ reaction-diffusion equations. Sparsely sampled measurement data has 10% noise.

Chen e.a. (2021) Physics-informed learning of governing equations from scarce data. *Nature comm.* 12, 6136.

- Ill-posed and inverse problems.
- Scalability when combined with domain decomposition
- Search for new intrinsic variables and representations
- Incorporate conservation laws

Karniadakis (2021) Physics-informed machine learning. *Nat. Rev. Phys.* 3, 422

PINNs: Limitations (and amendments)

- Discontinuous behavior: piecewise PINNs
- Translation and advective dominance (“wind”) require special tuning, as all systems with strongly different time scales:
Distributed PINNs
- Soft constraints may require re-weighting the loss terms.
- Chaotic systems remain chaotic and their prediction is limited (high precision simulations of deterministic systems can be impressively predictable by PINNs).
- PINNs need to be informed: More general differential equations can be used or by Genetic Programming.
- Can get stuck in local optima like any other optimisation method.
- Grid-based numerical solvers are quicker in forward problems.
- Limited to physics: CINNs, BINNs, LINNs have been proposed and tested.

Rout (2021) Numerical approximation in CFD problems using physics informed machine learning. (arxiv)

- Domain decomposition
- Phase transitions
- Combination of physics with other information (e.g. boundary conditions)
- Incorporation of non-physics laws (such as Black Scholes)
- Causality
- Efficiency
- Theory of PINN: Validation

Cuomo e.a. (2022) Scientific machine learning through physics-informed neural networks: Where we are and what's next. *J. Scient. Comput.* 92, 88.

- PINNs can provide reasonable extrapolations of data and in this respect perform better than standard neural networks.
- It could seem as if PINN have an understanding of the underlying physical principles which is no surprise as this information was made available to the PINN in the first place.
- Including existing physical principles into machine learning leads to more versatile models, nontrivial predictions, and thus can help to improve scientific understanding.

Next week

- Testing
- Validation
- Verification
- Confidence

Next bonus lecture

- Connections to kernel methods